

# PRIORITY QUEUE AND APPLICATIONS



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# Overview of Algorithm Design

## 1. Initial Solution

- Recursive Definition – A set of Solutions
- Inductive Proof of Correctness
- Analysis Using Recurrence Relations

## 2. Exploration of Possibilities

- Decomposition or Unfolding of the Recursion Tree
- Examination of Structures formed
- Re-composition Properties

## 3. Choice of Solution & Complexity Analysis

- Balancing the Split, Choosing Paths
- Identical Sub-problems

## 4. Data Structures & Complexity Analysis

- Remembering Past Computation for Future
- Space Complexity

## 5. Final Algorithm & Complexity Analysis

- Traversal of the Recursion Tree
- Pruning

## 6. Implementation

- Available Memory, Time, Quality of Solution, etc

## 1. Core Methods

- Divide and Conquer
- Greedy Algorithms
- Dynamic Programming
- Branch-and-Bound
- Analysis using Recurrences
- Advanced Data Structuring

Stacks  
Queues  
Lists  
Arrays

Heap,  
BST

## 2. Important Problems to be addressed

- Sorting and Searching
- Strings and Patterns
- Trees and Graphs
- Combinatorial Optimization

Priority Queue

## 3. Complexity & Advanced Topics

- Time and Space Complexity
- Lower Bounds
- Polynomial Time, NP-Hard
- Parallelizability, Randomization

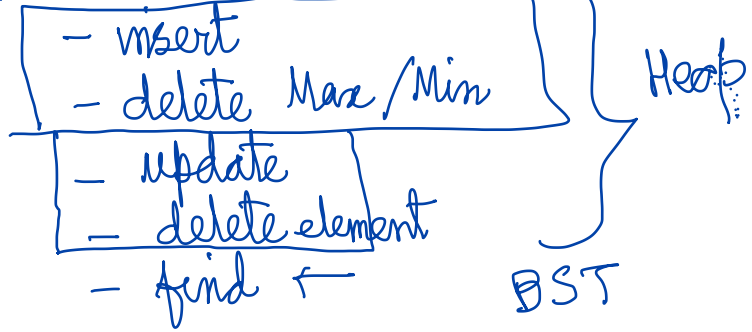
# Priority Queue: Operations & Applications

Queue: FIFO

↳ Elements have key values which could have an ordering

- Sorting, searching, optimization problems, max-min, max-next max
- Pole Wiring Problem
- Coins
- Activity Selection

operations



static :-

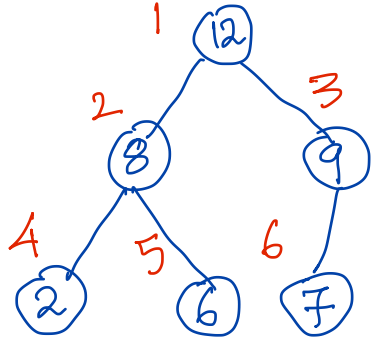
dynamic :-

# Priority Queue: Heap Implementation

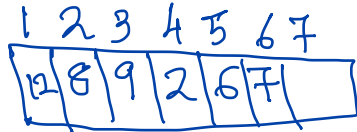
Build Heap  
 Insert-new element  
 Remove Min / Max

