



G

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D

Binary Trees

Binary Search Trees

Array

Linked List

↳ Capture Order

set

Binary Trees

- Capture Hierarchy

Binary Tree is a set of elements with

→ one special symbol called root

→ all other elements can be partitioned into two sets (possibly empty)

* left
* right } both these are binary trees themselves

leaf node \Rightarrow a node with 0 children

left subtrees of root(z)

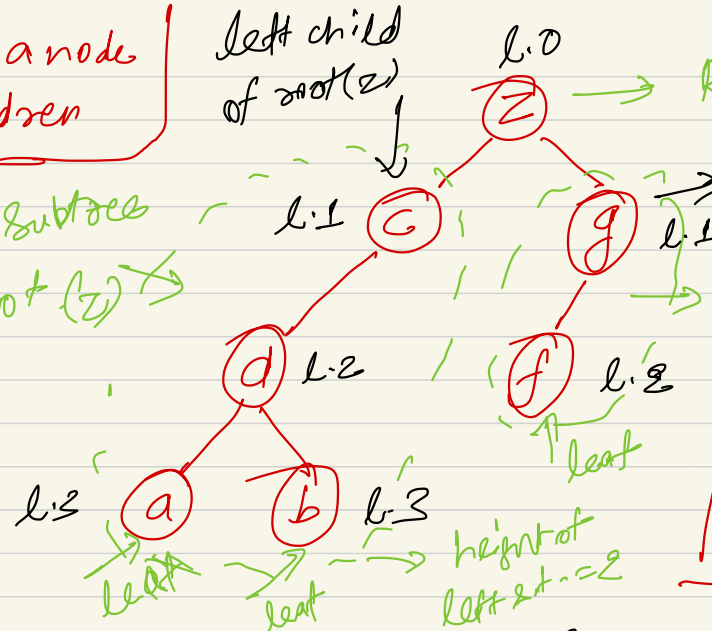
left child of root(z)

l.0 \rightarrow Root

right child of root(z)

right subtrees of root(z)

Height = 3
root(z)



height of left subtree = 2

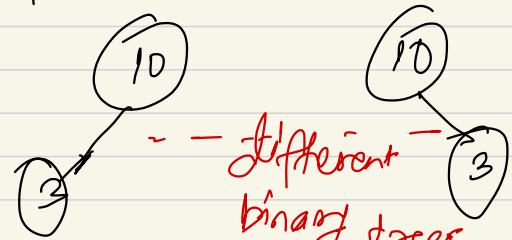
There is no cycle \Rightarrow there is exactly one path from any node to any other node

left-right distinction is important

parent of c? \rightarrow z

left child of d? \rightarrow a

left child of g? \rightarrow NIL



$\{ \frac{3}{10} \}$

* level of root node = 0
* level of any node = distance of the node from root

distance of a node from root

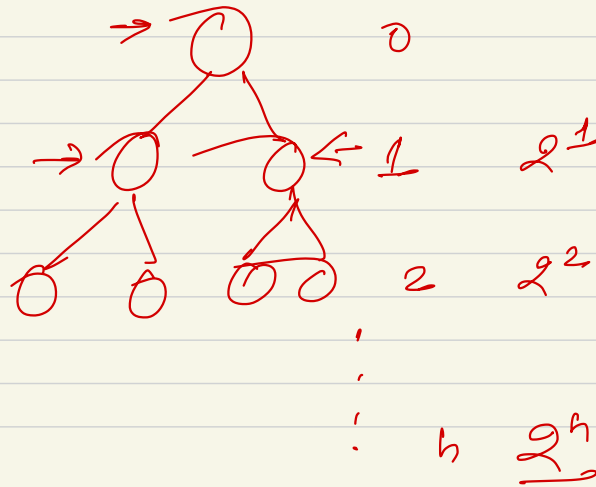
= No. of edges in the path from root to the node

Height of a tree = maximum level of any node in the tree

* Max. no. of nodes at level h , = 2^h

* Max. no. of nodes in a tree with height h

$$\Rightarrow 2^0 + 2^1 + \dots + 2^h$$
$$= \underline{2^{h+1} - 1}$$



* Min height of a tree with n nodes

$$n \leq \underbrace{2^{h+1} - 1}_{\text{max. nodes}}$$

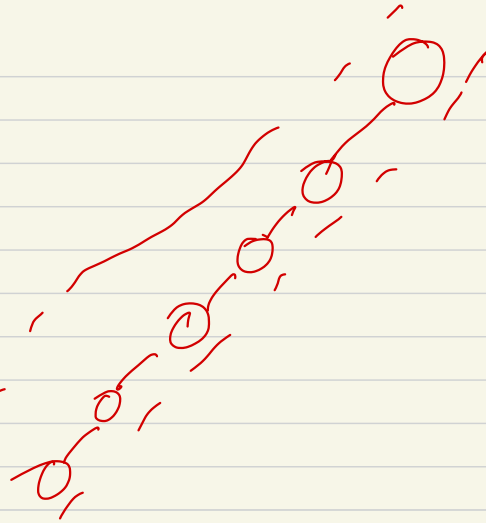
$$\begin{aligned} \underline{h} &\geq \log_2(n+1) - 1 \\ &= \underline{\Omega(\log n)} \end{aligned}$$

Can we say $h = O(\log n)$?

