Logistic Regression CS60010: Deep Learning

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Agenda

- § Understand regression and classification with linear models.
- § Brush-up concepts of maximum likelihood and its use to understand linear regression.
- § Using logistic function for binary classification and estimating logistic regression parameters.



Resources

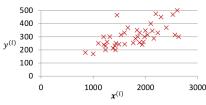
- § The Elements of Statistical Learning by T Hastie, R Tibshirani, J Friedman. [Link] [Chapter 3 and 4]
- § Artificial Intelligence: A Modern Approach by S Russell and P Norvig. [Link] [Chapter 18]

Linear Regression

- § In a regression problem we want to find the relation between some input variables \mathbf{x} and output variables y, where $\mathbf{x} \in \mathbb{R}^d$ and $y \in \mathbb{R}$.
- § Inputs are also often referred to as covariates, predictors and features; while outputs are known as variates, targets and labels.
- § Examples of such input-output pairs can be
 - ► {Outside temperature, People inside classroom, target room temperature | Energy requirement}
 - ► {Size, Number of Bedrooms, Number of Floors, Age of the Home | Price}

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 - Outside temperature, People inside classroom, target room temperature | Energy requirement}
 - ► {Size, Number of Bedrooms, Number of Floors, Age of the Home Price}
- § We have a set of N observations of y as $\{y^{(1)}, y^{(2)}, \cdots, y^{(N)}\}$ and the corresponding input variables $\{\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \cdots, \mathbf{x}^{(N)}\}$.



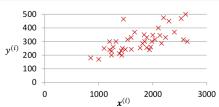
Linear Regression

- The input and output variables are assumed to be related via a relation, known as hypothesis. $\hat{y} = h_{\theta}(\mathbf{x})$, where θ is the parameter vector.
- The goal is to predict the output variable $\hat{y}^* = f(\mathbf{x}^*)$ for an arbitrary value of the input variable x^* .
- Let us start with scalar inputs (x) and scalar outputs (y).

Univariate Linear Regression

- § hypothesis: $h_{\theta}(x) = \theta_0 + \theta_1 x$.
- § Cost Function: Sum of squared errors.

$$J(\theta_0, \theta_1) = \frac{1}{2N} \sum_{i=1}^{N} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

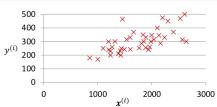


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- § Optimization objective: find model parameters (θ_0, θ_1) that will minimize the sum of squared errors.
- § Gradient of the cost function w.r.t. θ_0 :

$$\frac{J(\theta_0, \theta_1)}{\theta_0} = \frac{1}{N} \sum_{i=1}^{N} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)$$

§ Gradient of the cost function w.r.t. θ_1 :

$$\frac{J(\theta_0, \theta_1)}{\theta_1} = \frac{1}{N} \sum_{i=1}^{N} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) x^{(i)}$$

Apply your favorite gradient based optimization algorithm.

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Univariate Linear Regression

§ These being linear equations of θ , have a unique closed form solution too.

$$\theta_1 = \frac{N \sum_{i=1}^{N} y^{(i)} x^{(i)} - \left(\sum_{i=1}^{N} x^{(i)}\right) \left(\sum_{i=1}^{N} y^{(i)}\right)}{N \sum_{i=1}^{N} \left(x^{(i)}\right)^2 - \left(\sum_{i=1}^{N} x^{(i)}\right)^2}$$
$$\theta_0 = \frac{1}{N} \left\{\sum_{i=1}^{N} y^{(i)} - \theta_1 \sum_{i=1}^{N} x^{(i)}\right\}$$

- § We can easily extend to multivariate linear regression problems, where $\mathbf{x} \in \mathbb{R}^d$
- § hypothesis: $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_d x_d$. For convenience of notation, define $x_0 = 1$.
- Thus h is simply the dot product of the parameters and the input vector.

$$h_{\boldsymbol{\theta}}(\mathbf{x}) = \boldsymbol{\theta}^T \mathbf{x}$$

Sost Function: Sum of squared errors.

$$J(\boldsymbol{\theta}) = J(\theta_0, \theta_1, \cdots, \theta_d) = \frac{1}{2N} \sum_{i=1}^{N} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right)^2$$
(1)