update element  
 delete element

→ provided we have pointer or index of node



1. Complete Binary Tree
2. Heap property



insert-new

- ↳ inserts at the end
- update-up (A, node)
- $O(\log n)$

remove-max

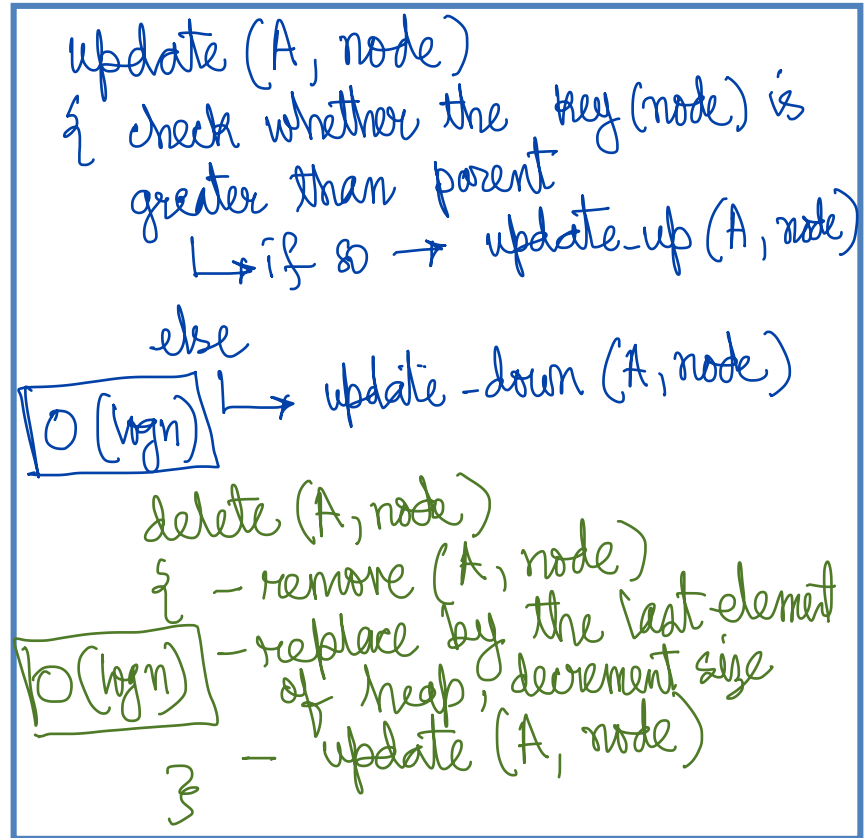
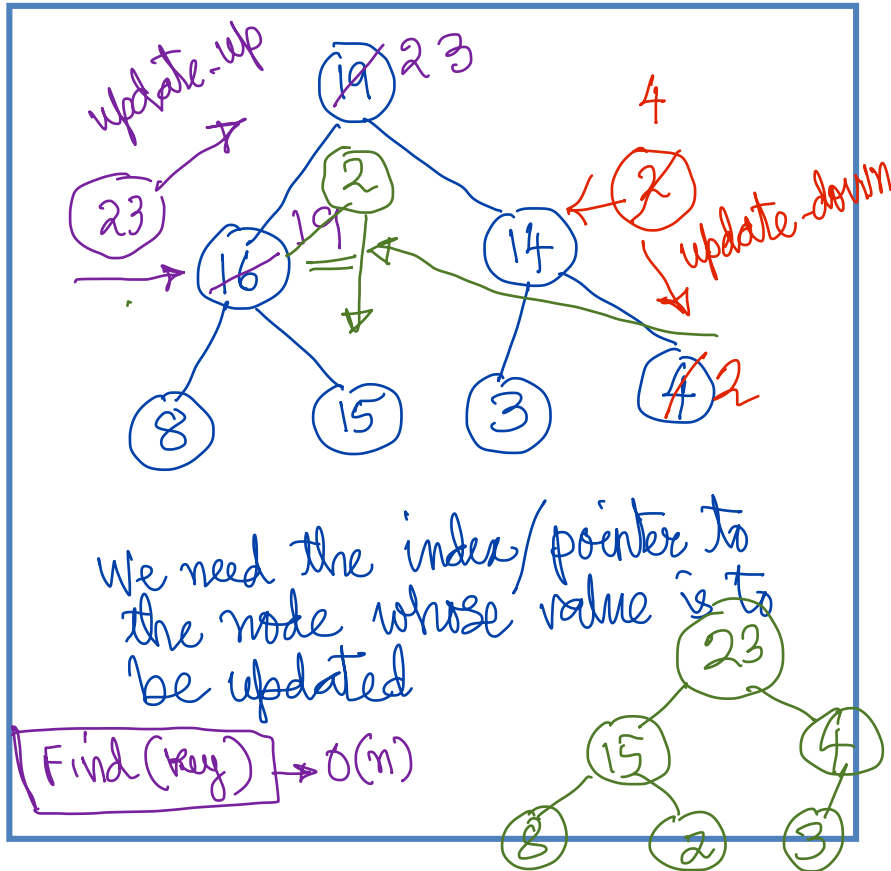
- ↳ remove to root or first element
- replace root by last element
  - update-down (A, node)
- $O(\log n)$

