

Introduction

We start with different constructs of the grammar given in the laboratory assignment and discuss semantic actions and intermediate code generation. First we consider simple variable declaration.

 $\mathbf{2}$



Synthesized Attributes

- The variable VL may have a synthesized attribute locLst, a list of indices of the symbol table where names are inserted.
- Type and other information of these names will be updated afterward^a.
- The non-terminal TY saves the type name in its synthesized attribute TY.type.

^aThere is an alternate mechanism available if we can access the stack below the handle.



- In our simple case it is int or float.
- But it can be multi-dimensional array of any base type e.g. int a[3][4][5] - 3-element array of 4-element array of 5-element array of integers. In fact there may be upper and lower bounds of array indices for every dimension.



- In case of a defined type like structure or disjoint sum there is a list of fields and the type of each one of them may be built-in or defined.
- A defined type name can be saved with all its field information and sizes.
- A variable of a defined type may have a link to the corresponding type entry.

Note

- In case of a procedure or function name we need to save the number of parameters and their types. Also the type of the value it returns.
- If the whole type information is available, its size etc. can be calculated and stored.
- In our simple case we need to store the size and the offset of the memory location from a base address.

- searchInsert(symTab, lexme, err): it searches the current symbol table with the second parameter^a.
- In a normal situation there should not be any entry of the lexme. It is inserted in the table and the index is returned.

^aThere may be separate functions for search() and insert().

- If the lexme is found in the table (already inserted), it is an error condition.
- The type of the identifier is still unknown.
- mkLocLst(loc): makes a list of symbol-table location specified by loc and returns the single element list.

- catLocLst(l1,l2): concatenates two lists of symbol-table locations and returns the concatenated list.
- updateType(symTab, l, type): updates type of the symbol-table locations from the list l using type.







- Our next consideration is the expression grammar.
- We shall consider a small portion of it without involving array etc.

Part of Expression Grammar

 $\begin{array}{rcl} \mathrm{E} & \rightarrow & \mathrm{E} + \mathrm{E} \\ & \rightarrow & \mathrm{id} \\ & \rightarrow & \mathrm{ic} \\ & \rightarrow & \mathrm{fc} \end{array}$

Where id is a simple scalar variable, ic is an integer constant and fc is a floating-point constant.

Synthesized Attributes

- An expression E has two attributes, E.loc which is an index to the symbol table, and E.type^a.
- The symbol table entry corresponding to
 E.loc may be a program defined variable or a compiler generated variable.

^aWhich is also available in the symbol table.

- searchInsert(symTab, lexme, err): is as we have already defined.
- But in this case, if the lexme corresponds to a program variable and it is not found in the symbol-table, it is an error. Necessary actions are to be taken^a.

^aWe may insert the name in the symbol table with a type UNDEF or some default type. This will stop generating error message on the same undefined variable.

- The function newTemp() generates a compiler defined variable name. Its type is determined by the type of the expression being evaluated.
- The function getType(symTab, loc) returns the type of the variable at the index loc of the symbol table.













Grammar for Statements

Our next considerations are statements. We start with simple assignment statement.







Control Flow Statements

Our next consideration are the statements that control the flow of execution. Here we use a technique known as backpatching to fill the jump/branch addresses.





• List of these unfilled code indices are passed as synthesized attributes.







- The non-terminal BE has two synthesized attributes trueLst and falseLst.
- BE.trueLst is the list of 3-address codes (indices) corresponding to jumps/branches that will be taken when the expression of BE evaluates to true.

Synthesized Attributes

- Similarly BE.falseLst is the list of code indices from where jump/branches are taken when BE evaluates to false.
- The BE.trueLst will be backpatched by the index of the 3-address code where the control will be transferred when BE evaluates to true.
- Similar is the case for **BE.falseLst**.



semantics actions.

^aIf the sequence of instructions is maintained as a list, then we may have a label in the list or a pointer to the target instruction.