We will use the following to write the cost function in a compact matrix vector notation

$$h_{\boldsymbol{\theta}}(\mathbf{x}) = \boldsymbol{\theta}^T \mathbf{x} = \mathbf{x}^T \boldsymbol{\theta}$$

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$$\begin{bmatrix} \widehat{y}^{(1)} \\ \widehat{y}^{(2)} \\ \vdots \\ \widehat{y}^{(N)} \end{bmatrix} = \begin{bmatrix} h_{\theta}(\mathbf{x}^{(1)}) \\ h_{\theta}(\mathbf{x}^{(2)}) \\ \vdots \\ h_{\theta}(\mathbf{x}^{(N)}) \end{bmatrix} = \begin{bmatrix} \mathbf{x}_{0}^{(1)} & \mathbf{x}_{1}^{(1)} & \mathbf{x}_{2}^{(1)} & \cdots & \mathbf{x}_{d}^{(1)} \\ \mathbf{x}_{0}^{(2)} & \mathbf{x}_{1}^{(2)} & \mathbf{x}_{2}^{(2)} & \cdots & \mathbf{x}_{d}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{x}_{0}^{(N)} & \mathbf{x}_{1}^{(N)} & \mathbf{x}_{2}^{(N)} & \cdots & \mathbf{x}_{d}^{(N)} \end{bmatrix} \begin{bmatrix} \theta_{0} \\ \theta_{1} \\ \theta_{2} \\ \vdots \\ \theta_{d} \end{bmatrix}$$

$$\widehat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$$

$$(2)$$

Here, \mathbf{X} is a $N \times (d+1)$ matrix with each row an input vector. $\widehat{\mathbf{y}}$ is a N length vector of the outputs in the training set.

§ Eqn. (1), gives,

$$J(\boldsymbol{\theta}) = \frac{1}{2N} \sum_{i=1}^{N} (\boldsymbol{\theta}^{T} \mathbf{x}^{(i)} - y^{(i)})^{2} = \frac{1}{2N} \sum_{i=1}^{N} (\widehat{y}^{(i)} - y^{(i)})^{2}$$

$$= \frac{1}{2N} ||\widehat{\mathbf{y}} - \mathbf{y}||_{2}^{2} = \frac{1}{2N} (\widehat{\mathbf{y}} - \mathbf{y})^{T} (\widehat{\mathbf{y}} - \mathbf{y})$$

$$= \frac{1}{2N} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})^{T} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) = \frac{1}{2N} \{\boldsymbol{\theta}^{T} (\mathbf{X}^{T} \mathbf{X}) \boldsymbol{\theta} - \boldsymbol{\theta}^{T} \mathbf{X}^{T} \mathbf{y} - \mathbf{y}^{T} \mathbf{X} \boldsymbol{\theta} + \mathbf{y}^{T} \mathbf{y}\}$$

$$= \frac{1}{2N} \{\boldsymbol{\theta}^{T} (\mathbf{X}^{T} \mathbf{X}) \boldsymbol{\theta} - (\mathbf{X}^{T} \mathbf{y})^{T} \boldsymbol{\theta} - (\mathbf{X}^{T} \mathbf{y})^{T} \boldsymbol{\theta} + \mathbf{y}^{T} \mathbf{y}\}$$

$$= \frac{1}{2N} \{\boldsymbol{\theta}^{T} (\mathbf{X}^{T} \mathbf{X}) \boldsymbol{\theta} - 2(\mathbf{X}^{T} \mathbf{y})^{T} \boldsymbol{\theta} + \mathbf{y}^{T} \mathbf{y}\}$$

§ Equating the gradient of the cost function to 0,

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{1}{2N} \left\{ 2\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - 2\mathbf{X}^T \mathbf{y} + 0 \right\} = 0$$

$$\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - \mathbf{X}^T \mathbf{y} = 0$$

$$\boldsymbol{\theta} = \left(\mathbf{X}^T \mathbf{X} \right)^{-1} \mathbf{X}^T \mathbf{y}$$
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§ This gives a closed form solution, but another option is to use iterative solution (just like the univariate case).