Build-heap  
 bottom up

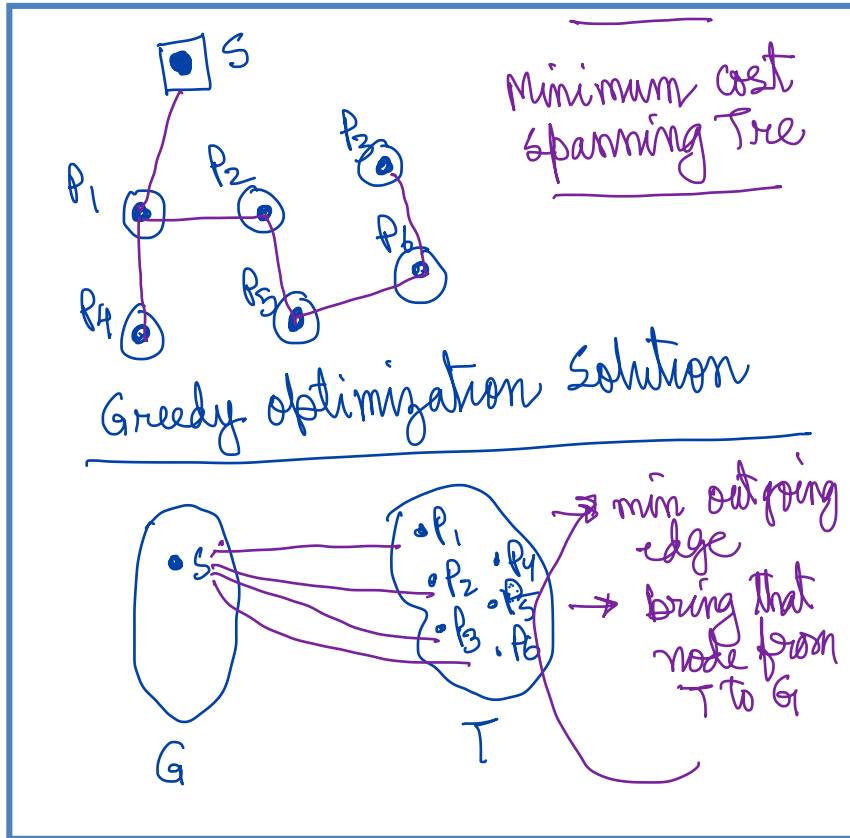
Heapify  
 update-down iteratively

$O(n)$

# Heap Priority Queue: Update / Revise / Delete



# Electrical Pole Placement Problem



what data structure to use?

operations: - **PRIORITY QUEUE**

R: Set of edges between G & T

- insert - new
  - delete
  - remove - min
- } → Edges (e)  
} → Nodes (n)

