# LOGICAL DEDUCTION IN AI

#### **INFERENCING BY RESOLUTION REFUTATION**



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## Solve the "Alpine Club Problem" using FOL

Tony, Mike, and John belong to the Alpine Club. Every member of the Alpine Club is either a skier, a mountain climber, or both. No mountain climber likes rain, and all skiers like snow. Mike dislikes whatever types of weather Tony likes and likes whatever types of weather Tony dislikes. Tony likes rain and snow. Is there a member of the Alpine Club who is a mountain climber but not a skier? If so, who?

#### **Alpine Club Problem**

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# SEARCH IN AI

#### CONSTRAINT SATISFACTION PROBLEMS

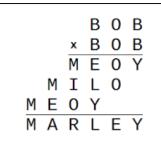


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#### **Constraint Satisfaction Problems (CSPs)**

8



**CRYPTARITHMETIC PUZZLE** 

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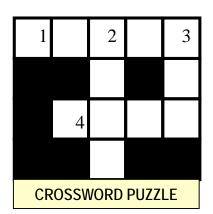
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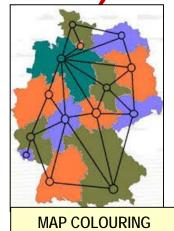
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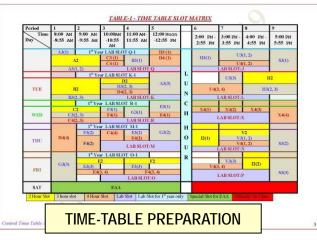
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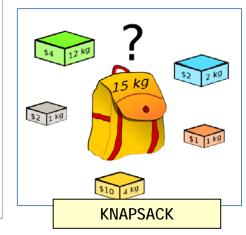




| Flight No | Destination   | Time | Gate | Remarks            |
|-----------|---------------|------|------|--------------------|
| CX7183    | Berlin        | 7:50 | A-11 | Gate closing       |
| QF3474    | London        | 7:50 | A-12 | Gate closing       |
| BA372     | Paris         | 7:55 | B-10 | Boarding           |
| AY6554    | New York      | 8:00 | C-33 | Boarding           |
| KL3160    | San Francisco | 8:00 | F-15 | Boarding           |
| BA8903    | Manchester    | 8:05 | B-12 | Gate lounge open   |
| BA710     | Los Angeles   | 8:10 | C-12 | Check-in open      |
| QF3371    | Hong Kong     | 8:15 | F-10 | Check-in open      |
| MA4866    | Barcelona     | 8:15 | F-12 | Check-in at kiosks |
| CX7221    | Copenhagen    | 8:20 | G-32 | Check-in at kiosks |

AIRLINE GATE SCHEDULING



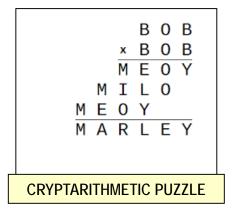


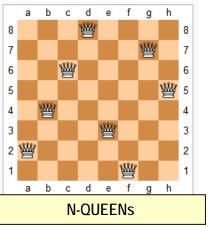
## **Basic CSP Formulation**

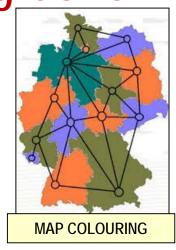
#### • Variables

- A Finite Set of Variables V\_1, V\_2, ...., V\_n
- Domains
  - Each Variable has a Domain D\_1, D\_2, ...., D\_n from which it can take a value.
  - The Domains may be discrete or continuous domains
- Satisfaction Constraints
  - A Finite Set of Satisfaction Constraints, C\_1, C\_2, ...C\_m
  - Constraints may be unary, binary or be among many variables of the domain
  - All Constraints have a Yes / No Answer for Satisfaction given values of variables
- Optimization Criteria (Optional)
  - A Set of Optimization Functions O\_1, O\_2, ....O\_p
  - These Optimization Functions are typically max or min type
- Solution
  - To Find a Consistent Assignment of Domain Values to each Variable so that All Constraints are Satisfied and the Optimization Criteria (if any) are met.



