

## Data Type Stack & Queue

## Stack and Queue

Both stack and queue are important data types used in computing. They are essentially lists of data with restricted entry and exit orderings.

## Use of Stack

1. Most modern computer architecture supports hardware stack to implement recursive programming, exception handling, system call implementation.
2. Compiler uses stack for syntax checking and semantic action.

## Basic Operations on a Stack

$\text{init}() \rightarrow s:\text{Stack}$ , empty stack.

$\text{isEmpty}(s) \rightarrow b:\text{Boolean}$

$\text{top}(s) \rightarrow v:\text{Data}$ , if  $s$  is not empty  
error, otherwise

$\text{push}(s, v) \rightarrow t:\text{Stack}$

$\text{pop}(s) \rightarrow t:\text{Stack}$ , if  $s$  is not empty  
error, otherwise

## A Few Axioms of the Stack Operations

$\text{isEmpty}(\text{init}()) = \text{true}$

$\text{isEmpty}(\text{push}(s, v)) = \text{false}$

$\text{pop}(\text{init}()) = \text{error}$

$\text{pop}(\text{push}(s, v)) = s$

$\text{top}(\text{init}()) = \text{error}$

$\text{top}(\text{push}(s, v)) = v$

The axioms define the operations.

## Stack: an Example

init() → [], empty stack

push([], 5) → [5]

push([5], 7) → [5 7]

push([5 7], 3) → [5 7 3]

pop([5 7 3]) → [5 7]

push([5 7], 10) → [5 7 10]

top([5 7 10]) → 10

LIFO list.

## Basic Operations on a Queue

init() →  $q$ :Queue, an empty queue

isEmpty( $q$ ) →  $b$ :Boolean

front( $q$ ) →  $d$ :Data, if  $q$  is not empty  
→ error, otherwise

add( $q, d$ ) →  $p$ :Queue

delete( $q$ ) →  $p$ :Queue, if  $q$  is notempty  
→ error, otherwise

**Note**

The operation **add** is also called **insert**, **enqueue**; similarly the operation **delete** is also called **dequeue**.

## A Few Axioms of the Queue Operations

$\text{isEmpty}(\text{init}()) = \text{true}$

$\text{isEmpty}(\text{add}(q, d)) = \text{false}$

$\text{delete}(\text{init}()) = \text{error}$

$\text{delete}(\text{add}(q, d)) = q, \text{ if } q \text{ is empty}$

$= \text{add}(\text{delete}(q), d), \text{ otherwise}$

$\text{front}(\text{init}()) = \text{error}$

$\text{front}(\text{add}(q, v)) = v, \text{ if } q \text{ is empty}$

$= \text{front}(q), \text{ otherwise}$

## Queue: an Example

init() → [], empty queue

add([], 5) → [5]

add([5], 7) → [5 7]

add([5 7], 3) → [5 7 3]

delete([5 7 3]) → [7 3]

add([7 3], 10) → [7 3 10]