each operation will be of  $O(e)$

$$O(n \log e + e \log e)$$

$$= O(e \log e) \quad e = O(n^2)$$

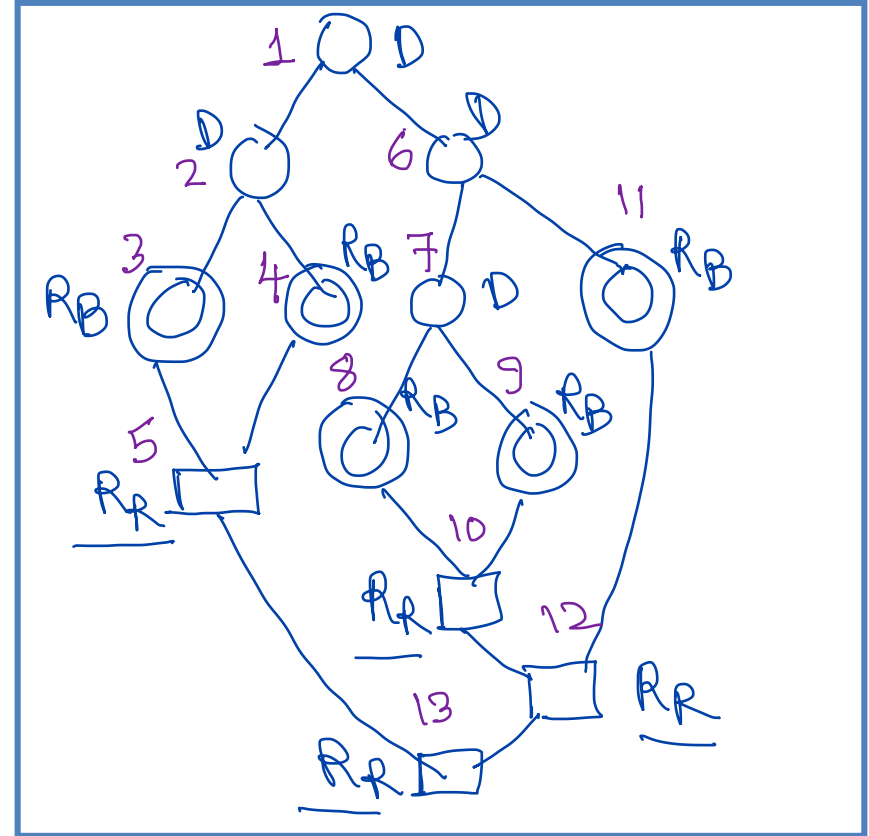
$$= O(n^2 \log n)$$

# Evaluation of Recursion Tree

$$\begin{aligned} f(x) &= R_B(x) \text{ if } B(x) \\ &= \{ 1. (Y_1, Y_2, \dots, Y_k) = D(x) \\ &\quad 2. R_R(f(Y_1), f(Y_2), \dots \\ &\quad \quad \dots, f(Y_k)) \} \end{aligned}$$

Evaluation of the Recursion Tree

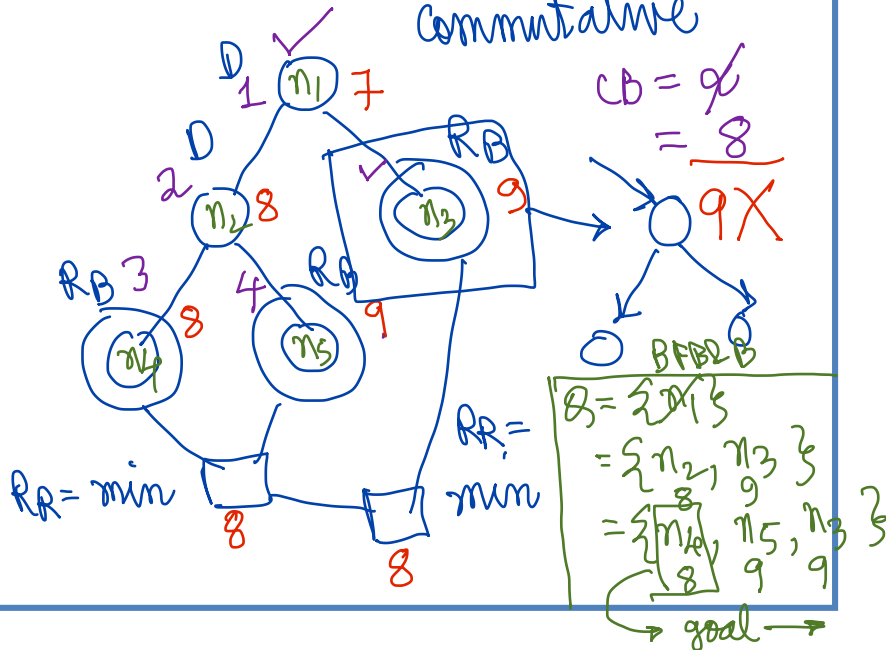
- Depth-first  $\rightarrow$  Stack
- Breadth-first  $\rightarrow$  Queue
- Iterative Deeping