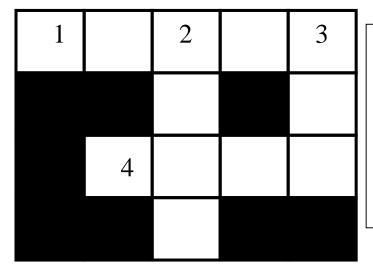






- 1. VARIABLES
- 2. DOMAINS
- 3. SATISFACTION CONSTRAINTS
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION

### Formulating CSPs: Crossword



| Word List:               |
|--------------------------|
| astar, happy, hello,     |
| hoses, live, load, loom, |
| peal, peel, save, talk,  |
| ant, oak, old            |

- 1. VARIABLES
- 2. DOMAINS
- 3. SATISFACTION CONSTRAINTS
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION

# Formulating CSPs: Flight Gate Scheduling

| Flight No | Dep Time | G Start | G End |
|-----------|----------|---------|-------|
| F1        | 7:00     | 6:15    | 7:15  |
| F2        | 8:30     | 7:45    | 8:45  |
| F3        | 7:45     | 7:00    | 8:00  |
| F4        | 9:45     | 9:00    | 10:00 |
| F5        | 10:00    | 9:15    | 10:15 |
| F6        | 9:00     | 8:15    | 9:15  |
| F7        | 11:00    | 10:15   | 11:15 |

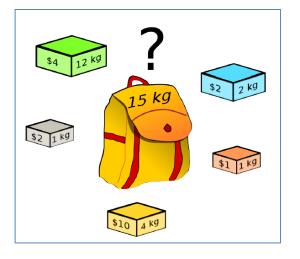
| 1. | VARIABLES |
|----|-----------|
| 2. | DOMAINS   |

3. SATISFACTION

CONSTRAINTS

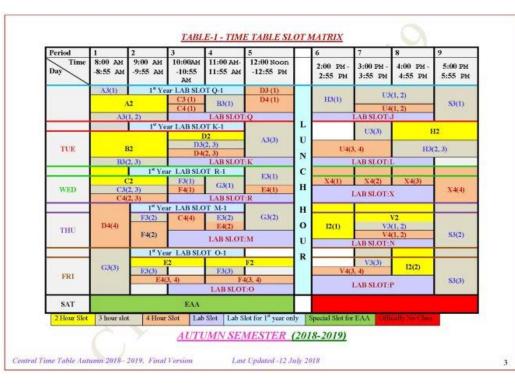
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION

### Formulating CSPs: Knapsack

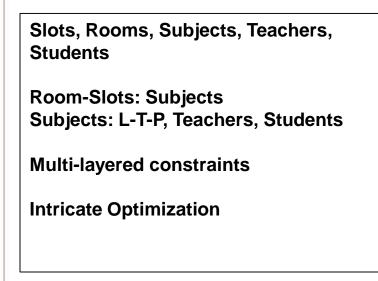


- 1. VARIABLES
- 2. DOMAINS
- 3. SATISFACTION
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION

# Formulating CSPs: Time Table



- 2. DOMAINS
- 3. SATISFACTION CONSTRAINTS
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION



# Exercise: Time-Tabling in the era of online classes

<sup>1.</sup> VARIABLES

#### Formulating CSPs: Time Table

- 1. VARIABLES
- 2. DOMAINS
- 3. SATISFACTION CONSTRAINTS
- 4. OPTIMIZATION CRITERIA
- 5. SOLUTION

## **CSP Solution Overview**

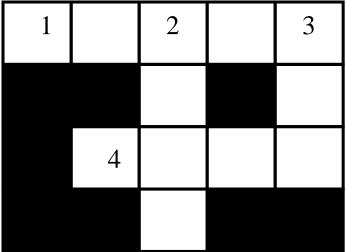
#### • <u>CSP Graph Creation</u>:

- Create a Node for Every Variable. All possible Domain Values are initially Assigned to the Variable
- Draw <u>edges</u> between Nodes if there is a Binary Constraint. Otherwise Draw a <u>hyper-edge</u> between nodes with constraints involving more than two variables
- <u>Constraint Propagation</u>:
  - Reduce the Valid Domains of Each Variable by Applying <u>Node Consistency</u>, <u>Arc / Edge</u> <u>Consistency</u>, K-<u>Consistency</u>, till no further reduction is possible. If a solution is found or the problem found to have no consistent solution, then terminate