Max. possible height for a tree with n nodes

n nodes

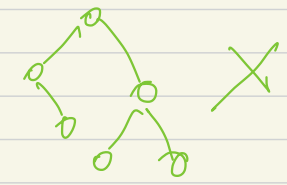
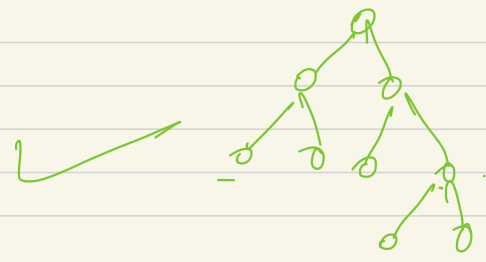
→ height
= $n+1$



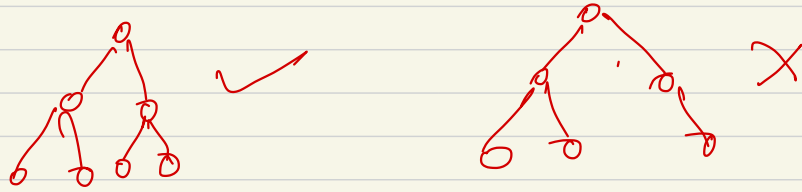
$$h = O(n)$$

$$\Omega(\log n)$$

Full Binary Trees \rightarrow Binary Trees whose all nodes have either 0 or 2 children

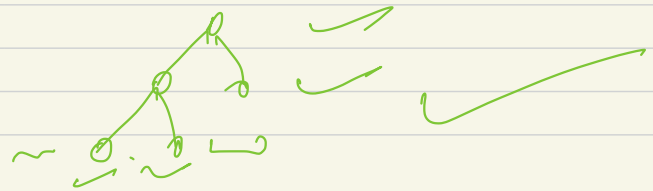
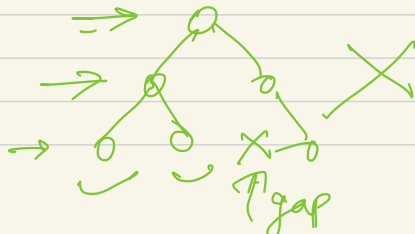


Complete Binary trees of height $h \Rightarrow \underline{2^{h+1} - 1}$ nodes



Almost (nearly) complete Binary trees \Rightarrow Nodes are filled from top to bottom & left to right (at any level) with no gaps left

\Rightarrow At the last level, you may not have all the nodes



Operations on a Binary Tree

Main application comes with special types of b. trees (with more restrictions on structures)

* Main operation is Traversal

— 'visit' each node once

→ What should be the order?

PreOrder

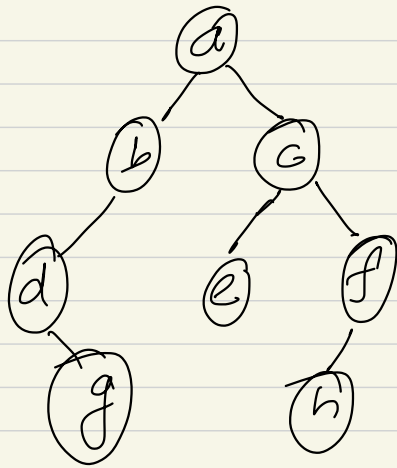
- root
- left subtree
- right subtree

Inorder

- left subtree
- root
- right subtree

Post-order

- left subtree
- right subtree
- root



Preorder root, left, right
a, b, d, g, c, e, f, h

Inorder left, root, right
 d, g, b, a, e, c, h, f

Post order left, right, root
 g, d, b, e, h, f, c, a

For a node x

— Key(x) = data stored in x

left(x) = left child of x

right(x) = right child of x

parent(x) = parent of x

[e.g. c]

[e.g. e]

[e.g. f]

[e.g. a]

= NIL
 if doesn't
 exist

Preorder (x)

root, left, right

if x = NIL return

main
cases

right (x) \Rightarrow print additions --
preorder (left [x])
preorder (right [x])

Inorder (x)

Inorder (left [x])

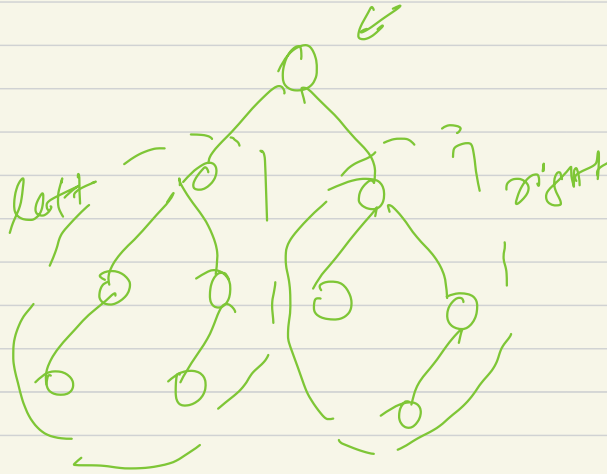
right (x)

Inorder (right [x])

Postorder

Complexity \Rightarrow Constant # of operations
on each node $\leq \underline{cn}$
 $= O(n)$

* What is the size of the trees? (# nodes)



$$1 + \text{size}(\text{left}) + \text{size}(\text{right})$$

```
int findSize(x)
```

```
    count = 0;
```

```
    if (x == NULL) return 0;
```

```
    C1 = findSize(left[x]);
```

```
    C2 = findSize(right[x]); return C1 + C2 + 1;
```

Suppose each node stores an integer value.

* Find the sum of the values of nodes

* Count the elements $< / >$ a certain value
 $< 10 ?$

$O(n)$

* Count the number of leaf nodes
(# children = 0)

How do you represent a binary tree?

typedef struct node {

int key;

struct node *left, *right, *parent;

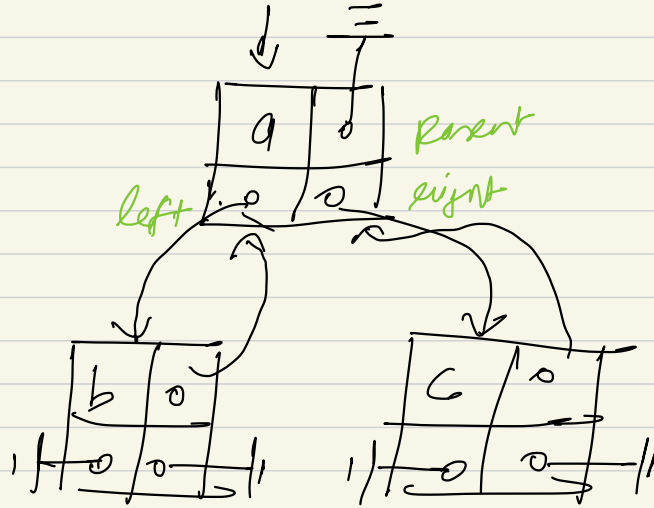
} NODE;