- mkLst(i): makes a single element list with the code index i and returns the pointer of the list.
- $\operatorname{catLst}(l_1, l_2)$: two lists pointed by l_1 and l_2 are concatenated and returned as a list.
Important Functions

- fill(l, i): the unfilled targets of each jump/branch instruction whose indices are in the list l are filled/backpatched by the index i of the target instruction.
- The global variable nextInd has the sequence number(index) of next 3-address code to be generated.



An Alternative

- As an alternative the non-terminal mR has a synthesized attribute label. The reduction of mR generates a new label, attaches it to the next 3-address code and saves it in mR.label.
 - mR $\rightarrow \varepsilon$
 - $\{mR.label = newlabel()\}$

 $\{codeGen(label, mR.label)\}$

Goutam Biswas















Compiler Design



Goutam Biswas



- Let the next index (nextInd) of the 3-address code sequence be 100.
- The 3-address codes corresponding to BE_2 in readable form is

```
100 if x < y goto \cdots
```

- $101 \text{ goto } \cdots$
- BE_2 .trueLst = {100} and BE_2 .falseLst = {101} and nextInd: 102.



- Next 3-address code is due to exp₄.
 102 \$i ← b + c
- Then the code corresponding to BE_6 is 103 if a > \$i goto ... 104 goto ...

Example

- BE_6 .trueLst = {103} and BE_6 .falseLst = {104} and nextInd: 105.
- The not operator flips the lists.
 BE₄.trueLst = {104} and BE₄.falseLst = {103}.
- Next reduction is $mR_2 \rightarrow \varepsilon$. The attribute $mR_2.nextInd \leftarrow nextInd$: 105.







• BE_1 .trueLst = {100, 105} and BE_1 .falseLst = {103, 106}.



Example: Note

It is clear that codes in sequence numbers 101 and 104 are useless. We replace them by no-operations (nop)



Statements and Backpatching

We use backpatching for assignment statement, sequence of statements and flow-of-control statements. So the grammar is modified with marker non-terminals^a

^aOne should be careful about doing that as in some cases the modified grammar may cease to be LALR.



Synthesized Attribute of a Statement

Every statement (S and SL) has a synthesized attribute nextLst. This is the list of indices of jump and branch instructions (unfilled) within the statement that transfer control to the 3-address instruction following the statement.



Lect 12













- Next reduction is $mR_1 \rightarrow \varepsilon$. The attribute $mR_1.nextInd \leftarrow nextInd$: 107.
- The code corresponding to SL₁ is 107 \$(i+1) = 5 * y 108 x = \$(i+1)
- The reduction of $kR_1 \rightarrow \varepsilon$ generates the code 109 goto \cdots Its attribute is kP nextLet = [100]

Its attribute is kR.nextLst = $\{109\}$



Example

```
The sequence of code and synthesized data at
this point of compilation are
100 if x < y goto \cdots
101 nop
102 $i \leftarrow b + c
103 if a > \$i goto \cdots
104 nop
105 if p == q goto \cdots
106 \text{ goto } \cdots
107 \ \text{(i+1)} = 5 * y
108 x = $(i+1)
109 \text{ goto } \cdots
110 $(i+2) = a + p
111 a = $(i+2)
```



- BE.trueLst = $\{100, 105\}$ and BE.falseLst = $\{103, 106\}$.
- $mR_1.nextInd = 107.$
- kR.nextLst = $\{109\}$
- $SL_1.nextLst = SL_2.nextLst = nil$



During the reduction to IS following actions are taken.

- Backpatch BE.trueLst with $mR_1.nextInd$.
- Backpatch BE.falseLst with kR.nextInd.
- if Stmt.nextLst = mkLst(kR.nextLst+1) as $SL_1.nextLst = SL_2.nextLst = nil.$

Example

```
Final sequence of code is
100 if x < y goto 107
101 nop
102 $i \leftarrow b + c
103 if a > $i goto 110
104 nop
105 if p == q goto 107
106 goto 110
107  $(i+1) = 5 * y
108 x = $(i+1)
109 \text{ goto } \cdots
110 $(i+2) = a + p
111 a = $(i+2)
```


exitLoop Statement

- Our exit is similar to break is C language.
- We only consider necessary semantic actions and translation of exit in the context of a while-statement.
- We define an exit-list (extLst=Nil) after entering a while-loop.



the S.nextLst.











