

ALGORITHM DESIGN USING **DIVIDE & CONQUER** METHOD: I



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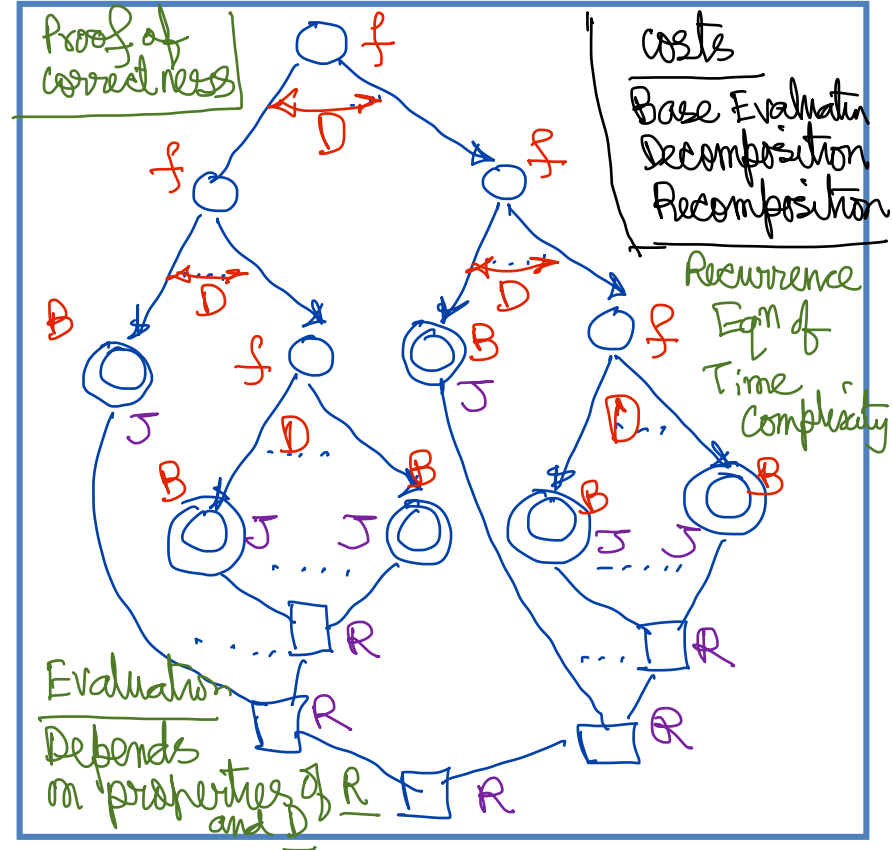
Algorithm Design by Recursion Transformation

- ❑ Algorithms and Programs
- ❑ Pseudo-Code
- ❑ Algorithms + Data Structures = Programs
- ❑ Initial Solutions + Analysis + Solution Refinement + Data Structures = Final Algorithm
- ❑ Use of Recursive Definitions as Initial Solutions
- ❑ Recurrence Equations for Proofs and Analysis
- ❑ Solution Refinement through Recursion Transformation and Traversal
- ❑ Data Structures for saving past computation for future use

1. Initial Solution ✓
 - a. Recursive Definition – A set of Solutions
 - b. Inductive Proof of Correctness
 - c. Analysis Using Recurrence Relations
2. Exploration of Possibilities
 - a. Decomposition or Unfolding of the Recursion Tree
 - b. Examination of Structures formed
 - c. Re-composition Properties
3. Choice of Solution & Complexity Analysis
 - a. Balancing the Split, Choosing Paths *Divide & Conquer*
 - b. Identical Sub-problems
4. Data Structures & Complexity Analysis
 - a. Remembering Past Computation for Future
 - b. Space Complexity
5. Final Algorithm & Complexity Analysis
 - a. Traversal of the Recursion Tree
 - b. Pruning
6. Implementation
 - a. Available Memory, Time, Quality of Solution, etc

Structure of Recursive Definition

- $f(x)$
1. Base Condition $B(x)$
if $B(x)$ return $(J(x))$
 2. Decomposition $D(x)$
 $\langle x_1, x_2, \dots, x_k \rangle = D(x)$
 3. Recursive Call
for each i , $y_i = f(x_i)$
 4. Recomposition $R(y)$
 $J = R(y_1, y_2, \dots, y_k)$
 5. Returning the Result
return (J)



Examples

Max(L)

B: $|L|=1$

D: split of L

R: maximum of two elements

Costs:

B: $O(1)$

D: depends of how we store L
and where we decide to
split $O(1)$

R: $O(1)$

↳ associative & commutative

Fib

B: $n=0, n=1$

D: $n-1, n-2$

R: +

Coins

B: $\{ \}$ NULL and $|L|=0$ or 1

D: Move one element at a time
from list T to S

R: minimum

alternative

D': inclusion/exclusion method

Basics of Divide & Conquer Method

1. Mechanism of Decomposition and the CHOICE POINTS

$$T(n) = T(n_1) + T(n_2) + \dots + T(n_k) \\ + \text{decomposition } (n) \\ + \text{recomposition } (R)$$

various alternatives of

D and R properties of D and R

→ choice points: how to optimally split the problem

2. Evaluation

3. Dynamic Programming

↳ solving identical subproblems once and memorizing the past solutions

4. Data Structuring

Organizing data of past computation for future use

5. Branch & Bound

Pruning of unnecessary paths in the computation of the recursion tree

Basics of Divide & Conquer Method

CHOICE OF D (Decomposition)
and R (Recomposition)