front([7 3 10]) → 7

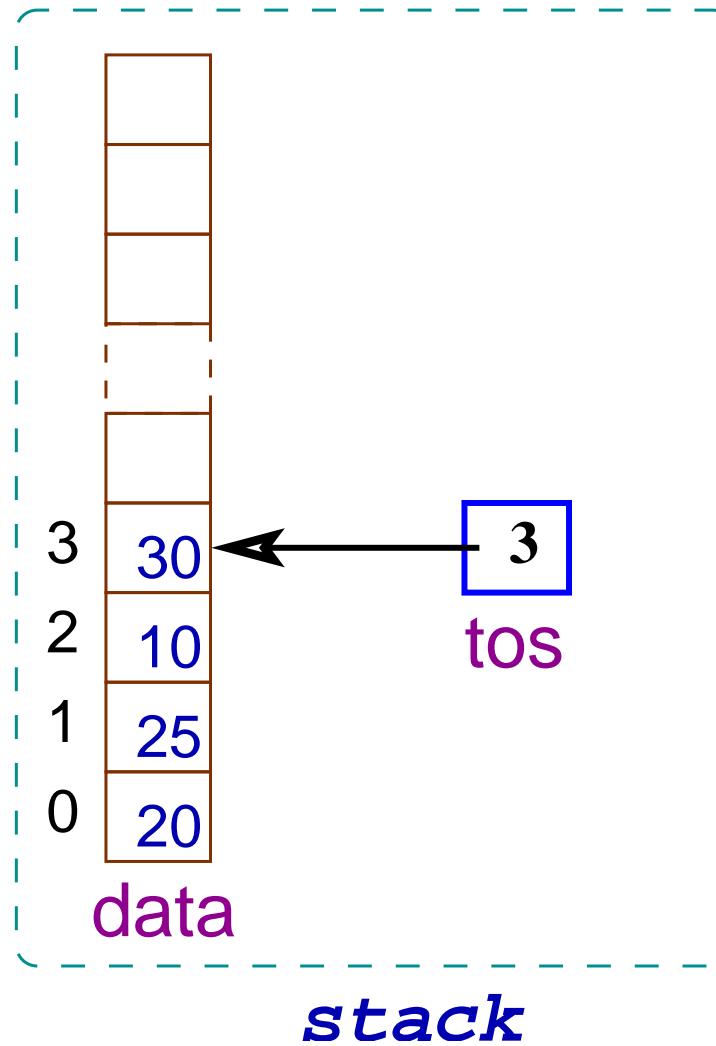
FIFO list.

## Implementation of Stack & Queue

A stack (queue) may grow to any arbitrary size. So an **ideal stack** (ideal queue) cannot be implemented in a real machine (finite capacity). We can implement an approximation of a stack (queue).

## Stack on an Array: data representation

```
typedef struct {  
    int data[SIZE];  
    int tos; // top of stack  
} stack;
```



## Stack on an Array: operations

```
void init(stack * ) ;  
int push(stack * , int) ;  
int pop(stack * ) ;  
int top(stack * , int * ) ;  
int isEmpty(stack * ) ;  
int isFull(stack * ) ; // For finite size
```

## Note

The data type **stack** is a big structure and we shall always pass a pointer to it to avoid large volume of data copy in parameter passing (call-by value).

**stack.h**

```
#ifndef _STACK_H
#define _STACK_H
#define SIZE 200
#define ERROR 1
#define OK 0
typedef struct {
    int data[SIZE];
    int tos;
} stack;

void init(stack *) ;
int push(stack * , int) ;
```

```
int pop(stack *) ;  
int top(stack *, int *) ;  
int isEmpty(stack *) ;  
int isFull(stack *) ; // For finite size  
#endif
```

## Implementation: stack.c

```
#include "stack.h"

void init(stack *s) // stack.c
{ s->tos = -1; }

int isFull(stack *s)
{ return s->tos == SIZE-1; }

int isEmpty(stack *s)
{ return s->tos == -1; }

int push(stack *s, int n) {
    if(isFull(s)) {
```

```
        printf("The STACK is full\n");
        return ERROR ;
    }
    s->data[+s->tos]=n;
    return OK ;
}

int Pop(stack *s) {
    if(isEmpty(s)) {
        printf("The STACK is empty\n");
        return ERROR ;
    }
    s -> tos-- ;
    return OK ;
}
```

```
}
```

```
int Top(stack *s , int *val) {
    if(isEmpty(s)) {
        printf("The STACK is empty\n") ;
        return ERROR ;
    }
    *val = (s -> data[s -> tos]) ;
    return OK ;
}
```

## Compiling the datatype

```
$ cc -Wall -c stack.c
```

We get the object module **stack.o**. We can construct library from it.

