

# Distinct Elements in Streams and the Klee's Measure Problem

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with Addendum from: Don Knuth

Corresponding publications: PODS-21, PODS-22, ESA-22

## A real life problem

How to keep a count (or approximate count) on the number of **DISTINCT** persons visiting your webpage?

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### Resource Minimization Objectives:

- Should not use too much space
- Should not take too much time to update your database

# Data Streams

**Goal:** Computation over a stream of items

- An item of the stream arrives & stored in temporary memory.
- The item is accessed using the allowed set of operations and some of the information is stored in a working space.
- The item then disappears and the next item arrives.

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- **Space complexity** - The (worst case) amount of space required.
- **Update-time complexity** - The (worst case) amount of time required to process any item.

## Set Streams: When the items are sets

### Union Size Estimation

Given a stream of sets  $S_1, \dots, S_m$ , all  $S_i \subseteq \Omega$  and two parameters  $\epsilon, \delta$

Output an estimate  $\mathcal{E}$  such that with probability  $\geq (1 - \delta)$

$$(1 - \epsilon) \left| \bigcup_{i=1}^m S_i \right| \leq \mathcal{E} \leq (1 + \epsilon) \left| \bigcup_{i=1}^m S_i \right|$$

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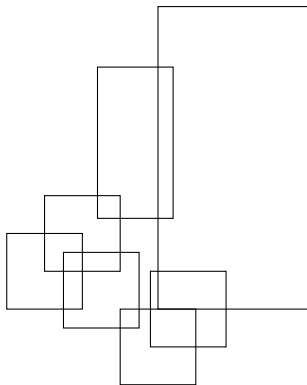
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Lets come back to these formalizations later.

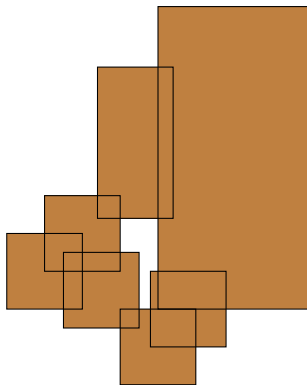
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  - Know the size of  $S_i$ :  $\mathcal{O}(d \log |\Delta|)$
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- Lot of work done, most recently by Tirthapura-Woodruff (2012), Vahrendhold (2007), Indyk-Woodruff (2005)
- **Open Problem:** Show Klee's Measure Problem can be done with space and update-time complexity  $\tilde{O}(\text{poly}(d, \log |\Delta|))$ .

## Special Case of Union Estimation: Distinct Elements Problem

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**Naive Solution** Maintain a large hash table.

Worst-case space complexity of  $\mathcal{O}(n)$

**Objective** Optimize space and update time complexity

**Update Time:** Time to process each element of the stream

## Rich History of work

- Flajolet and Martin (1985), Alon, Matias, and Szegedy (1996), Bar-Yossef, Jayram, Kumar, Sivakumar and Trevisan (2001), ..., Kane, Nelson, and Woodruff (2010), ..., Błasiok (2019), ...

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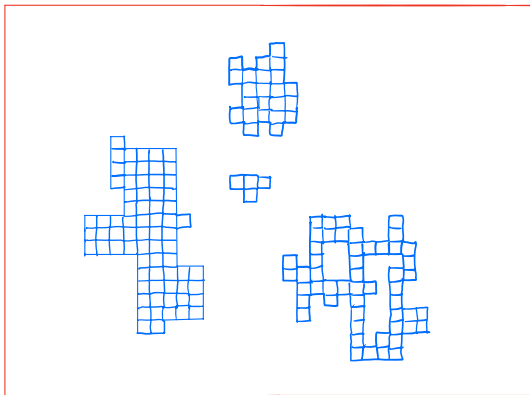
### Theorem (C-Vinodchandran-Meel (ESA'22))

*A simple algorithm with time and space complexity of  $O(\frac{1}{\epsilon^2} \cdot \log n \cdot (\log m + \log 1/\delta))$ .*

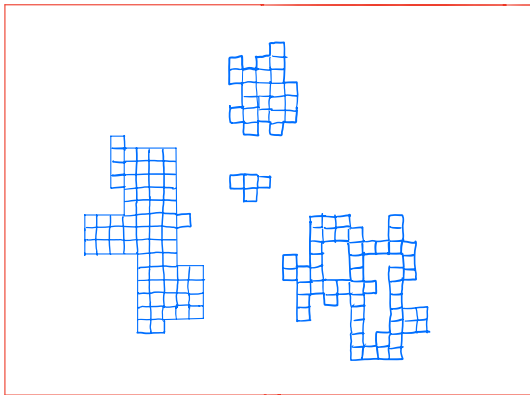
**Remark:** The description and algorithm requires only basic data structures and knowledge of elementary probability theory (Chernoff Bound), and can be easily taught in an undergraduate course, and the algorithm is practically efficient.