Represent trees
by a pointer
to the root



* left & right pointers
are always there

* parent may / may not
be there



put some restrictions

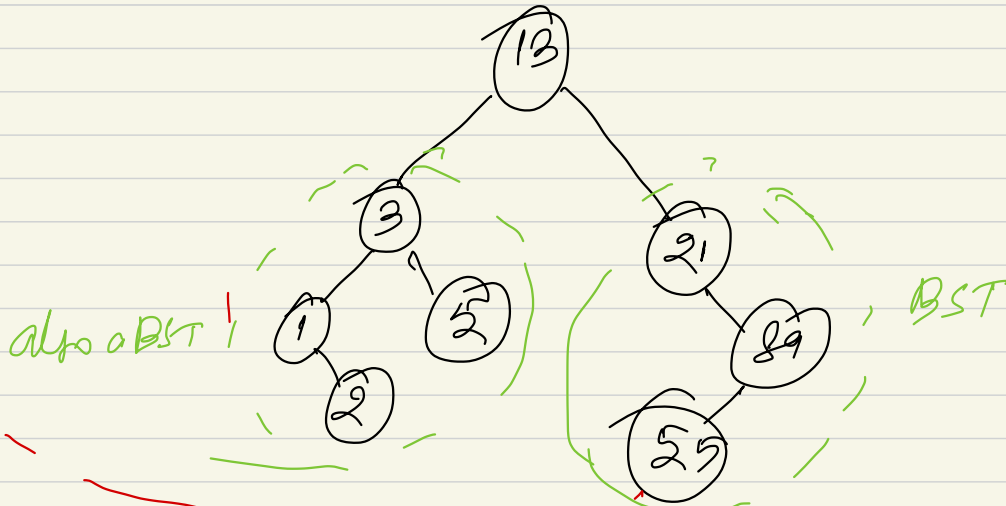
special kinds of binary trees

Binary Search Tree (BST)

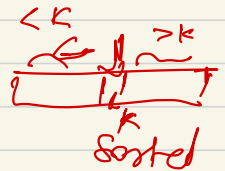
Binary Search Tree (BST)

BST is a binary tree such that for any node (root), the values in its left subtree are smaller than the value of the node, and the values in the right subtree are greater than the value of the node.

Insert 23



Search 89



~~23~~

Main Operations

- Search: ✓
- Insert.
- Delete.

Others

- Find Min
- Find Max
- Find Successor
- Find Predecessor

Complexity

$$= O(h(T))$$

$$= O(n)$$

Point points

Search (x, k)

if ($x = NULL$) return not found;

if ($key[x] = k$) return found;

if ($key[x] > k$) return search(left[x], k);

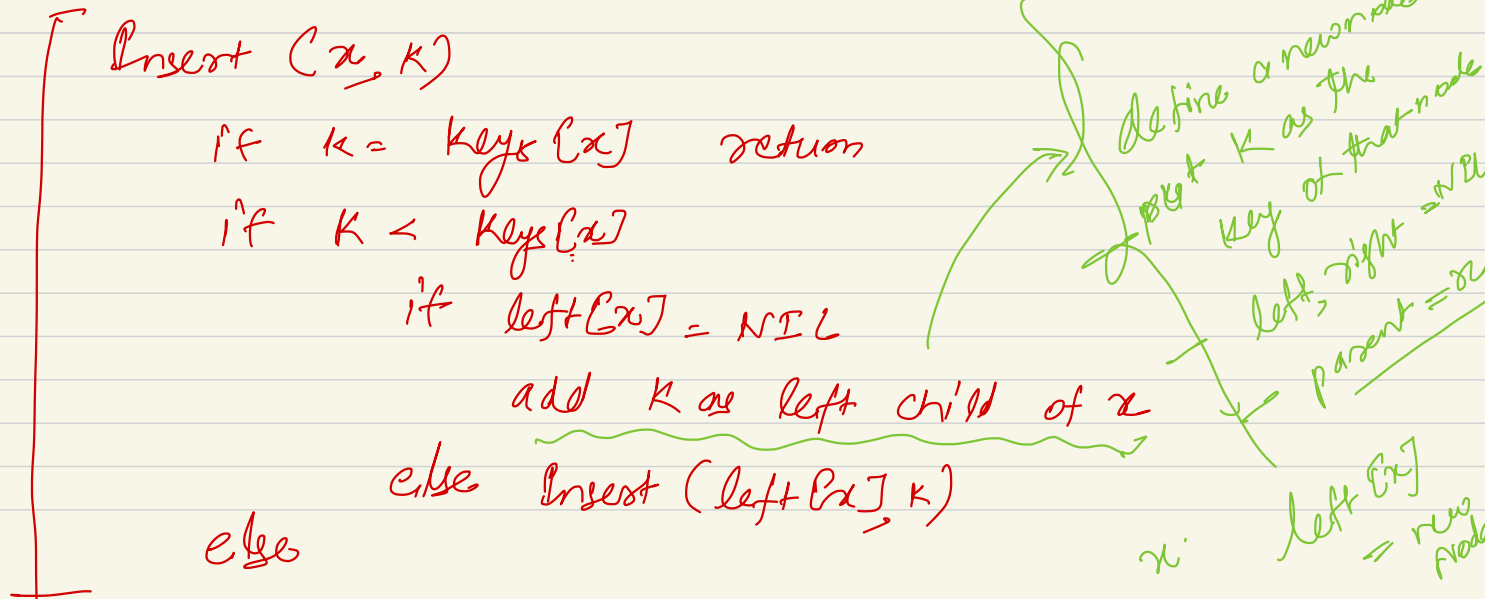
if ($key[x] < k$) return search(right[x], k);

Searching in BST resembles binary search in sorted arrays

Insert operation in BST

If the value is already present in BST we return the same tree.

otherwise, we insert the new value as a leaf node in an appropriate position.