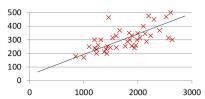
$$\frac{\partial J(\boldsymbol{\theta})}{\partial \theta_j} = \frac{1}{N} \sum_{i=1}^{N} \left(h_{\boldsymbol{\theta}}(x^{(i)}) - y^{(i)} \right) x_j^{(i)}$$

- § Iterative Gradient Descent needs to perform many iterations and need to choose a stepsize parameter judiciously. But it works equally well even if the number of features (d) is large.
- § For the least square solution, there is no need to choose the step size parameter or no need to iterate. But, evaluating $(\mathbf{X}^T\mathbf{X})^{-1}$ can be slow if d is large.

Linear Regression as Maximum Likelihood Estimation

- So far we tried to fit a "straightline" ("hyperplane" to be more precise) for linear regression problem.
- This is, in a sense, a "constrained" way of looking at the problem.

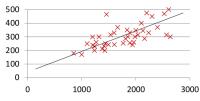
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- § This is, in a sense, a "constrained" way of looking at the problem.

 Datapoints may not be perfectly fit to the hyperplane, but "how uncertain" they are from the hyperplane is never considered.



- § An alternate view considers the following.
 - $ightharpoonup y^{(i)}$ are generated from the $\mathbf{x}^{(i)}$ following a underlying hyperplane.
 - \blacktriangleright But we don't get to "see" the generated data. Instead we "see" a noisy version of the $y^{(i)}$'s.
 - Maximum likelihood (or in general, probabilistic estimation) models this uncertainty in determining the data generating function.

Linear Regression as Maximum Likelihood Estimation

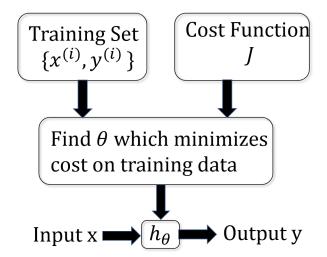
§ Thus data are assumed to be generated as follows.

$$y^{(i)} = h_{\theta}(\mathbf{x}^{(i)}) + \epsilon^{(i)}$$

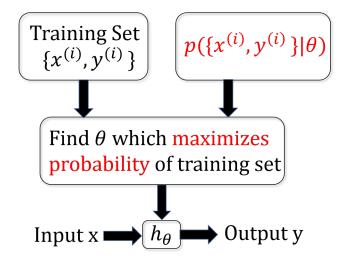
where $\epsilon^{(i)}$ is an additive noise following some probability distribution.

- § So, $(\mathbf{x}^{(i)}, y^{(i)})$'s form a joint distribution.
- § The idea is to assume a probability distribution on the noise and the probability distribution is parameterised by some additional parameters (e.g., Gaussian with 0 mean and covariance σ^2).
- § Then find the parameters (both θ and σ^2) that is "most likely" to generate the data.

Recall: Cost Function



Alternate View: "Maximum Likelihood"



- § Intuitive example: Estimate a coin toss
 - I have seen 3 flips of heads, 2 flips of tails, what is the chance of head (or tail) of my next flip?
- § Model:

Each flip is a Bernoulli random variable x.

x can take only two values: 1(head), 0(tail)

$$p(x|\theta) = \begin{cases} \theta, & \text{if } x = 1\\ 1 - \theta, & \text{if } x = 0 \end{cases}$$
 (5)

where, $\theta \in [0,1]$, is a parameter to be defined from data

§ We can write this probability more succinctly as

$$p(x|\theta) = \theta^x (1-\theta)^{1-x} \tag{6}$$

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- § We will prove in the following that the intuition in this case is correct, by proving that the guess $\theta = \sum_i x_i/n$ is the "most likely" value for the real θ .
- § Then the joint probability is

$$f(x_1,, x_n; \theta) = \prod_i f(x_i; \theta) = \theta^{\sum_i x_i} (1 - \theta)^{n - \sum_i x_i}$$
 (7)

- § We now want to find the θ which makes this probability the highest.
- § It is easier to maximize the log of the joint probabilities $log \mathcal{L}(\theta) = \sum_i x_i log \ \theta + (n \sum_i x_i) log \ (1 \theta)$, which yields the same result, since the log is monotonously increasing.
- § As we may remember, maximizing a function means setting its first derivative to 0.