- The exit-list can be maintained as a special label (say exit) in the symbol table.
- Nesting of loop will complicate the situation. In that case we use a stack to push exit-list headers of outer loops.



• If a loop creates a local environment, the outer symbol-tables are pushed in a stack. If the exit-list is maintained on a symbol-table, it will automatically be stacked.





- var \rightarrow ID sizeListO
- sizeListO \rightarrow sizeList
 - sizeList \rightarrow sizeList [INT_CONST] \rightarrow [INT_CONST]







- Array int x[3][4][5] may be viewed as follows:
- A 3-element array of 4-element array of 5-element array of base type int.
- Important information are base type, range of each dimension and the total size in bytes.



- In some programming languages the upper and lower bounds of each dimension can be specified.
- More information such as lower bound and upper bound of of indices is necessary to save in such a situation.









• The address of
$$x[i][j][k]$$
 is
 $x_a + (((i \times 5 + j) \times 7) + k) \times w$

Goutam Biswas



Essential information to compute the offset of x[i][j][k] are starting address x_a , values of three indices i, j, k, the sizes of the second and the third dimensions, 5, 7 respectively, and size of the base type.

Offset Computation: an Example

- If the array is stored in column-major order, the address of x[i][j][k] is
 x_a + (((k × 5 + j) × 3) + i) × w. Here the sizes of the first and the second dimensions are useful for offset computation.
- In both the cases we assume that when the range of a dimension [n] is specified, the indices are $0, \dots, n-1$.

Offset Computation: an Example

- In some languages the ranges of indices of different dimensions are given explicitly, e.g. int x[1-3][2-5][3-7], where possible values of first indices are 1,2,3; second indices are 2,3,4,5; and third indices are 3,4,5,6,7.
- In row-major storage the address of x[i][j][k] is $x_a + ((((i-1) \times (5-2+1) + (j-2)) \times (7-3+1)) + (k-3)) \times w$, where x_a is the address of x[1][2][3].



- Let $s_2 = 5 2 + 1$ and $s_3 = 7 3 + 1$ be the sizes of second and third dimensions.
- The expression can be rewritten as $x_a - ((((1 \times s_2 + 2) \times s_3) + 3) \times w) + ((((i \times s_2 + j) \times s_3) + k) \times w).$
- The first two terms are independent of (i, j, k). In a nested loop they can be computed outside it.





Note

- Each expression has an attribute exp.loc, an index of the symbol table corresponding to a variable.
- The symbol-table entry of the array identifier has the sizes of different dimensions. But it is not available during the reduction of [exp] to indexList or indexList [exp] to indexList^a

^aThough it is available immediately below the handle in the stack.



• The non-terminal id may have two attributes, id.base and id.offset.

- Let array deceleration be
 x[r₁] [r₂] ··· [r_k]:int.
- Let the use of an array in an expression is
 x[exp₁][exp₂] ··· [exp_k]
- Let the base address of the array be x_b .
- Let the width of the base type be w.



Note that indexListO.locLst = {exp₁.loc, \cdots , exp_k.loc}. The address computation of the array element and the semantic actions corresponding to the reduction $id \rightarrow ID indexListO$ is as follows: temp1 = searchInsert(symTab, newTemp(), err)updateType(mkLocLst(temp1), ADDR) $codeGen(assign, exp_1.loc, temp1)$ $\$_{i+1} = \exp_1 \log_1$

for i = 1 to k - 1 do

temp2 = searchInsert(symTab, newTemp(), err)
updateType(mkLocLst(temp2), ADDR)

 $codeGen(assAddrMultConst, temp1, r_{i+1}, temp2)$

$$\$_{j+2i} = \$_{j+2i-1} \times \mathbf{r}_{i+1}$$

temp1 = searchInsert(symTab, newTemp(), err) updateType(mkLocLst(temp1), ADDR)