## User Program: testStack.c

```
#include <stdio.h>
#include "stack.h"
int main() // testStack.c
{
    stack s ;
    int x , err , val ;
    char c ;

    init(&s);

    printf(" 'U' for push (U 15)\n 'O' for pop\n 'T' for to
    printf(" 'E' for exit :\n");
```

```
while((c = getchar()) != 'e' && c != 'E')  
    switch(c) {  
        case 'u' :  
        case 'U' :  
            scanf("%d",&x);  
            err = push(&s,x);  
            break;  
        case 'o' :  
        case 'O' :  
            err = pop(&s);  
            break;  
        case 't' :  
        case 'T' :  
            err = top(&s , &val) ;  
    }
```

```
        if(!err) printf("%d\n", val);
        break;
    case '\n' :
    case '\t' :
    case ' ' :
        break;
    default :
        printf("Token Unknown\n");
    }
}

return 0;
```

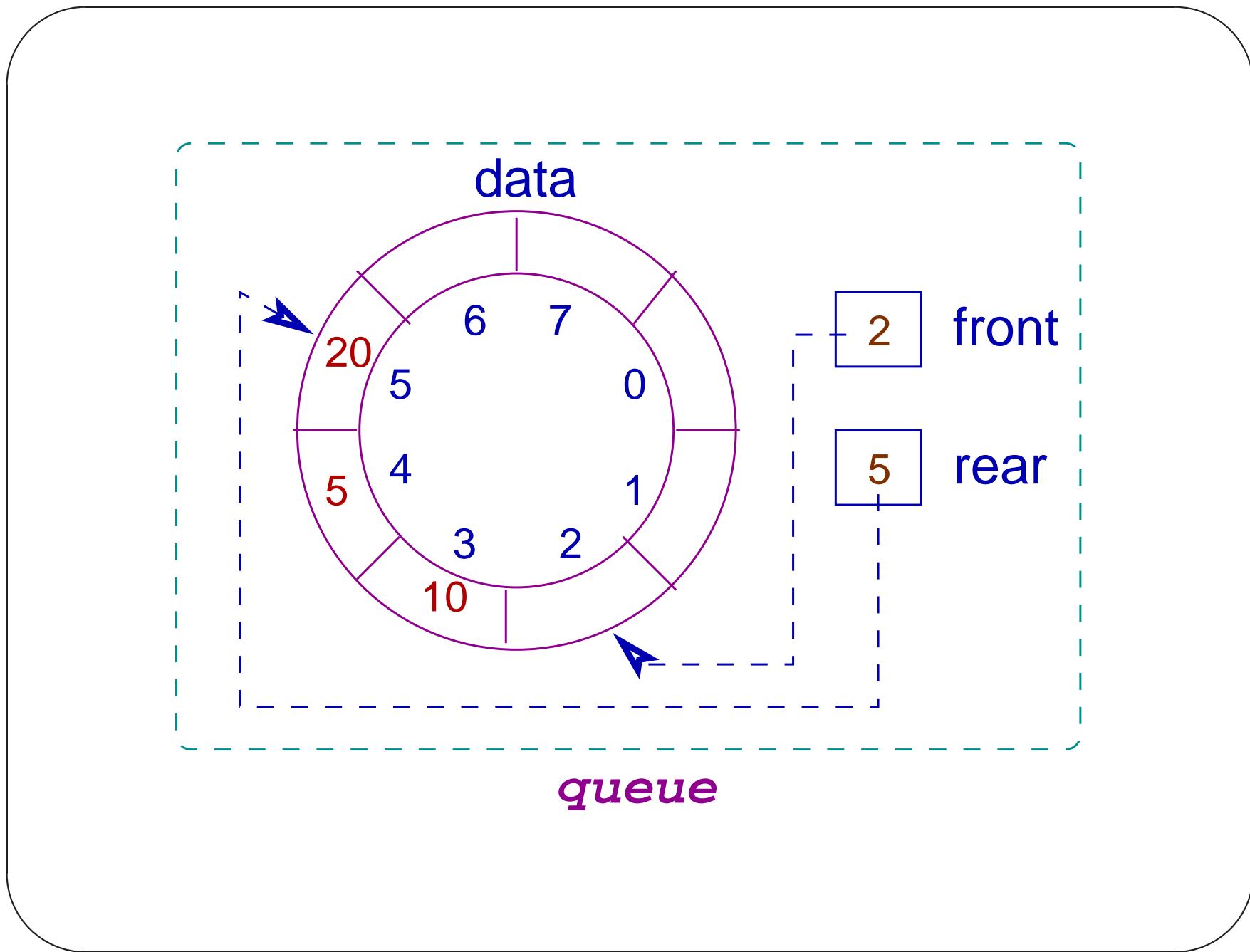
## Compiling the User Program

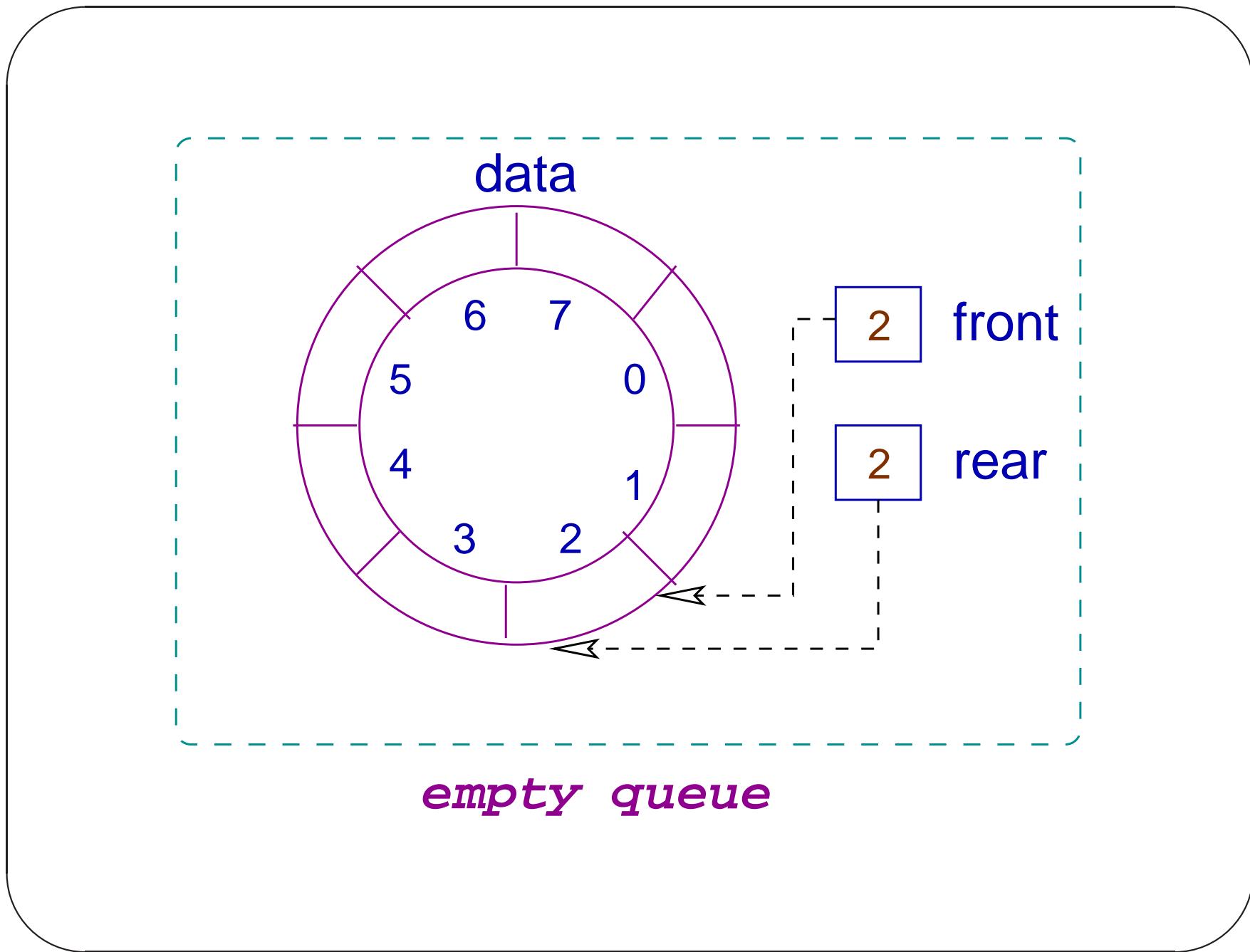
```
$ cc -Wall testStack.c stack.o  
We get the executable module a.out.
```