$$\frac{\partial \log \mathcal{L}(\theta)}{\partial \theta} = \frac{\sum_{i} x_{i}}{\theta} - \frac{(n - \sum_{i} x_{i})}{1 - \theta}$$

$$= \frac{(1 - \theta) \sum_{i} x_{i} - \theta n + \theta \sum_{i} x_{i}}{\theta (1 - \theta)}$$

$$= \frac{\sum_{i} x_{i} - \theta n}{\theta (1 - \theta)} = 0$$

$$\implies \theta = \frac{\sum_{i} x_{i}}{n}$$

Maximum Likelihood Estimation

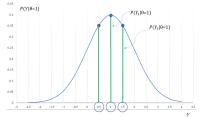
We have n=3 data points $y_1=\mathbf{1}, y_2=\mathbf{0.5}, y_3=\mathbf{1.5},$ which are independent and Gaussian with unknown $mean=\theta$ and $variance=1:y_i\sim\mathcal{N}(\theta,1)$

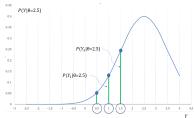
with **likelihood** $P(y_1, y_2, y_3; \theta) = P(y_1; \theta)P(y_2; \theta)P(y_3; \theta)$. Consider two guesses of θ , 1 and 2.5. Which has higher likelihood (probability of generating the three observations)?

Maximum Likelihood Estimation

We have n=3 data points $y_1=1, y_2=0.5, y_3=1.5$, which are independent and Gaussian with unknown $mean = \theta$ and variance = 1: $y_i \sim \mathcal{N}(\theta, 1)$

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Finding the θ that maximizes the likelihood is equivalent to moving the Gaussian until the product of 3 green bars (likelihood) is maximized.

Slide Motivation: Nando de Freitas [Link]

Maximum Likelihood Estimation of model parameters θ

- § In general, we have observations, $\mathcal{D} = \{u^{(1)}, u^{(2)}, \cdots, u^{(N)}\}$
- § We assume data is generated by some distribution $U \sim p(U;\theta)$
- § Compute the likelihood function

$$\mathcal{L}(\theta) = \prod_{i=1}^{N} p(u^{(i)}; \theta) \leftarrow \text{Likelihood Function}$$
 (9)

$$\theta_{ML} = \underset{\theta}{\arg \max} \mathcal{L}(\theta)$$

$$= \underset{\theta}{\arg \max} \sum_{i=1}^{n} \log p(u^{(i)}; \theta) \leftarrow \text{Log Likelihood}$$
 (10)

§ $\log(f(x))$ is monotonic/ increasing, same $\arg\max$ as f(x)

- § Let us assume that the noise is Gaussian distributed with mean 0 and variance σ^2 $u^{(i)} = h_{\theta}(\mathbf{x}^{(i)}) + \epsilon^{(i)} = \boldsymbol{\theta}^T \mathbf{x}^{(i)} + \epsilon^{(i)}$
- § Noise $\epsilon^{(i)} \sim \mathcal{N}(0, \sigma^2)$ and thus $y^{(i)} \sim \mathcal{N}(\boldsymbol{\theta}^T \mathbf{x}^{(i)}, \sigma^2)$.

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variance
$$\sigma^2$$
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- § Noise $\epsilon^{(i)} \sim \mathcal{N}(0, \sigma^2)$ and thus $y^{(i)} \sim \mathcal{N}(\boldsymbol{\theta}^T \mathbf{x}^{(i)}, \sigma^2)$.
- § Let us compute the likelihood.