#### • Search for Solution:

- Apply Search Algorithms to Find Solutions
- There are interesting properties of CSP graphs which lead of efficient algorithms in some cases: Trees, Perfect Graphs, Interval Graphs, etc
- Issues for Search: <u>Backtracking</u> Scheme, <u>Ordering</u> of Children, <u>Forward Checking</u> (Look-Ahead) using Dynamic Constraint Propagation
- Solving by <u>Converting to Satisfiability (SAT)</u> problems

#### **CSP Graph for Crossword**



#### Word List:

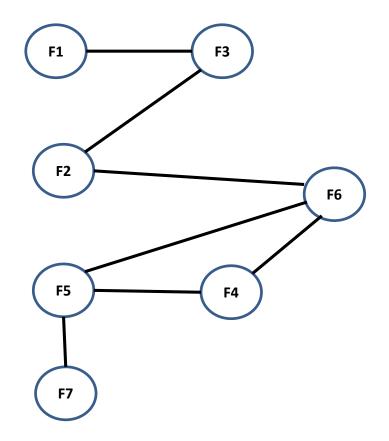
astar, happy, hello, hoses, live, load, loom, peal, peel, save, talk, ant, oak, old

## **CSP Graph for Airline Gate Scheduling**

| Flight No | Dep Time | G Start | G End |
|-----------|----------|---------|-------|
| F1        | 7:00     | 6:15    | 7:15  |
| F2        | 8:30     | 7:45    | 8:45  |
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## **Constraint Propagation Steps**

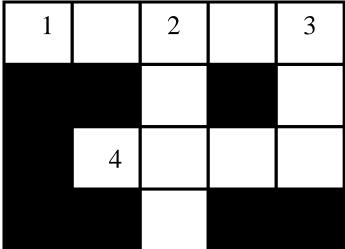
#### <u>Constraints</u>

- Unary Constraints or Node Constraints
- Binary Constraints or Edges between CSP Nodes
- Higher order or Hyper-Edges between CSP Nodes
- Node Consistency
  - For every Variable V\_i, remove all elements of D\_i that do not satisfy the Unary Constraints for the Variable
  - First Step is to reduce the domains using Node Consistency

#### Arc Consistency

- For every element x\_ij of D\_i, for every edge from V\_i to V\_j, remove x\_ij if it has no consistent value(s) in other domains satisfying the Constraints
- Continue to iterate using Arc Consistency till no further reduction happens.
- <u>K-Consistency or Path Consistency</u>
  - For every element y\_ij of D\_i, choose a Path of length L with L variables, use a consistency checking method similar to above to reduce domains if possible

# **CSP Graph for Crossword**



#### Word List:

astar, happy, hello, hoses, live, load, loom, peal, peel, save, talk, ant, oak, old

#### Applying Node Consistency:

- D1 = {astar, happy, hello, hoses}
- D2 = {live, load, loom, peal, peel, save, talk}
- D3 = {ant, oak, old}
- D4 = {live, load, loom, peal, peel, save, talk}

NOW APPLY ARC CONSISTENCY

Applying Arc Consistency: D1 = {astar, happy, hello, hoses}

D2 = {live, load, loom, peal, peel, save, talk}

D3 = {ant, oak, old}

D4 = {live, load, loom, peal, peel, save, talk}

## Arc Consistency Algorithm AC-3

AC-3(*csp*) // inputs - CSP with variables, domains, constraints

- 1. queue  $\leftarrow$  local variable initialized to all arcs in csp
- 2. while queue is not empty do
- 3.  $(X_i, X_j) \leftarrow \text{pop}(\text{queue})$
- 4. **if** Revise(csp,  $X_i$ ,  $X_j$ ) **then**
- 5. **if** size of  $D_i = 0$  **then return** false
- 6. **for each**  $X_k$  **in**  $X_i$ .neighbors- $\{X_j\}$  **do**
- 7. add  $(X_k, X_i)$  to queue
- 8. return true