 $codeGen(assAddrAdd, temp2, exp_{i+1}, temp1)$

$$\$_{j+2i+1} = \$_{j+2i} + \exp_{i+1}$$

```
\begin{split} & \text{temp2} = \text{searchInsert(symTab, newTemp(), err)} \\ & \text{updateType(mkLocLst(temp1), ADDR)} \\ & \text{codeGen(assAddrMultConst, temp1, w, temp2)} \\ & \$_{j+2k} = \$_{j+2k-1} \times w \\ & \text{id.base} = \text{searchInsert(symTab,ID.lexme,err).sTab.offset} \\ & \text{id.offset} = \text{temp2} \end{split}
```

The 3-address code corresponding to $\exp \rightarrow id$ is, temp = searchInsert(symTab, newTemp(), err) updateType(mkLocLst(temp1), ADDR) codeGen(assAddrAddConst, id.base, id.offset, temp) $s_{j+2k+1} = s_{j+2k} + x_b$ temp1 = searchInsert(symTab, newTemp(), err) updateType(mkLocLst(temp1), TYPE) codeGen(assignIndirFrm, temp, temp1) $s_{j+2k+2} = *s_{j+2ki+1}$





- The semantic actions up to id are identical.
- The non-terminal dotId will have attributes of id i.e. dotId.base and dotId.offset.
- The value of dotId.base + dotId.offset is computed. The location corresponding to this address is indirectly assigned exp.loc.

```
temp = searchInsert(symTab, newTemp(), err)
updateType(mkLocLst(temp), ADDR)
codeGen(assAddrPlus, dotId.base, dotId.offset, temp)
codeGen(assIndirTo, exp<sub>4</sub>.loc, temp)
```



Goutam Biswas

Grammar of Function Declaration


Note

• We may rewrite the rule

funDef \rightarrow funID fparamListO -> type funBody as

funDef \rightarrow funHeader funBody

funHeader \rightarrow funID fparamListO -> type

• The name of the function and its type information, an ordered list of return type and types of formal parameters, can be inserted in the current symbol table during the reduction to funHeader.



- It is necessary to save the current symbol table (ct) (pointer to it) in a stack and create a new symbol table (nt) for the new environment of the function.
- There is a link from the the function name entry in ct to the new table nt.



• It is also necessary to insert the formal parameter names and their types in the new symbol-table (nt) as they will be used as variables during the translation of the function body.



- callStmt \rightarrow (ID : actParamListO)
 - $\exp \rightarrow (ID : actParamListO)$
- actParamList \rightarrow actParamList, exp
- actParamList $\rightarrow \exp$



- Corresponding to every reduction to actParamList the following three address code may be generated. codeGen(param, exp.loc)
- But we shall delay the generation of this code due to several reasons.



- It is necessary to check type equivalence of actual and formal parameters. It may also be necessary to write code for type conversion. But none of these can be easily done during the reduction to actParamLst.
- Moreover we want to group all actual parameter codes together, without mixing them with the code to evaluate expressions.



- So we save the list of locations of exp's as synthesized attribute of actParamList.
- Finally during the reduction to exp or callStmt, a sequence of codeGen(param, exp.loc)
 3-address codes are emitted.



- Actual function call will be made during the reduction to exp or the callStmt.
- The 3-address code in case of reduction to callStmt is
 - codeGen(call, temp, count),
 - where temp is the symbol-table index
 - corresponding to the function name and
 - count is the number of actual parameters.



- The 3-address code corresponding to the reduction to exp is slightly different. A new variable name is created and inserted in the symbol table with its type information etc. The code is $codeGen(assCall, temp, count, temp_1),$ where $temp_1$ is the index of the symbol-table
 - corresponding to the new variable.



Our discussion on parameter passing assumes call-by-value. We have not talked about call-by-reference, call-by-name, call-by-need, etc. Code for Structure We have not talked about code generation for structure or record declaration and access.



There is no switch statement in our language. But what are the possible translation mechanisms of such a statement?