$$p(\mathbf{y}|\mathbf{X};\boldsymbol{\theta},\sigma^{2}) = \prod_{i=1}^{N} p(y^{(i)}|\mathbf{x}^{(i)};\boldsymbol{\theta},\sigma^{2})$$

$$= \prod_{i=1}^{N} (2\pi\sigma^{2})^{-\frac{1}{2}} e^{-\frac{1}{2\sigma^{2}} \left(y^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)}\right)^{2}}$$

$$= (2\pi\sigma^{2})^{-\frac{N}{2}} e^{-\frac{1}{2\sigma^{2}} \sum_{i=1}^{N} \left(y^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)}\right)^{2}}$$

$$= (2\pi\sigma^{2})^{-\frac{N}{2}} e^{-\frac{1}{2\sigma^{2}} \left(\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\right)^{T} \left(\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\right)}$$

$$= (11)$$

§ So we have got the likelihood as,

$$p(\mathbf{y}|\mathbf{X};\boldsymbol{\theta},\sigma^2) = (2\pi\sigma^2)^{-\frac{N}{2}} e^{-\frac{1}{2\sigma^2}(\mathbf{y}-\mathbf{X}\boldsymbol{\theta})^T(\mathbf{y}-\mathbf{X}\boldsymbol{\theta})}$$

§ The log likelihood is

$$l(\boldsymbol{\theta}, \sigma^2) = -\frac{N}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^T (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})$$

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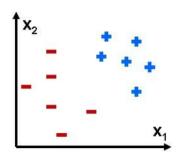
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- § Maximizing the likelihood w.r.t. θ means maximizing $-(\mathbf{y} \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} \mathbf{X}\boldsymbol{\theta})$ which in turn means minimizing $(\mathbf{y} \mathbf{X}\boldsymbol{\theta})^T(\mathbf{y} \mathbf{X}\boldsymbol{\theta})$.
- § Note the similarity with what we did earlier.
- § Thus linear regression can be equivalently viewed as minimizing error sum of squares as well as maximum likelihood estimation under zero mean Gaussian noise assumption.



Classification

- § $y \in \{0,1\}$, where 0: "Negative class" (e.g., benign tumor), 1: "Positive class" (e.g., malignant tumor)
- § Some more examples:
 - Email: Spam/ Not Spam?
 - ▶ Video: Viral/Not Viral?
 - ▶ Tremor: Earthquake/Nuclear explosion?





- § Linear functions can be used to do classification as well as regression.
- § For example,

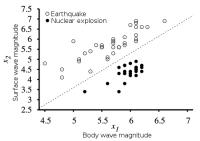


Figure credit: AIMA: Russell, Norvig

- § A **decision boundary** is a line (or a surface, in higher dimensions) that separates the two classes.
- § A linear function gives rise to a **linear separator** and the data that admit such a separator are called **linearly separable**.



§ The linear separator in the associated fig is given by,

$$x_2 = 1.7x_1 - 4.9$$

$$\Rightarrow -4.9 + 1.7x_1 - x_2 = 0$$

$$\Rightarrow [-4.9, 1.7, -1.0] \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = 0$$

$$\theta^T \mathbf{x} = 0$$

$$\begin{cases} \mathbf{r} \\ \mathbf{r} \\$$

Body wave magnitude

Figure credit: AIMA: Russell, Norvig





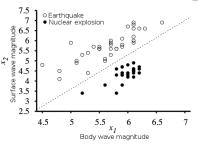


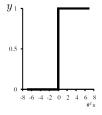
Figure credit: AIMA: Russell, Norvig

- § The explosions (y = 1) are to the right of this line with higher values of x_1 and lower values of x_2 . So, they are points for which $\theta^T \mathbf{x} \geq 0$
- § Similarly earthquakes (y=0) are to the left of this line. So, they are points for which $\theta^T \mathbf{x} < 0$
- § The classification rule is then,

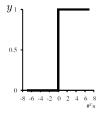
$$y(\mathbf{x}) = \begin{cases} 1 & \text{if } \boldsymbol{\theta}^T \mathbf{x} \ge 0 \\ 0 & \text{otherwise} \end{cases}$$



§ Alternatively, we can think y as the result of passing the linear function $\theta^T \mathbf{x}$ through a threshold function.



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- § To get the linear separator we have find the θ which minimizes classification error on the training set.
- § For regression problems, we found θ in both closed form and by gradient descent. But both approaches required us to compute the gradient.
- § This is not possible for the above threshold function as the gradient is undefined when the *value* at x axis = 0 and 0 elsewhere.

§ Perceptron Rule - This algorithm doesnot compute the gradient to find θ .