**The paper is just five pages (including abstract and bibliographical remarks)**  
**Knuth** (May 23): “ Ever since I saw it, a few days ago, I've been unable to resist trying to explain the ideas to just about everybody I meet.”

## How to estimate the volume of an object?

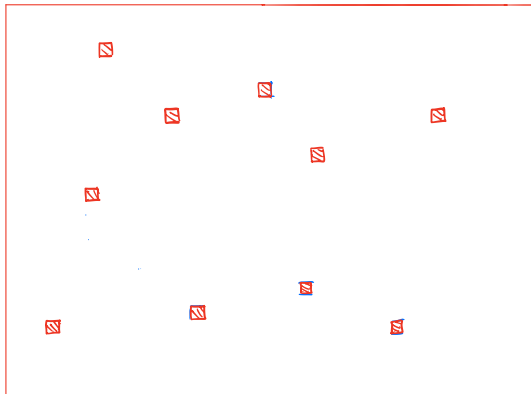


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- Pick random points from the universe and measure the fraction of points falling inside the region.

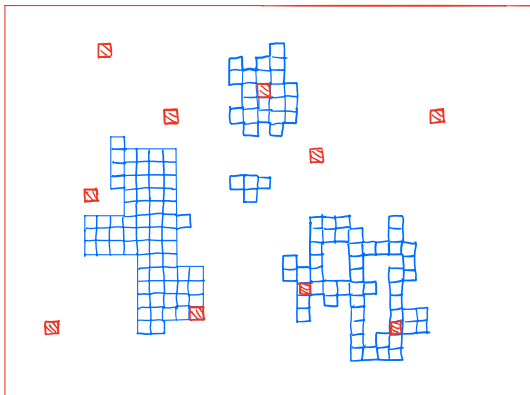
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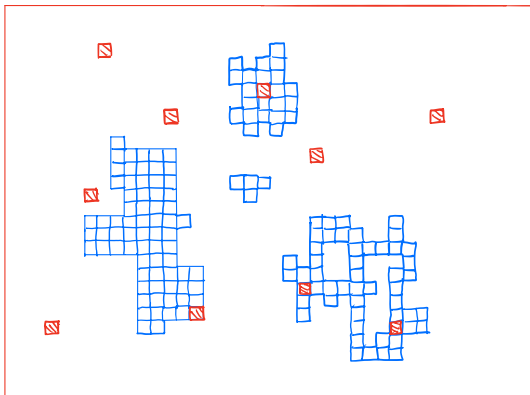


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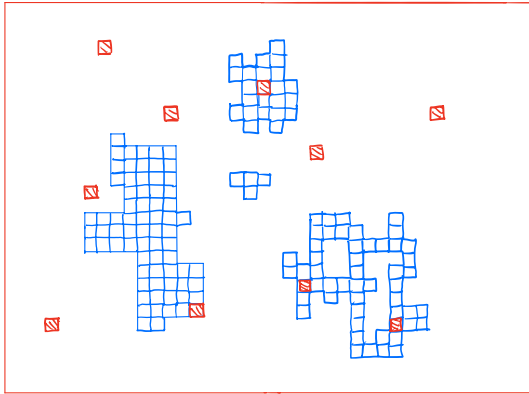
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- **CATCH**: Works when the size of region is large compared to universe.