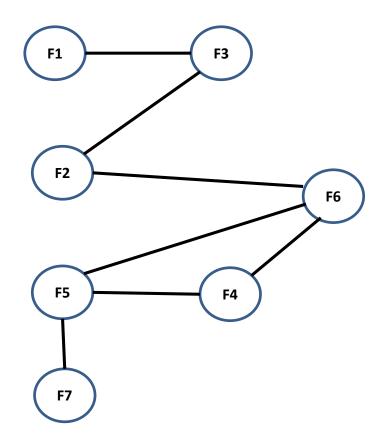
Revise( $csp, X_i, X_j$ )

- 1. revised  $\leftarrow$  false
- 2. for each x in  $D_i$  do
- 3. **if** no value y in  $D_j$  allows (x, y) to satisfy constraint between  $X_i$  and  $X_j$  **then**
- 4. delete x from  $D_i$
- 5. revised  $\leftarrow$  true
- 6. return revised

#### Time complexity: O(n<sup>2</sup>d<sup>3</sup>)

## **Consistency for Airline Gate Scheduling**

| Flight No | Dep Time | G Start | G End |
|-----------|----------|---------|-------|
| F1        | 7:00     | 6:15    | 7:15  |
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| F7        | 11:00    | 10:15   | 11:15 |



#### Backtracking Algorithm for CSP



CSP-BACKTRACKING(a)

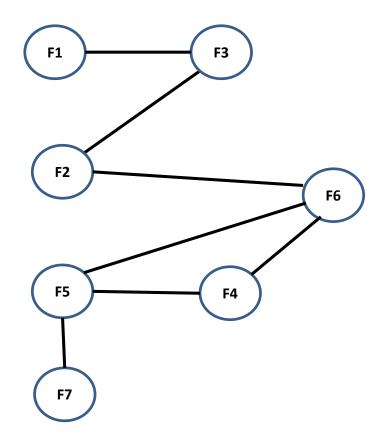
- If a is complete then return a
- − X ← select unassigned variable
- D  $\leftarrow$  select an ordering for the domain of X
- For each value v in D do
  - If v is consistent with a then
    - Add (X = v) to a

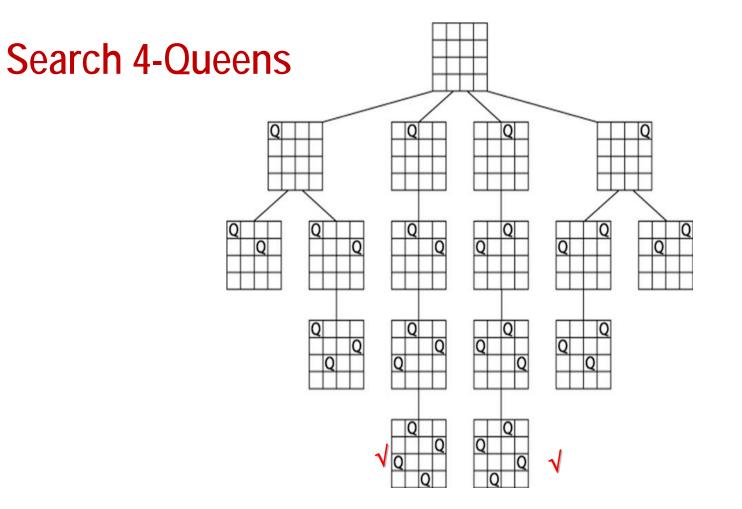
    - If result ≠ failure then return result
- Return failure



# **Backtracking for Airline Gate Scheduling**

| Flight No | Dep Time | G Start | G End |
|-----------|----------|---------|-------|
| F1        | 7:00     | 6:15    | 7:15  |
| F2        | 8:30     | 7:45    | 8:45  |
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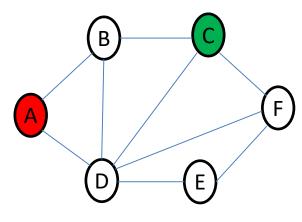


#### Strategies for CSP Search Algorithms

- Initial Constraint Propagation
- Backtracking Search
  - Variable Ordering
    - Most Constrained Variable / Minimum Remaining Values
    - Most Constraining Variable
  - Value Ordering
    - Least Constraining Value leaving maximum flexibility
  - Dynamic Constraint Propagation Through Forward Checking
    - Preventing useless Search ahead
  - Dependency Directed Backtracking
- SAT Formulations and Solvers
- Optimization
  - Branch-and-Bound
  - SMT Solvers, Constraint Programming
- Learning, Memoizing, etc
- CSP Problems are NP-Hard in General