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- § Perceptron Learning Rule can find a linear separator given the data is linearly separable.
- § For data that are not linearly separable, the Perceptron algorithm fails.

- § Perceptron Rule This algorithm doesnot compute the gradient to find θ .
- § Perceptron Learning Rule can find a linear separator given the data is linearly separable.
- § For data that are not linearly separable, the Perceptron algorithm fails.
- § So, we need to go for a gradient based optimization approach
- § Thus, we need to approximate hard threshold function with something smooth.

$$\sigma(u) = \frac{1}{1 + e^{-u}}$$
$$y = \sigma(h_{\theta}(x)) = \sigma(\boldsymbol{\theta}^{T} \mathbf{x})$$

- § Notice that the output is a number between 0 and 1, so it can be interpreted as a probability value belonging to Class 1.
- § This is called a logistic regression classifier. The gradient computation is tedious but straight forward.

- § Mathematically, the probability that an example belongs to class 1 is $P(y^{(i)} = 1 | \mathbf{x}^{(i)}; \boldsymbol{\theta}) = \sigma(\boldsymbol{\theta}^T \mathbf{x}^{(i)})$
- § Similarly, $P(y^{(i)} = 0 | \mathbf{x}^{(i)}; \boldsymbol{\theta}) = 1 \sigma(\boldsymbol{\theta}^T \mathbf{x}^{(i)})$
- $\S \text{ Thus, } P(y^{(i)}|\mathbf{x}^{(i)};\boldsymbol{\theta}) = \left(\sigma \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)}\right)\right)^{y^{(i)}} \left(1 \sigma \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)}\right)\right)^{(1-y^{(i)})}$



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- § The joint probability of all the labels

$$\prod_{i=1}^{N} \left(\sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \right)^{y^{(i)}} \left(1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \right)^{(1-y^{(i)})}$$

- § Mathematically, the probability that an example belongs to class 1 is $P(y^{(i)} = 1 | \mathbf{x}^{(i)}; \boldsymbol{\theta}) = \sigma(\boldsymbol{\theta}^T \mathbf{x}^{(i)})$
- § Similarly, $P(y^{(i)} = 0 | \mathbf{x}^{(i)}; \boldsymbol{\theta}) = 1 \sigma(\boldsymbol{\theta}^T \mathbf{x}^{(i)})$
- $\S \text{ Thus, } P(y^{(i)}|\mathbf{x}^{(i)};\boldsymbol{\theta}) = \left(\sigma \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)}\right)\right)^{y^{(i)}} \left(1 \sigma \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)}\right)\right)^{(1-y^{(i)})}$
- § The joint probability of all the labels

$$\prod_{i=1}^{N} \left(\sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \right)^{y^{(i)}} \left(1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \right)^{(1-y^{(i)})}$$

§ So the log likelihood for logistic regression is given by,

$$l(\boldsymbol{\theta}) = \sum_{i=1}^{N} y^{(i)} \log \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) + (1 - y^{(i)}) \log (1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}))$$



§ Derivative of log likelihood w.r.t. one component of θ ,

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \theta_{j}} = \frac{\partial}{\partial \theta_{j}} \sum_{i=1}^{N} y^{(i)} \log \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) + (1 - y^{(i)}) \log \left(1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})\right)
= \sum_{i=1}^{N} \left[\frac{y^{(i)}}{\sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})} - \frac{1 - y^{(i)}}{1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})} \right] \frac{\partial}{\partial \theta_{j}} \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})
= \sum_{i=1}^{N} \left[\frac{y^{(i)}}{\sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})} - \frac{1 - y^{(i)}}{1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})} \right] \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \left(1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})\right) \mathbf{x}_{j}^{(i)}
= \sum_{i=1}^{N} \left[\frac{y^{(i)} - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})}{\sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \left(1 - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)})\right) \mathbf{x}_{j}^{(i)} \right]
= \sum_{i=1}^{N} \left[y^{(i)} - \sigma(\boldsymbol{\theta}^{T} \mathbf{x}^{(i)}) \right] \mathbf{x}_{j}^{(i)}$$
(12)

§ This is used in an iterative gradient ascent loop.