Create a BST, print elements (some traversal orders)

Search

Insert

Copy

C Program

BST

Search

$O(h)$

$O(n)$

Insert

$O(h)$

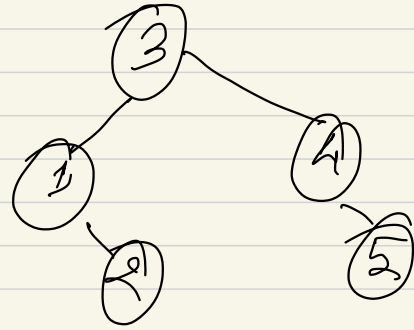
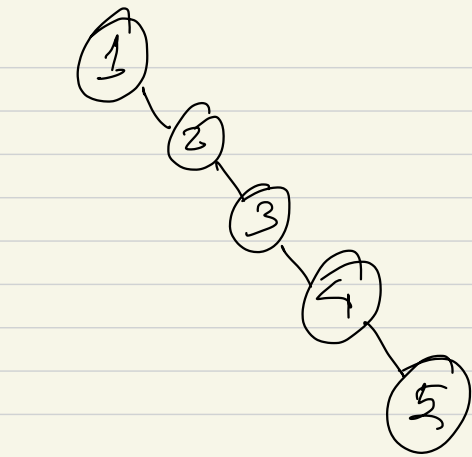
$O(n)$

set {1, 2, 3, 4, 5}

BST ?

Sorted array

[1 | 2 | 3 | 4 | 5]



separate BSTs

1, 2, 3, 4, 5
2, 3, 4, 5

Given a BST, can you print all the values in a sorted order?

Hint: In-order? Pre-order

1, 2, 3, 4, 5

Find Min(x)

while left[x] != NIL

x = left[x]

return x

Find Max(x)

while right[x] != NIL

x = right[x]

return x

$O(h)$

$O(\log n)$

$O(n)$

Traversal

Find Successor

: immediately next value in the sorted order

$O(h)$?

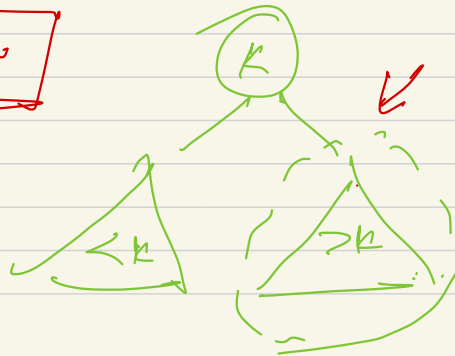
If \exists a right child

↳ min. of right child

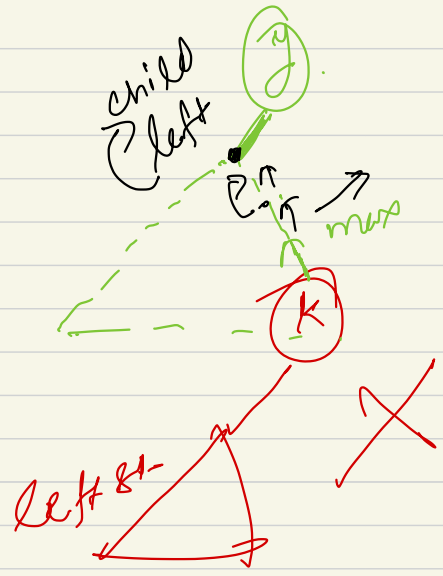
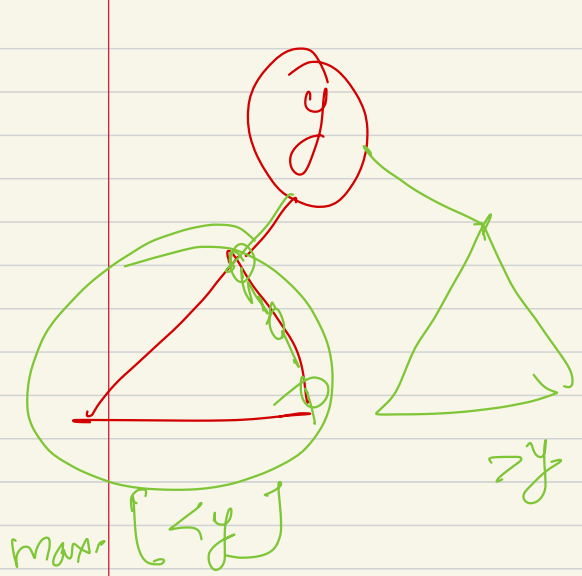
If no right child

??

min. of all values larger than k



right child



k is the right child

successor?

let y be the successor

↓

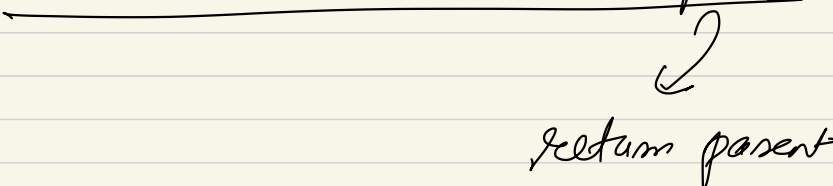
k

{ k will lie in the left sub. of y } k will be predecessor of y
 if it will be the min element
 max.
 ↓
 prec. element inserted.

You've to find a node such that K is the largest
in its left subtree

Keep following the parent pointers until you

Find a node that is left child of its parent



return parent

Suppose we've the parent pointer

BST - successor (x)

if right[x] != null

return findmin(right[x])

y = x.p // parent [x]

while y != null & x = y.right // right [y]

x = y

y = y.p

return y

BST - predecessor (x)