→ Time Complexity

↳ optimize this time complexity

Analysis

1. By analysis of the recurrence eqn formed

2. By Analysis of the Recursion Tree and costs (computation) incurred during D and R

→ split of D
(max, max-min, max-2nd max)
(coins)

3. what structures are formed which enable us to develop alternative insights for an iterative solution to the recursive defⁿ

Sorting & Searching Problems

Searching

1. Unordered set or list
2. Ordered list or sequence
3. A combination
4. Static / Dynamic

Sorting

1. Ascending or Descending Order
2. In-Memory Sorting
3. Secondary Storage Sorting

Searching an Unordered List

Search-U(L, x)

Let $L = \{s_1, s_2, \dots, s_n\}$

if ($|L| = 0$) return (false)

if ($|L| = 1$)
if ($s_1 = x$) return (true)
else return (false)

split L into non-empty L_1, L_2

if (Search-U(L_1, x))
return (true)

else return (Search-U(L_2, x))

$$1. T(n) = T(k) + T(n-k) + O(1)$$

$$= O(n)$$

choice: Any split is equal in complexity

choose $\underline{1}, \underline{n-1}$

solution:

An iterative loop

for $i = 1$ to n do

if ($x = s_i$) return (true)

return (false)

Searching an Unordered List: Finalization

Finalization

1. choice
2. check whether this is optimal

↳ unless every element is checked in the WORST CASE we may not find the correct answer by any algo.

VARIANT

1. SearchAll(L, S) ✓✓

/where we have

$$L = \{l_1, l_2, \dots, l_n\}$$

$$S = \{s_1, s_2, \dots, s_m\}$$

Both unordered
and we have to return
the elements of S that are
in L.

$$\{L \cap S\}$$

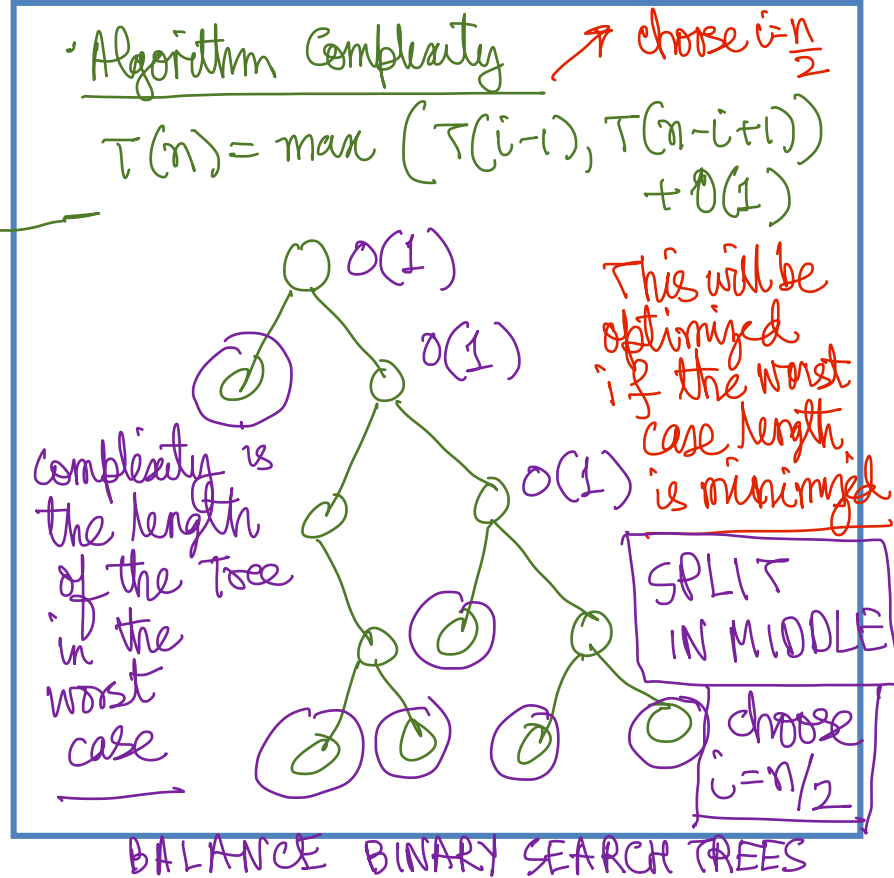
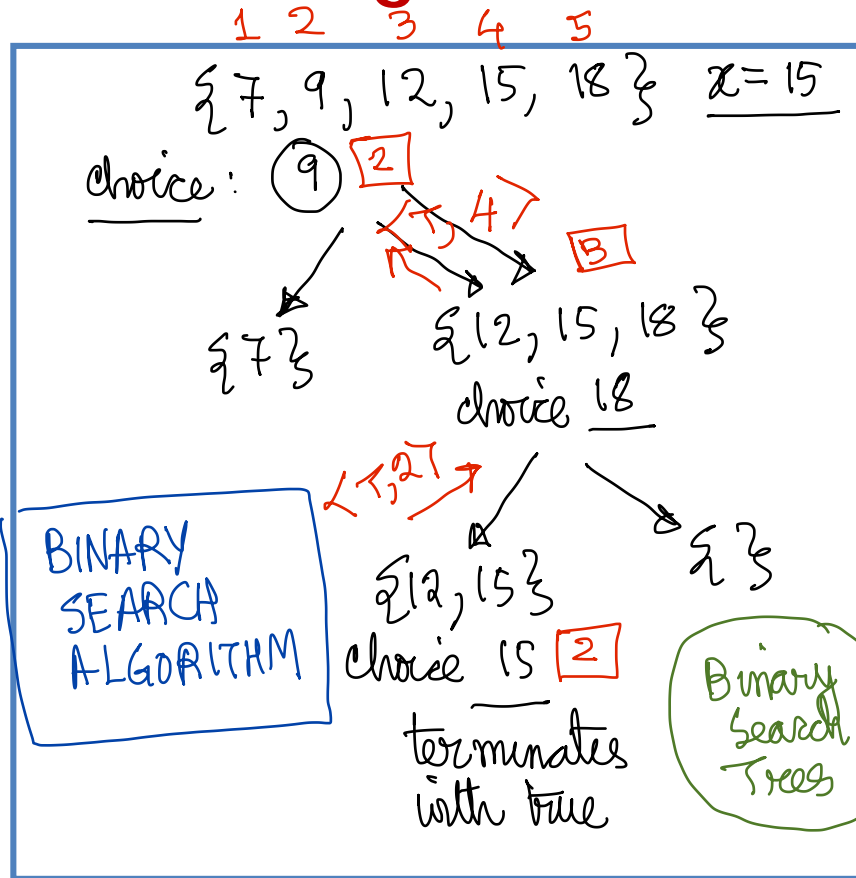
→ how do we solve this problem