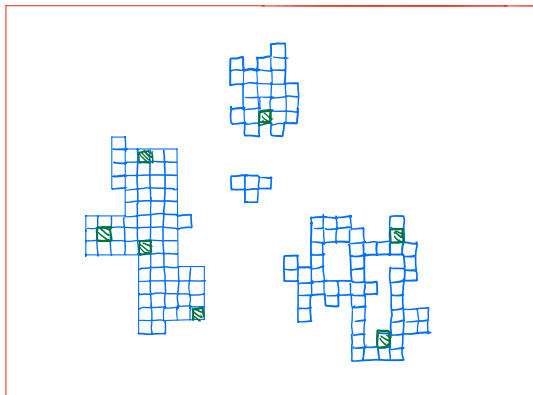
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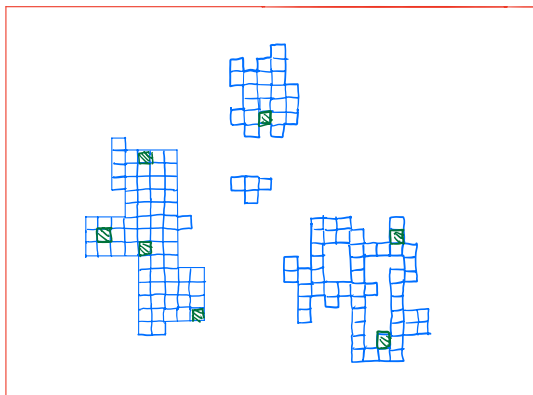
**NOT GOOD** for our purpose.

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- Pick every element in the region independently with probability  $p$ .

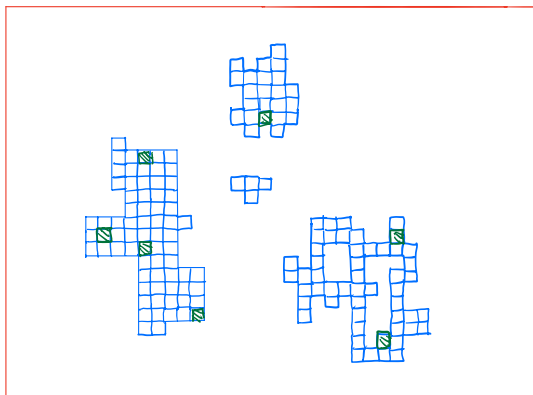
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The expected number of elements picked =  $p \times (\text{size of the region})$ .  
So the estimate can be =  $(\text{number of elements picked}) \times \frac{1}{p}$

The estimation is good if  $p \geq \frac{1}{\epsilon^2(\text{size of the region})}$

### Theorem (C-Vinodchandran-Meel (ESA'22))

*A simple algorithm with time and space complexity of  $O(\frac{1}{\epsilon^2} \cdot \log n \cdot (\log m + \log 1/\delta))$ .*

**Core Idea** If we pick every ball in a bucket with probability  $p$  in our bucket and we end up  $k$  balls in the bucket, then  $\frac{k}{p}$  is a good estimate of the number of balls in the bucket.

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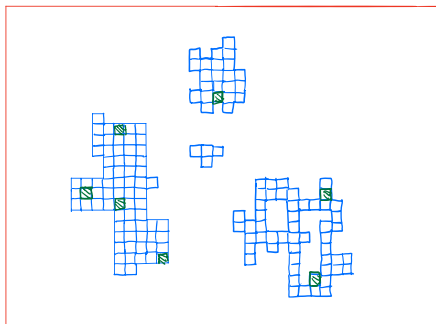
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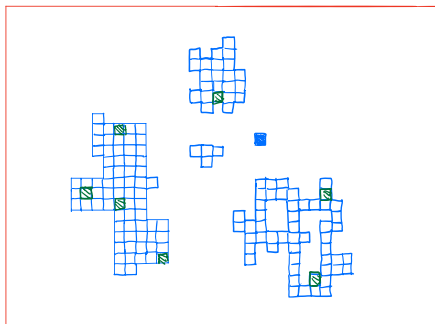
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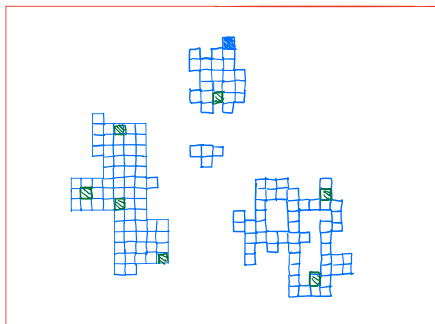
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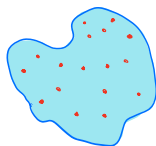
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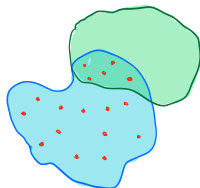
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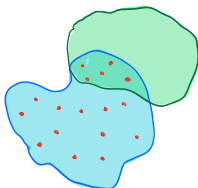
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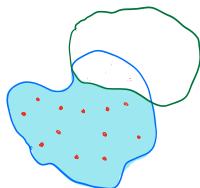
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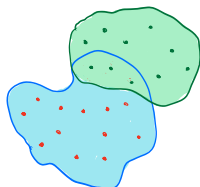
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### Algorithm Sampler