BST - DELETE

Delete a node from BST - x

Case 1: If x has no children

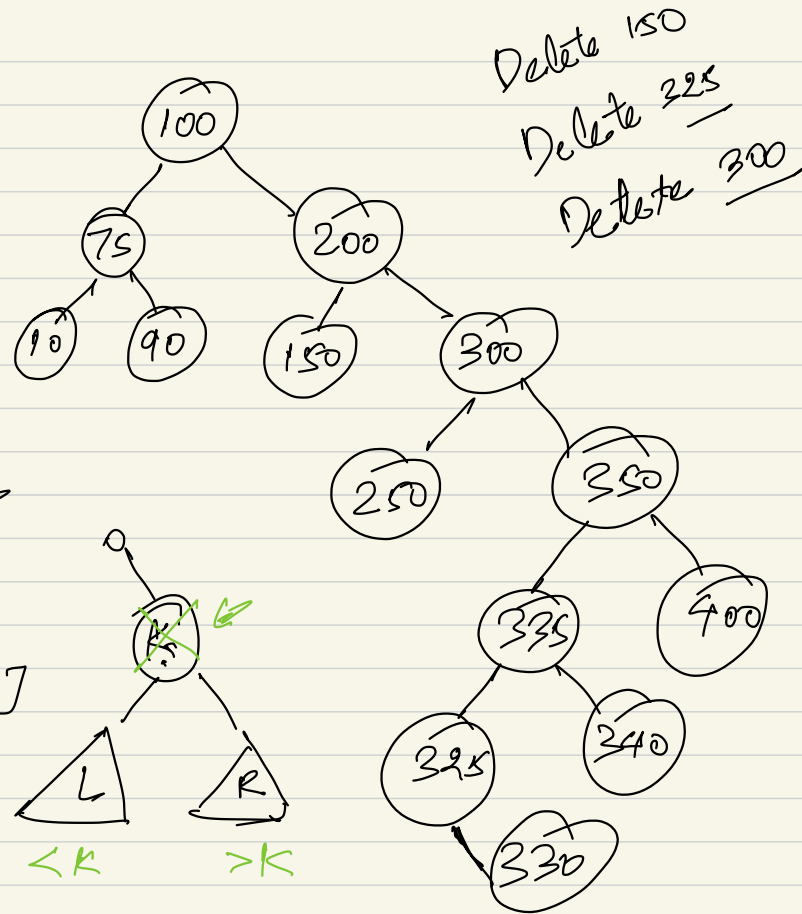
\Rightarrow Remove it by modifying the parent to replace x with \max of the cor. child.

[x is left / right child of p]
replace cor. pointer by tree

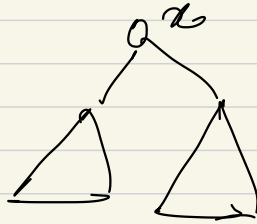
Case 2: If x has just one child

[one subtree]

\Rightarrow We elevate the child to take x 's position in the tree



Case 3: If x has 2 children



Take the min. value from
the right subtree of x
: y

Alternate 1:-

Find the predecessor
of x (i.e. left child)

Repeat similar
steps

1. $key[x] = key[y]$

2. Delete the node y using
either case 1 or 2

[because y can't have a
left child]

Each of the operations in BST T

- search
- insert
- delete

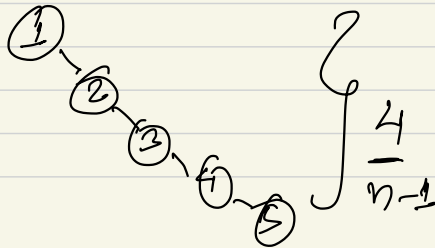
take $O(h)$ time

in the worst case

$O(n)$

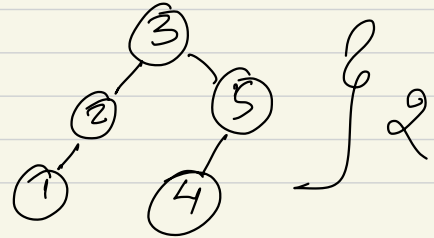
Height of a BST depends on the sequence in which the values are inserted.

1, 2, 3, 4, 5



1, 2, 3, 4, 5

3, 2, 1, 5, 4



Prove/
Disprove: When the values are in sorted order (increasing / decreasing) the maximum height of a BST is achieved only

$O(h)$ $O(n)$
Can we somehow ensure the height of a BST to be $O(\log n)$?

The idea: \rightarrow Modify the insert & delete functions in such a way that the height of the trees at any time does not grow too much & stays not far away from the best possible height (logarithm in the size of the trees)

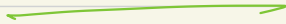
* If such adjustments can be made efficiently, we keep the height bounded by $O(\log n)$. \Rightarrow All major op^s are $O(\log n)$

Keeping the height of a tree with n nodes limited by an $O(\log n)$ value is commonly known as height-balancing.

a tree with height $O(\log n)$ is called a height-balanced tree

→ Red-Black Trees

→ AVL trees ✓



AVL Trees

(height balanced BSTs)

admissible trees

$$h = O(\log n)$$

Defining Property of AVL Trees \Rightarrow

Let u be any node in an AVL tree. Let L & R be the left and right subtrees of u . Then, we must have

$$|h(R) - h(L)| \leq 1$$

In other words, the heights of the left & right subtrees of any node in an AVL tree differ by at most one.

* If we can maintain this property $\Rightarrow h = O(\log n)$

\rightarrow How do we maintain this property (efficiently)

In addition to key, left, right, (parent) a node in an AVL tree

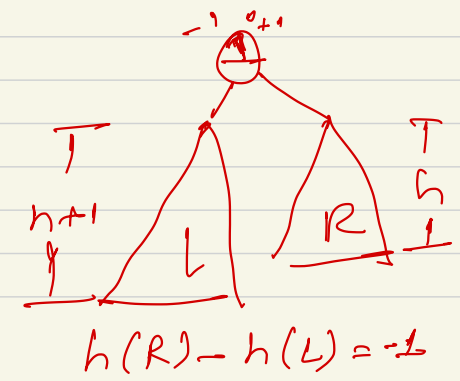
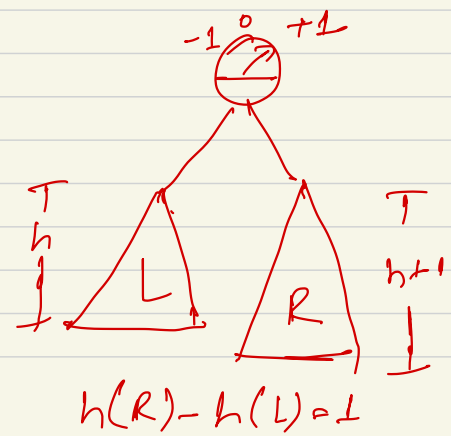
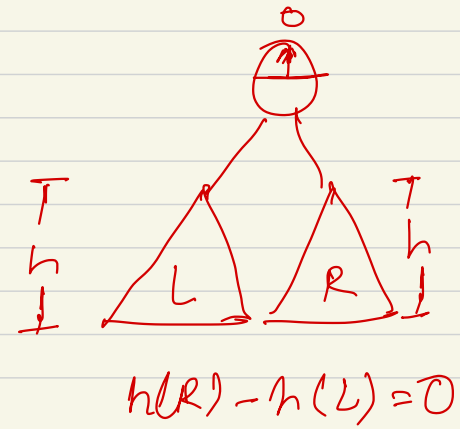
should maintain the balance factor of the node.