Searching Ordered Lists

$\text{search}_0(L, x)$
 $\{ L = \{s_1, s_2, \dots, s_n\}$
 $\quad [s_i \leq s_j \text{ for } j > i]$
B: $\text{if } |L| = 0 \text{ return } (\text{false}, \infty)$
D: choose (s_i)
 $\text{if } (s_i = x) \text{ return } (\text{true}, i)$
 else
 $\text{if } (s_i < x)$
 $\quad \{ L' = \{s_{i+1}, \dots, s_n\}$
 $\quad \langle y, z \rangle = \text{search}_0(L', x)$
 $\quad \text{if } (y) \text{ return } (\text{true}, z+i)$
 $\quad \text{else return } (\text{false}, \infty)$
 $\quad \}$
 $\text{else } \{ L' = \{s_1, \dots, s_i\}$

$\langle y, z \rangle = \text{search}_0(L', x)$
 $\text{if } (y) \text{ return } (\text{true}, z)$
 $\text{else return } (\text{false}, \infty)$
 $\}$
 $\}$
D: choice of i
R: OR \rightarrow compute only in one direction
 $T(n) = \max \{ T(i-1), T(n-i+1) \} + O(1)$

Searching Ordered Lists: Data Structure View



Problem Variations and Approaches

$$T(n) = T(n/2) + O(1)$$
$$= O(\log n) \quad \checkmark$$

which is the height of the
Balanced Recursion Tree in
the worst case

Other options

$$T(n) = \max \left\{ T\left(\frac{1}{2}n\right), T\left(\frac{2}{3}n\right) \right\} + O(1)$$
$$= T\left(\frac{2}{3}n\right) + O(1)$$
$$= O(\log n)$$

$T(n) \rightarrow$ into 3 parts and
done 2 comparisons

$$T(n) = T\left(\frac{n}{3}\right) + 2 \rightarrow$$

$$T(n) = T\left(\frac{n}{2}\right) + 1$$

VARIATIONS

1. Search-0 (L, S)

2. Dynamic Search

\rightarrow interleaved queries
(insert, find) into L (insert, delete, find)
in L

ordered
 \rightarrow order or unordered

Overview of Algorithm Design

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- b. Inductive Proof of Correctness
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1. Core Methods

- a. Divide and Conquer
- b. Greedy Algorithms
- c. Dynamic Programming
- d. Branch-and-Bound
- e. Analysis using Recurrences
- f. Advanced Data Structuring

2. Important Problems to be addressed

- a. Sorting and Searching
- b. Strings and Patterns
- c. Trees and Graphs
- d. Combinatorial Optimization

3. Complexity & Advanced Topics

- a. Time and Space Complexity
- b. Lower Bounds
- c. Polynomial Time, NP-Hard
- d. Parallelizability, Randomization

Thank you

Any Questions?