# Pruning & Branch & Bound

Optimization problems : min/max

$R_R \rightarrow \min/\max$   
 $\hookrightarrow$  associative & commutative



pruning

DFB&B : — Maintain a current Best (initialized to  $\infty$ )

- whenever we find a solution we update current best to the better solution
- Any node which has got cost  $\geq$  current best is pruned

Best first B&B

- ordered search using a priority queue of costs
- Remove-Min, insert-children, stop when goal is reached



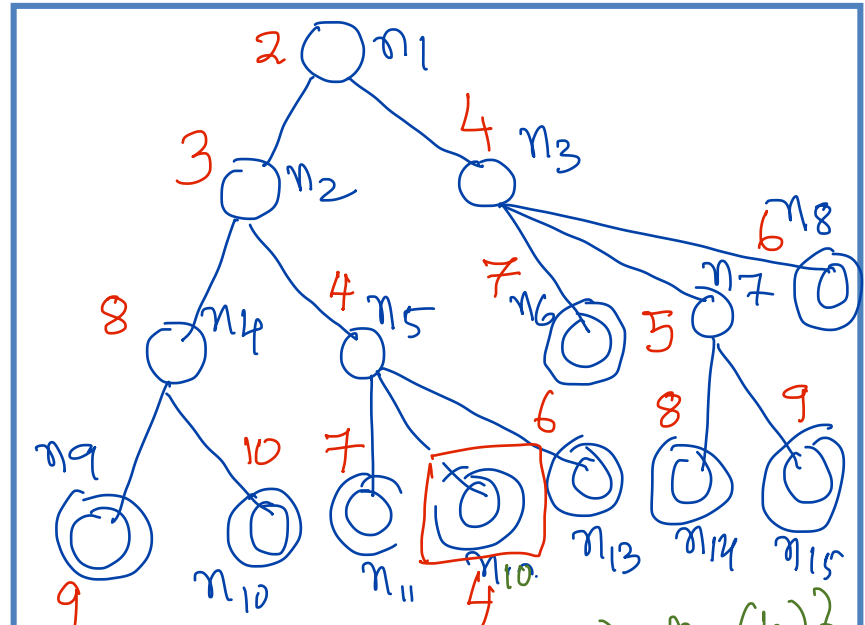
# Best First Search using Priority Queues

## MINIMIZATION

1. Initialize:  $Q = \{ \text{start} \}$
2. Remove from  $Q$  to node  $n$  with lowest cost. If  $Q$  is empty  $\rightarrow$  fail
3. If  $n$  is goal  $\rightarrow$  stop with solution
4. Generate successors of node  $n$  using the decomposition rule. Let them be  $n_1, n_2, \dots, n_k$
5. If  $n_i \notin Q$  insert  $n_i$  in  $Q$
6. If  $n_i \in Q$  update  $n_i$  in  $Q$
7. Goto step 2.

$Q \leftarrow$  Priority Queue

1. Insert
2. Delete Min
3. Update



$Q = \{ n_1(2) \} \rightarrow \{ n_2(3), n_3(4) \}$   
 $\{ n_4(8), n_5(4) \} \leftarrow \{ n_3(4), n_4(8), n_5(4) \}$   
 $\{ n_6(7), n_7(5), n_8(6) \} \rightarrow \{ \dots, n_{10}(4) \dots \}$

SOLUTION



# Related Data Structures

- Binary Search Trees (BSTs)
  - ↳ Balanced BSTs
    - ↳ AVL Trees
    - B-Trees, etc
- Advanced Heaps
  - ↳ Binomial Heaps
  - Fibonacci Heaps
  - etc

- Weighted BSTs
  - ↳ frequency of access  
(DYNAMIC PROGRAMMING METHOD)
- Data Structures Using Advanced operations
  - Union, Intersection, Set Difference, etc.

# Summary

- insert
- remove - min / max
- update / delete

↳ Priority Queue operations

↳ Implemented by a Heap  
Data Structure

In case we have  
Find ← BST

Union / Intersection, etc ← ??

operations could be  
- provided before the algo.  
(static)

- online

Large class of optimization  
problems → Greedy, B&B

**Thank you**

**Any Questions?**