~~$h(L) - h(R)$~~ $h(R) - h(L)$

Values 0, +1, -1 can be used

[No need to store
ind. heights]

[CF by insert/
delete
balance factor
goes beyond
do sth.]



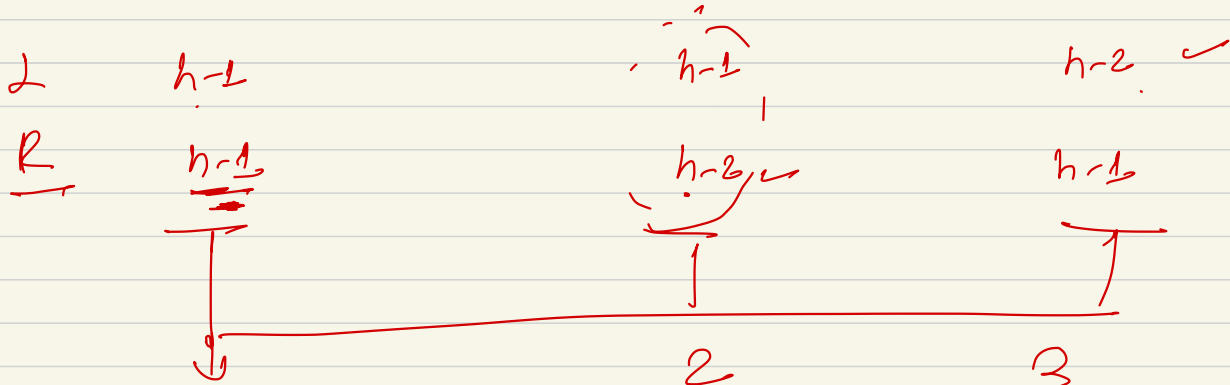
$$h = \Omega(\log n)$$

$$h = O(\log n)$$

$$|h(R) - h(L)| \leq 1 \Rightarrow h = O(\log n)$$

Given an AVL tree of height h , let M_h be the min number of possible nodes.

left & right subtrees



at least one more node

that the min possible nodes is Case 2 Case 3

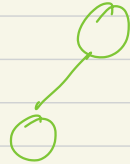
Assume left & right subtrees are AVL trees with min # of nodes

$$M_h = M_{h-1} + M_{h-2} + 1$$

$$M_0 = 1$$

$$M_1 = 2$$

$$\underbrace{M_{h+1}} = \underbrace{M_{h-1} + 1} + \underbrace{M_{h-2} + 1}$$



Let $N_h = \underline{M_{h+1}}$

$$\Rightarrow N_h = N_{h-1} + N_{h-2}$$

$$N_0 = 2$$

$$N_1 = 3$$

Recurrence for fibonacci
Numbers

$$N_h = F_{h+3} \approx \frac{1}{\sqrt{5}} \phi^{h+3}$$

* AVL tree is also referred as a fibonacci trees *

Let T be any AVL tree of height h with n nodes

$$n \geq M_h \approx \frac{1}{\sqrt{5}} \phi^{h+2} - 1$$

$$h \leq \frac{\log(n+1) + \log(\sqrt{5})}{\log(\phi)} \quad \rightarrow 3$$

$$\approx 1.44 \log n$$

$$\Rightarrow h = O(\log n)$$

\Rightarrow AVL tree is height balanced

$$\underbrace{|h(R) - h(L)|}_{\leq 1} \leq 1$$

Operations Θ -

Search Θ \rightarrow Can be carried out similar to BST.
 $O(\log n)$

Insertion / Deletion

! \rightarrow also proceed in the same way as in BST, but it may throw the trees out of balance.

\Rightarrow Some additional work is required to maintain the AVL property.

Insertion \Rightarrow Follow the procedure similar to BST.

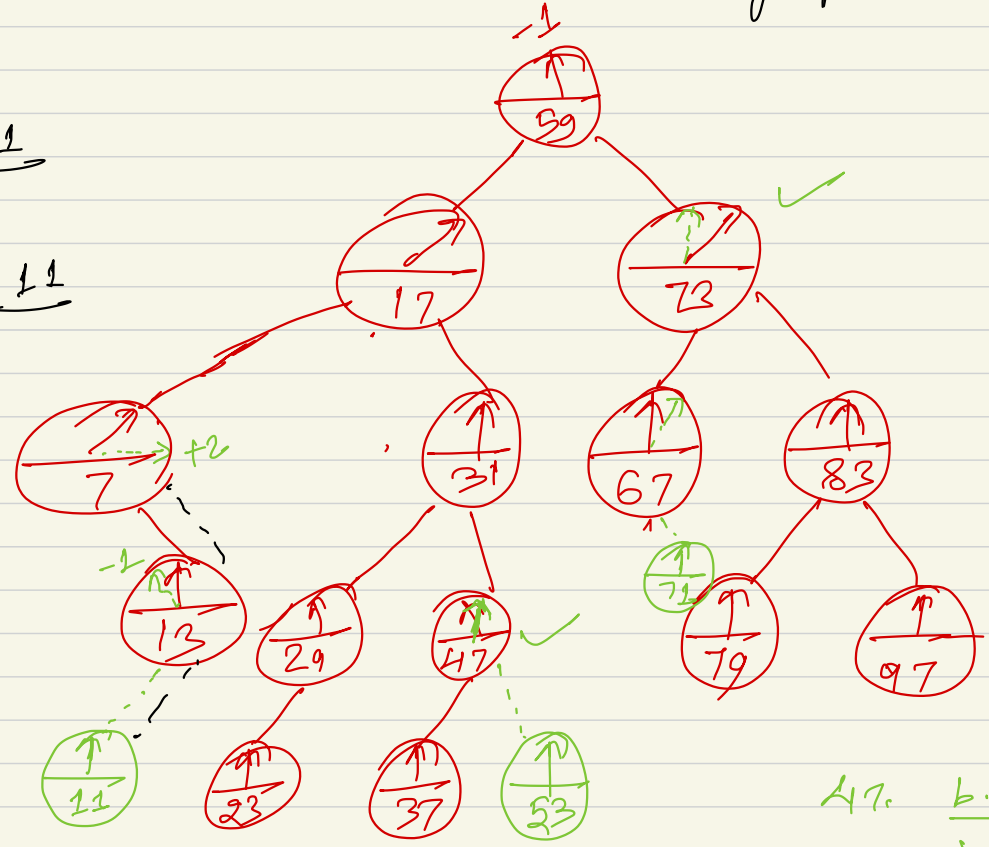
\rightarrow Finding a unique path from the root to node u , and inserting new value in a new leaf node as a child of u .