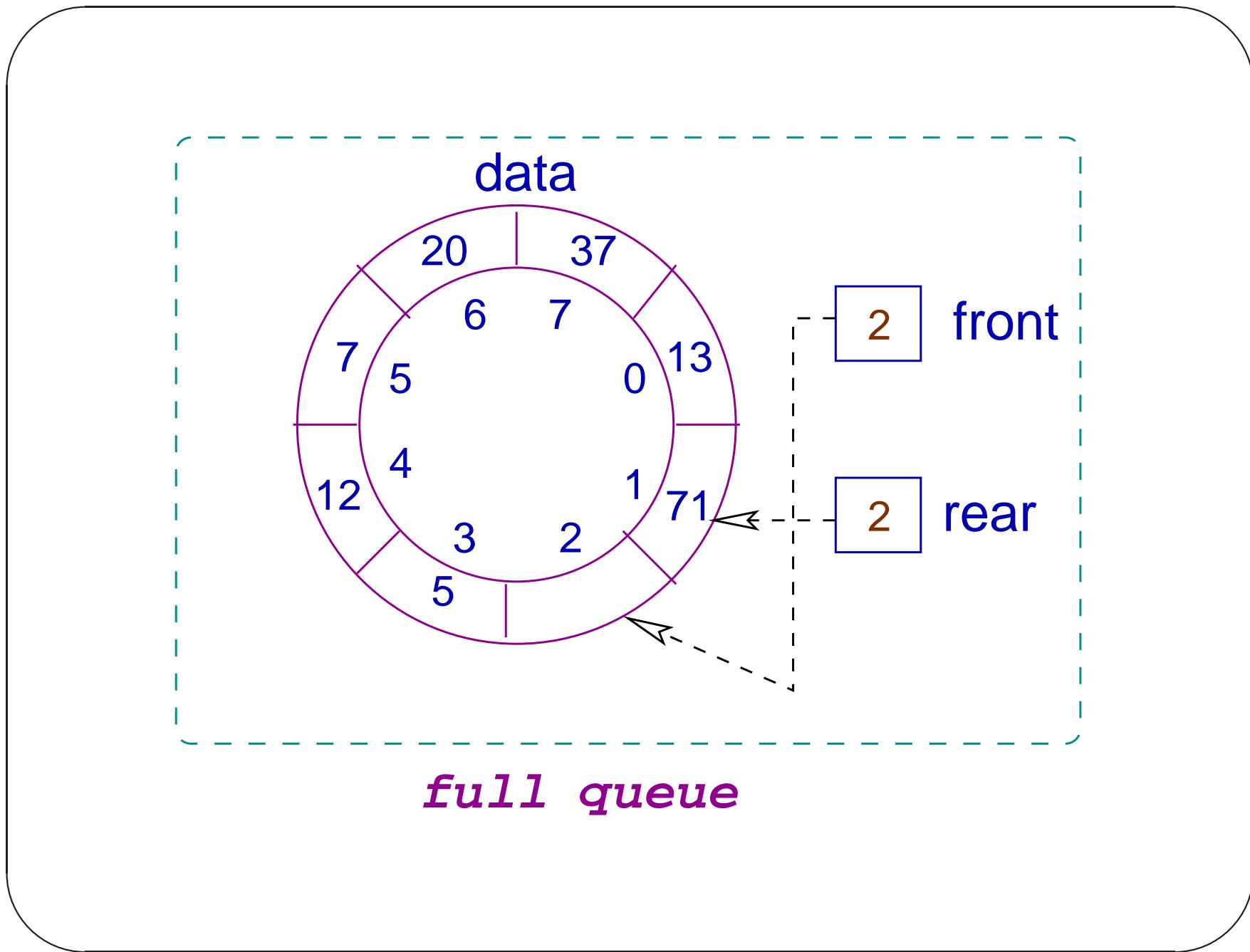
## Queue on Circular Array: Representation

```
#define MAX 200
typedef struct {
    int data[MAX] ;
    int front , rear ;
} queue;
```