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**Input** Stream  $\mathcal{D} = \langle a_1, a_2, \dots, a_m \rangle$ ,  $p$

- 1: **Initialize**  $\mathcal{B} \leftarrow \emptyset$ ;
  - 2: **for**  $i = 1$  to  $m$  **do**
  - 3:      $\mathcal{B} \leftarrow \mathcal{B} \setminus \{a_i\}$
  - 4:     With probability  $p$ ,  $\mathcal{B} \leftarrow \mathcal{B} \cup \{a_i\}$
- 

**Observation** Whether an element  $x \in \mathcal{B}$  or not only depends on whether  $x$  was picked when it appeared last time

## Key Ingredients - II

**Idea 1** Sample every element of  $\bigcup_{i=1}^m \{a_i\}$  independently with prob.  $p$

**Idea 2** Determine *just the right* value of  $p$ ?

- Too large  $p$ ,  $|\mathcal{B}|$  is too large
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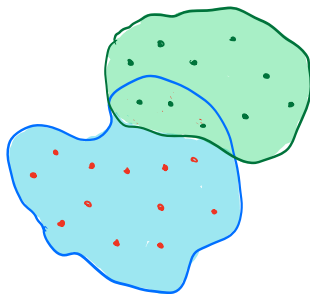
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**Currently:** Every element is picked independently with probability  $p$ .





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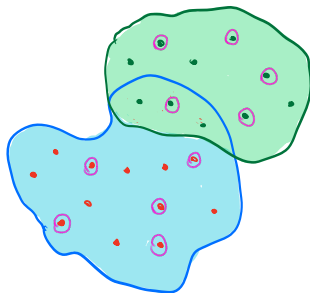
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For each sampled point pick it with probability  $\frac{1}{2}$ .



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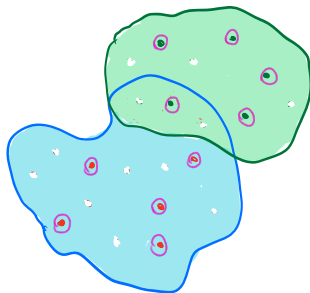
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### Algorithm Adaptive Estimator

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**Input** Stream  $\mathcal{D} = \langle a_1, a_2, \dots, a_m \rangle$ ,  $\epsilon$ ,  $\delta$

- 1: **Initialize**  $\mathcal{B} \leftarrow \emptyset$ ; thresh  $\leftarrow \frac{12}{\epsilon^2} \log(\frac{8m}{\delta})$ ;  $p \leftarrow 1$
  - 2: **for**  $i = 1$  to  $m$  **do**
  - 3:      $\mathcal{B} \leftarrow \mathcal{B} \setminus \{a_i\}$
  - 4:     With probability  $p$ ,  $\mathcal{B} \leftarrow \mathcal{B} \cup \{a_i\}$
  - 5:     **if**  $|\mathcal{B}| = \text{thresh}$  **then**
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**Claim 3**  $\Pr[\text{Bad} = \bigcup_i \text{Bad}_i] \leq \frac{\delta}{4}$

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**Lemma 1**  $\Pr[\text{Error}] \leq \frac{\delta}{2}$

Well, here we are

*Distinct Elements in Streams: An Algorithm for the (Text) Book, ESA 2022*

---

**Algorithm** Distinct-element-estimator

---

**Input** Stream  $\mathcal{D} = \langle a_1, a_2, \dots, a_m \rangle, \varepsilon, \delta$

- 1: **Initialize**  $p \leftarrow 1$ ;  $\mathcal{B} \leftarrow \emptyset$ ; thresh  $\leftarrow \frac{12}{\varepsilon^2} \log\left(\frac{8m}{\delta}\right)$
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---

**Theorem (C-Vinodchandran-Meel (ESA'22))**

A simple algorithm with time and space complexity of  $O\left(\frac{1}{\varepsilon^2} \cdot \log n \cdot (\log m + \log 1/\delta)\right)$ .