Now, we traverse the path upward, from this inserted leaf node to the root, and adjust the balance factors.

If the adjustment leads to a height difference of 2, we've to perform something special to restore height.

Insert 71

Insert 11



Insert 53

For a node y,
if balance factor
changes from ± 1 to 0

\Rightarrow Now, it has
become balanced
but the height of
tree rooted at
u doesn't

47. b. -1 \rightarrow 0
inserted right child

change

Overall trees
at u has
the same height \Leftarrow

$$-1 \text{ to } 0 \Rightarrow$$

+1

Right st. has gained
height (+1)

left st has same height

Overall trees
at u has
gained height

$$0 \text{ to } \pm 1 \Rightarrow$$

one of the subtrees
has gained height

\rightarrow You'll have to go up

Let's abstract this.

Consider a situation where balance factor of -2 is detected at a node U .

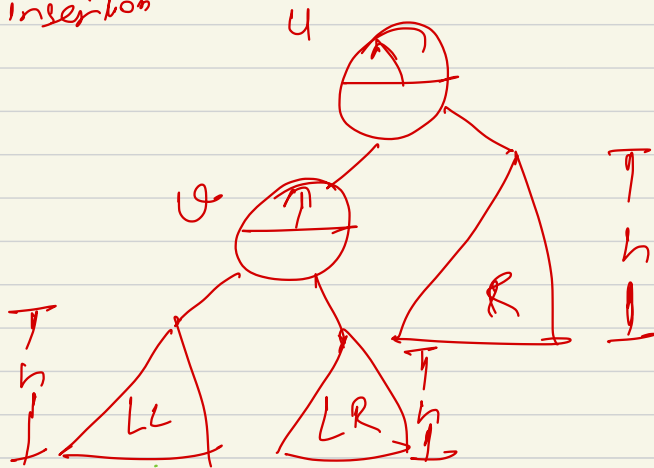
\Rightarrow Prior to insertion, this would have been left-heavy (-1).

Change from -1 to -2 implies that left child has gained height \Rightarrow left child's balance factor would have gone from 0 to $\underline{+1}$.

Let's take cases

U	$\underline{-2}$
U	± 1
	$\underline{+1} \quad \underline{-1}$

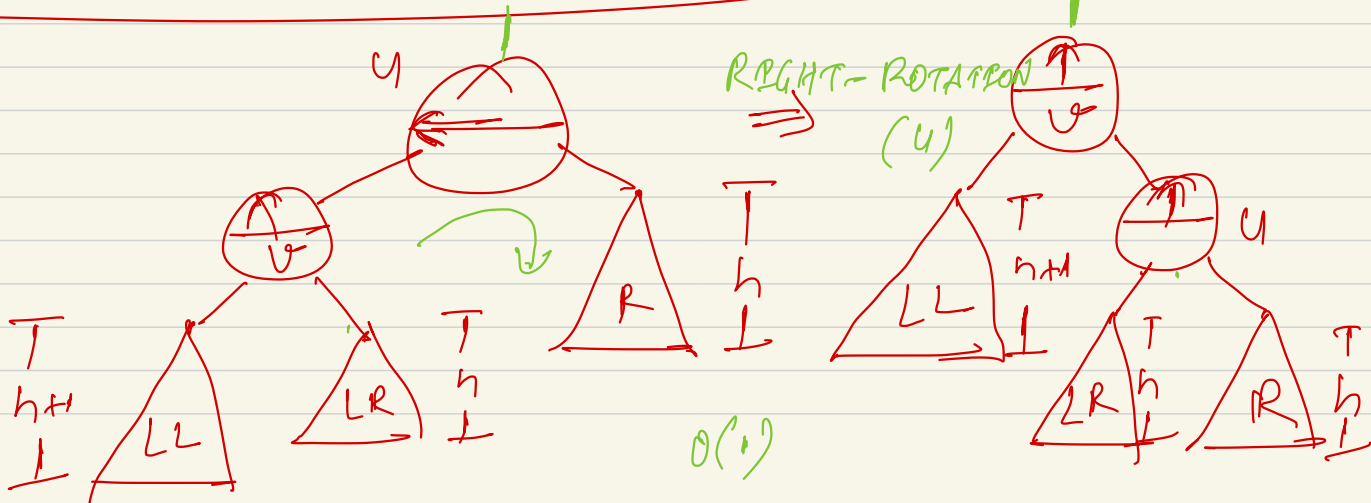
Before insertion

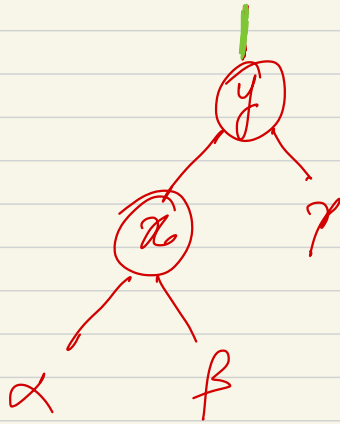


u & v have the same sign after insertion

Case 1.