The queue may contain  $\text{MAX} - 1$  data.







## Queue on Circular Array: Operations

```
void init(queue *) ;  
int add(queue *, int) ;  
int delete(queue *) ;  
int front(queue *, int *) ;  
int isEmpty(queue *) ;  
int isFull(queue *) ;
```

## Interface File: queue.h

```
#include <stdio.h>

#ifndef _QUEUE_H
#define _QUEUE_H

#define MAX 200
#define ERROR 1
#define OK 0

typedef struct { // queue.h
```

```
int data[MAX];  
int front, rear;  
} queue;  
  
/* Queue may contain MAX-1 data.*/  
  
void init(queue *);  
int add(queue *, int);  
int delete(queue *);  
int front(queue *, int *);  
int isEmpty(queue *);
```

```
int isFull(queue *);  
#endif
```

## Implementation File: queue.c

```
#include "queue.h"

void init(queue *q) // queue.c
{ q->front=q->rear=0; }

int isEmpty(queue *q)
{ return q->rear == q->front; }

int isFull(queue *q)
{ return (q->rear+1)%MAX == q->front; }
```

```
int add(queue *q, int n) {  
    if(isFull(q)) return ERROR;  
    q->rear=(q->rear+1)%MAX;  
    q->data[q->rear]=n;  
    return OK ;  
}  
  
int delete(queue *q) {  
    if(isEmpty(q)) return ERROR ;  
    q->front=(q->front+1)%MAX ;
```

```
        return OK ;  
    }  
  
int front(queue *q , int *v) {  
    if(isEmpty(q)) return ERROR ;  
    *v=q->data[(q->front+1)%MAX] ;  
    return OK ;  
}
```

## User Program: testQueue.c

```
#include "queue.h"
int main() // testQueue.c
{
    queue q ;
    int x , err , val ;
    char c;

    init(&q);
    printf(" 'A' for add (A 15)\n") ;
    printf(" 'D' for delete\n 'F' for front\n 'E' for exit
while((c = getchar()) != 'e' && c != 'E')
    switch(c) {
```

```
case 'a' :  
case 'A' :  
    scanf("%d", &x);  
    err = add(&q, x);  
    if(err) printf("The Queue is full\n");  
    break;  
case 'd' :  
case 'D' :  
    err = delete(&q);  
    if(err) printf("The Queue is empty\n");  
    break;  
case 'f' :  
case 'F' :  
    err = front(&q , &val) ;
```

```
        if(err) printf("The Queue is empty\n") ;
else printf("%d\n",val);
break;
case '\n' :
case '\t' :
case ' ' :
break;
default :
printf("Token Unknown\n");
}
return 0 ;
}
```

## Time Complexity of Operations

Both in stack and queue the running time of each operation is  $O(1)$ . Similarly the space complexity of each operation is also  $O(1)$ .

## Queue on Circular Array: A Variation

We may use a counter and keep data in all the array locations. In practice the array locations may be a structure and a counter is just a variable of type int.

```
#define MAX 200
typedef struct {
    int data[MAX] ;
    int front, rear, count ;
} queue;
```