## What is so nice about the algorithm?

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- It is simple and can be followed by students with only a knowledge of Chernoff bounds.
- The algorithm is a **sampling-based** algorithm.
  - This makes the algorithm much faster in implementation compared to hashing-based algorithms.
  - It can be extended to the Union of Sets Estimation Problem.

## Beyond the Singleton Setting: Delphic Sets (*know thyself*)

- The algorithm naturally extends to setting where every element  $a_i$  is replaced by  $S_i \subseteq [n]$  belonging to **Delphic family of sets** and we are interested in computing  $|\cup S_i|$

**Cardinality** : Know the size of  $S_i$

**Sample** : Sample uniformly at random elements from  $S_i$

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### Importance of Delphic Sets in Practice

- Estimation of the number of solutions of a DNF Formula
- Klee's Measure Problem: Volume of  $d$ -dimensional rectangles
- Test Coverage Estimation Problem

## Union Size Estimation

Given a stream of sets  $S_1, \dots, S_m$ , all  $S_i \subseteq \Omega$  and two parameters  $\epsilon, \delta$

Output an estimate  $\mathcal{E}$  such that with probability  $\geq (1 - \delta)$

$$(1 - \epsilon) \left| \bigcup_{i=1}^m S_i \right| \leq \mathcal{E} \leq (1 + \epsilon) \left| \bigcup_{i=1}^m S_i \right|$$

- Representation Size of each set:  $O(\log |\Omega|)$
- Actions supported in  $O(\log |\Omega|)$  space and time:
  - Know the size of  $S_i$ ,
  - Sample uniformly at random elements from  $S_i$ ,
  - For an element  $x \in \Omega$ , check if  $x \in S_i$

## Our Main Theorem (PODS 21)

### Theorem

For any stream of **DELPHIC** sets  $S_1, \dots, S_m$  and any parameter  $\varepsilon$  and  $\delta$ , there is a **very simple** algorithm that  $(\varepsilon, \delta)$ -estimates  $|\bigcup_{i=1}^m S_i|$  with

- **Update-time complexity** :  $\tilde{O}(\log^2(m/\delta) \cdot \varepsilon^{-2} \cdot \log |\Omega|)$
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- *Space complexity* :  $O(\log(m/\delta) \cdot \varepsilon^{-2} \log |\Omega|)$ .

**Note:** If one is only interested in *space complexity* and not on *update-time complexity*, simple  $F_0$  estimation by Kane, Nelson and Woodruff (2010) give  $O(\frac{1}{\varepsilon^2} + \log |\Omega|)$  bound and this is also lower bound for space complexity.

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**Except one more trick:** How do you do even handle the first set?

*How to sample each element of the set  $S_1$  independently with probability  $p$ ?*

## Same Algorithm (nearly) works

---

### Algorithm Delphic-Union

---

- 1: Initialize  $\mathcal{B} \leftarrow \emptyset; p \leftarrow 1$
  - 2: thresh  $\leftarrow 3 \cdot \left( \frac{\log(2m/\delta)}{\epsilon^2} \right)$
  - 3: **for**  $i = 1$  to  $m$  **do**
  - 4:     **for** all  $s \in \mathcal{B}$  **do**
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**Challenge** For each element of  $S_i$ : with probability  $p$  add it to  $\mathcal{B}$ .

## Same Algorithm (nearly) works

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### Algorithm Delphic-Union

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- 1: Initialize  $\mathcal{B} \leftarrow \emptyset; p \leftarrow 1$
  - 2: thresh  $\leftarrow 3 \cdot \left( \frac{\log(2m/\delta)}{\epsilon^2} \right)$
  - 3: **for**  $i = 1$  to  $m$  **do**
  - 4:     **for** all  $s \in \mathcal{B}$  **do**
  - 5:         **if**  $s \in S_i$  **then** remove  $s$  from  $\mathcal{B}$
  - 6:     For each element of  $S_i$ : with probability  $p$  add it to  $\mathcal{B}$ .
  - 7:     **while**  $|\mathcal{B}| \geq \text{thresh}$  **do**
  - 8:         Update  $p = p/2$
  - 9:         Throw away each element of  $\mathcal{B}$  with probability  $1/2$
  - 10: Output  $\frac{|\mathcal{B}|}{p}$
- 