#### Forward Checking: 3 Colouring Problem

Forward checking propagates information from <u>assigned</u> to <u>unassigned</u> variables

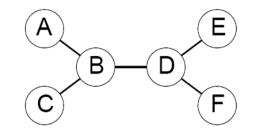


| А         | В         | С         | D         | E         | F         |
|-----------|-----------|-----------|-----------|-----------|-----------|
| {R, G, B} |
|           | {G, B}    | {R, G, B} | {G, B}    | {R, G, B} | {R, G, B} |
|           | (B)       |           | {B}       | {R, G, B} | {R, B}    |
| e!        |           | X         |           |           |           |

- B and D cannot both be blue!
- Why did we not detect this?
- Forward checking detects some inconsistencies, not all
- Constraint propagation: reason from constraint to constraint

#### **Special Cases**

Tree-structured CSPs



Theorem: if the constraint graph has no loops, the CSP can be solved in  ${\cal O}(n\,d^2)$  time

Compare to general CSPs, where worst-case time is  $O(d^n)$ 

For PERFECT GRAPHS, CHORDAL GRAPHS, <u>INTERVAL GRAPHS</u>, the Graph Colouring Problem can be solved in Polynomial Time

#### **MITTTS Lecture Scheduling Problem**

The MIT Time Travel Society (MITTTS) has invited seven famous historical figures to each give a lecture at the annual MITTTS convention, and you've been asked to create a schedule for them. Unfortunately, there are only four one-hour time slots available (1pm - 4pm), and you discover that there are some restrictions on how you can schedule the lectures and keep all the convention attendees happy.

For instance, physics students will be disappointed if you schedule Niels Bohr and Isaac Newton to speak during the same time slot, because those students were hoping to attend both of those lectures.

After talking to some students who are planning to attend this year's convention, you determine that they fall into certain groups, each of which wants to be able to see some subset of the timetraveling speakers. (Fortunately, each student identifies with at most one of the groups.) You write down everything you know:

The list of guest lecturers consists of Alan Turing, Ada Lovelace, Niels Bohr, Marie Curie,

Socrates, Pythagoas, and Isaac Newton.

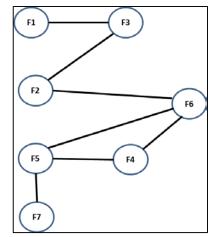
- 1. Turing has to get home early to help win World War II, so he can only be assigned to the 1pm slot.
- 2. The Course VIII students want to see the physicists: Bohr, Curie, and Newton.
- 3. The Course XVIII students want to see the mathematicians: Lovelace, Pythagoras, and Newton.
- 4. The members of the Ancient Greece Club wants to see the ancient Greeks: Socrates and Pythagoras.
- 5. The visiting Wellesley students want to see the female speakers: Lovelace and Curie.
- 6. The CME students want to see the British speakers: Turing, Lovelace, and Newton.
- 7. Finally, you decide that you will be happy if and only if you get to see both **C**urie and **P**ythagoras. (Yes, even if you belong to one or more of the groups above.)

#### You are to schedule these lectures satisfying the above constraints using minimum number of parallel sessions.

**MITTTS Lecture Scheduling Problem** 

#### Solving CSP using SAT / SMT Solvers

- Boolean Satisfiability (SAT) is a CSP
- CSPs can be modelled as SAT problems
  - Try: Map Colour, Gate Scheduling, n-Queens
  - Home Exercise: Write a Generic Scheme to Convert and CSP Problem to a SAT Problem
- SAT has very efficient solvers
  - MiniSAT, CHAFF, GRASP, etc
- For Optimization cases, we can formulate them as
  - Satisfiability Modulo Theories (SMT) with arithmetic and first order logic
  - 0/1 or Integer Linear Programming (ILP)
  - Constraint Programming Problems
  - SMT Solvers: Z3, Yices, Barcelogic, MathSAT, OpenSMT, etc



Thank you