insertion in LL

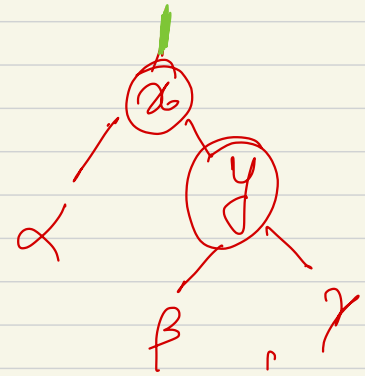




← LEFT-ROTATE (x)

→

RIGHT-ROTATE (T, y)



Operations that preserve BST properties;

Inorder

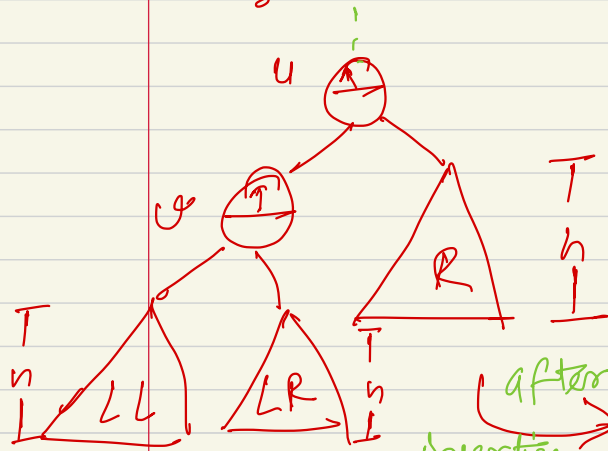
$$\alpha \cdot \text{key} < x \cdot \text{key} < \beta \cdot \text{key} < y \cdot \text{key} < \gamma \cdot \text{key}$$

Change some pointers \Rightarrow
 Constant numbers of
 pointer assignments

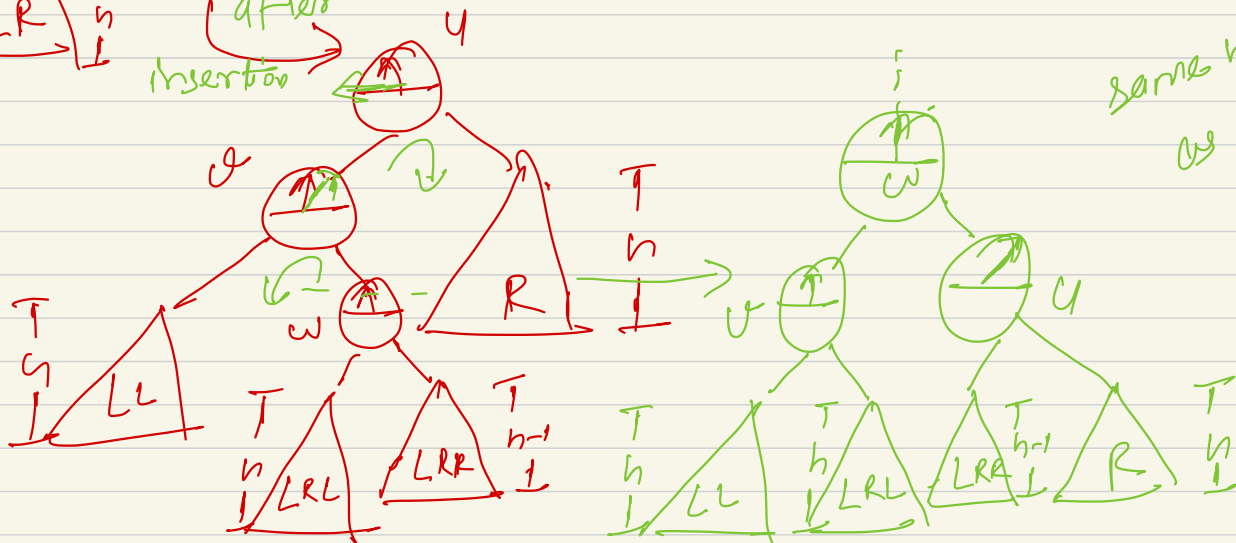
$\alpha \cdot \text{key} < x \cdot \text{key} < \beta \cdot \text{key} < y \cdot \text{key} < \gamma \cdot \text{key}$
 $O(1)$ -time

Case 2: Balance factors of u & v have opposite signs

Insertion in LR



after insertion



same height as before insertion.

* Even if insertion in LRR \Rightarrow w still has a 0 balance.

Insertion in AVL Tree:-

$O(h)$

Proceed like in BST (insert a new node)

→ Go up (traverse upto the root following path from this new leaf) $O(h)$

→ Update the balance factors

either

- You're done & don't have to go up ($\pm 1 \neq 0$)

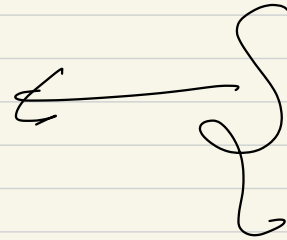
or - You find a node at which balance factor is ± 2 .

Restore the balance (don't have to go up)

1 rotation { Case 1

2 rotations { Case 2

$O(h) + O(h) = O(h)$



Deletion in AVL Trees

— Follow deletion in BST

— Restore the balance

→ rotations

↳ at every node on
the path in the
worst case

$O(\log n)$. constant operations

↓ = $O(\log n)$

Find the cases of deletion

Search
 Insert
 Delete } $O(\log n)$

Sorted array + Binary Search →
 vs

Storing Keys

Roll Nos

AVL Tree + Search

{ insert
 { delete

	Search	Insert	Delete
<u>Sorted Array</u>	$O(\log n)$	$O(n)$	$O(1)$
<u>AVL Tree</u>	$O(\log n)$	$O(\log n)$	$O(\log n)$

Sorting based on AVL trees

n integers values : sort them in increasing order.

Sorting — BST [in-order traversal]
 $O(n)$

Creating an AVL tree for n integers

$$\underline{O(n \log n)} + O(n)$$

AVL-Sort

→ $O(n \log n)$

create AVL
trees

In-order traversal

Binary Trees

Binary Search Trees

Height-balanced Binary Search Trees

(AVL Tree)

AVL-Soft

ROTATIONS

Red-black
Balanced Binary Search
Trees