**Challenge** For each element of  $S_i$ : with probability  $p$  add it to  $\mathcal{B}$ .

- $N_i \leftarrow \text{Bin}(|S_i|, p)$
- Draw  $N_i$  distinct elements from  $S_i$  by drawing  $N_i \log N_i \log\left(\frac{2m}{\delta}\right)$  samples

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**One Last thing:** What if  $N_i$  is too large? (Update time complexity)

- Well, just update  $p$  to  $p/2$  and resample  $N_i \leftarrow \text{Bin}(N_i, 1/2)$  until  $N_i < \text{thresh}$



## Union Estimation for DELPHIC sets

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### Algorithm Final Algorithm

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- 1: Initialize  $\mathcal{B} \leftarrow \emptyset$ ;  $p \leftarrow 1$ ; thresh  $\leftarrow 3 \cdot \left(\frac{\log(2m/\delta)}{\epsilon^2}\right)$
  - 2: **for**  $i = 1$  to  $m$  **do**
  - 3:     **for** all  $s \in \mathcal{B}$  **do**
  - 4:         **if**  $s \in S_i$  **then** remove  $s$  from  $\mathcal{B}$
  - 5:      $N_i \leftarrow \text{Bin}(|S_i|, p)$
  - 6:     **while**  $|\mathcal{B}| + N_i \geq \text{thresh}$  **do**
  - 7:          $N_i \leftarrow \text{Bin}(N_i, 1/2)$  and  $p \leftarrow p/2$
  - 8:         Throw away each element of  $\mathcal{B}$  with probability  $1/2$
  - 9:     Pick  $N_i$  distinct elements of  $S_i$  randomly and add them to  $\mathcal{B}$ .
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### Theorem

For any stream of **DELPHIC** sets  $S_1, \dots, S_m$  and any parameter  $\varepsilon$  and  $\delta$ , there is a **very simple** algorithm that  $(\varepsilon, \delta)$ -estimates  $|\bigcup_{i=1}^m S_i|$  with

- **Update-time complexity** :  $\tilde{O}(\log(m/\delta) \cdot \varepsilon^{-2} \cdot \log(m/\delta) \cdot \log |\Omega|)$
- **Space complexity** :  $O(\log(m/\delta) \cdot \varepsilon^{-2} \log |\Omega|)$ .

## Some implications of our result

### Theorem

There is a *very simple* algorithm that takes in input a stream of *Delphic* sets  $S_1, \dots, S_m$ , parameters  $\varepsilon$  and  $\delta$ , and provides  $(\varepsilon, \delta)$ -estimate of  $|\bigcup_{i=1}^m S_i|$

- *Update-time complexity* :  $\tilde{O}(\log^2(m/\delta) \cdot \varepsilon^{-2} \cdot \log n)$
- *Space complexity* :  $O(\log(m/\delta) \cdot \varepsilon^{-2} \cdot \log n)$ .

- **Klee's Measure Problem** Estimate union of axis-parallel rectangles in  $\mathbb{R}^d$ .  
Our algorithm gives the first efficient algorithm with linear dependence on the dimension  $d$  — a long standing open problem. (PODS-21, PODS-22)
- **Model Counting for DNF** Count the number of DNF solutions.  
Our algorithm (nearly) matches the optimal bounds (in non-streaming setting!) The practical implementation (after engineering improvements) achieves nearly 100× speed up over prior state of the art. (IJCAI-23)
- **Coverage Estimation Problem** Critical for software testing: estimate amount of coverage achieved with certain set of “test vectors”.  
We out-perform all currently used techniques in practice. (ICSE-22)

## Wrapping up ...

**Conclusion** A simple algorithm for element distinctness that is sampling based.

The algorithm generalizes to obtain estimates of union of DELPHIC sets.

The algorithm solves the Klee's Measure problem.

The algorithm can be used even in non-streaming set-up to design practically efficient algorithms.

**Further Work** (PODS 22, APPROX 24) Algorithm for Delphic sets without dependence on stream size ( $m$ ). We have the update-time and space complexity of  $\tilde{O}(\log^2(|\Omega|/\delta) \cdot \epsilon^{-2})$ .

Donald E. Knuth modified the algorithm to obtain a unbiased  $F_0$  estimator for the Distinct Element problem.

**Open Problem** Optimal algorithm for Delphic sets?

These slides are available at [tinyurl.com/streaming-talk](https://tinyurl.com/streaming-talk)

Knuth's Note: <https://cs.stanford.edu/~knuth/papers/cvm-note.pdf>