

Formal Languages and Automata Theory

Third Long Test

Time: 50 minutes

14–April–2021

Maximum marks: 40

1. Consider the language

$$L = \left\{ wc^m d^n \mid w \in \{a, b\}^*, m = \text{the number of } a\text{'s in } w, \text{ and } n = \text{the number of } b\text{'s in } w \right\}.$$

(a) Design a Turing machine that accepts L . (4)

Solution [Sketch] First check whether the input is in the correct format. If not (for example, if an a or a b appears after a c or a d , or if a d appears after a c), reject and halt. Match the a 's in w with the c 's. If the matching fails, reject and halt. Then, match the b 's in w with the d 's. If the matching fails, reject and halt. Accept and halt if the reject decision has not yet been taken so far.

(b) Give an unrestricted grammar for L . (6)

Solution The following grammar with the start symbol S generates L .

$$\begin{aligned} S &\rightarrow T\# \\ T &\rightarrow aTC \mid bTD \mid \varepsilon \\ DC &\rightarrow CD \\ D\# &\rightarrow d \\ Dd &\rightarrow dd \\ C\# &\rightarrow c \\ Cd &\rightarrow cd \\ Cc &\rightarrow cc \\ \# &\rightarrow \varepsilon \end{aligned}$$

2. (a) Let $f : \{1, 2, \dots, n\} \times \{1, 2, \dots, n\} \rightarrow \{1, 2, \dots, n^2\}$ be the bijective function $f(i, j) = (i-1)n + j$ for $1 \leq i, j \leq n$. Consider the language L that consists of all strings $x \# 0^k$ of the following form.

1. $x \in \{0, 1\}^*$, and $|x| = n^2$ for some integer $n \geq k \geq 1$. Denote $x = x_1 x_2 \dots x_{n^2}$.
2. For each i, j satisfying $1 \leq i < j \leq n$, we have $x_{f(i,j)} = x_{f(j,i)}$, and for each i in the range $1 \leq i \leq n$, we have $x_{f(i,i)} = 0$.
3. There exists a set $S \subseteq \{1, 2, \dots, n\}$ with $|S| \geq k$ such that for each $i, j \in S$, we have $x_{f(i,j)} = 0$.

Design a nondeterministic Turing machine (NTM) accepting L . (**Hint:** Think of undirected graphs.) (6)

Solution The strings in L are encodings of adjacency matrices of graphs with $n \geq 1$ vertices and an integer k , with the additional property that the graph has an independent set of size at least k .

On the work tape of the NTM, guess n , and check for Condition 1.

Then, check for Condition 2.

Condition 3 requires the graph to have an independent set S of size at least k . Guess a binary vector of length n (first write down n 0's, where the square of the length should match the length of x , then nondeterministically change some of the 0's to 1's) which is an indicator vector I for the vertices of S . Check if the indicator vector I has at least k 1's (the number of 1's should be at least the number of 0's after the $\#$ symbol in the input), otherwise reject. For each i, j in the range $1 \leq i, j \leq n$ such that both the i -th and the j -th bits in I are 1, check if $x_{f(i,j)} = 0$. If this is not true for some pair i, j , then reject. Otherwise, accept the input string.

(b) A Jump Turing machine (JTM) $J = (Q, \Sigma, \Gamma, \delta, \vdash, \sqcap, s, t, r)$ is like a standard one-tape Turing machine (TM) with the only exception that each transition of J is of the form $\delta(p, A) = (q, B, m)$, where $p, q \in Q$, and

$A, B \in \Gamma$, and $m \in \mathbb{Z}$. This means that if the finite control of J is in the state p and the head of J scans the tape symbol A , then the state changes to q , the content of the tape cell is changed from A to B , and the head jumps by m cells relative to the current position. If $m = 0$, the head stays at the current cell. If $m > 0$, the head makes a right jump. If $m < 0$, the head makes a left jump with the understanding that if the head is at position i on the tape and $|m| > i$, then the head goes to the leftmost cell (which stores the left end-marker \vdash). Also assume that if A is \vdash , then $m \geq 0$. Prove that a JTM is equivalent to a TM. (4)

Solution A TM is a special case of a JTM where $m = \pm 1$ in each transition.

Conversely, we show that a transition $\delta_J(p, A) = (q, B, m)$ of J can be simulated by multiple transitions of an ordinary TM M . Q_M consists of all the states in Q_J along with some additional temporary states. Let us see how different values of m can be handled.

$m > 0$: Introduce $m - 1$ temporary states u_1, u_2, \dots, u_{m-1} and the transitions $\delta_M(p, A) = (u_1, B, R)$, $\delta_M(u_1, *) = (u_2, *, R)$, $\delta_M(u_2, *) = (u_3, *, R)$, \dots , $\delta_M(u_{m-1}, *) = (q, *, R)$. Here, $*$ is any tape symbol which is not changed during the last $m - 1$ transitions of M .

$m < 0$: Write $m = -n$ with $n > 0$. Introduce n temporary states v_1, v_2, \dots, v_n and the transitions $\delta_M(p, A) = (v_1, B, L)$, $\delta_M(v_1, *) = (v_2, *, L)$, $\delta_M(v_2, *) = (v_3, *, L)$, \dots , $\delta_M(v_{n-1}, *) = (q, *, L)$. Here, $*$ is any tape symbol other than \vdash . In order to ensure that M never moves to the left of the left end-marker, add the transitions $\delta_M(v_i, \vdash) = \delta_M(v_n, \vdash, R)$ for all $i \in [1, n - 1]$, and $\delta_M(v_n, *) = (q, *, L)$.

$m = 0$: Add a temporary state w and the transitions $\delta_M(p, A) = (w, B, R)$ and $\delta_M(w, *) = (q, *, L)$.

Notice that since each m in a transition is finite, and there are only finitely many entries in the transition table of J , only finitely many temporary states need to be added.

3. Let N be a nondeterministic Turing machine (NTM). We say that N faces a dilemma if at some point in its working, it encounters a situation where the finite control is in the state p , the head scans the tape symbol a , and $\delta(p, a)$ offers multiple (two or more) possibilities, where p is neither the accept nor the reject state. Consider the following two languages.

$$\begin{aligned} \text{DILEMMA}_\varepsilon &= \left\{ N \mid N \text{ is an NTM which faces a dilemma at least once on input } \varepsilon \right\}, \\ \text{DILEMMA}_{\text{ALL}} &= \left\{ N \mid N \text{ is an NTM which faces a dilemma at least once on each input} \right\}. \end{aligned}$$

- (a) Prove that $\text{DILEMMA}_\varepsilon$ is recursively enumerable but not recursive. (5)

Solution [RE] Here is a Turing machine T that recognizes $\text{DILEMMA}_\varepsilon$. T simulates N on ε . The simulation of an NTM in the current context goes as follows. Before simulating each move of N , T first finds out the number m of transition possibilities that apply to the current situation of N . If $m = 0$, T rejects and halts. If $m = 1$, T simulates the unique transition applicable. If the resulting state is t or r , T rejects and halts. If $m \geq 2$, T accepts and halts.

[Not recursive] We propose a reduction $\text{HP} \leq \text{DILEMMA}_\varepsilon$ that takes $M \# w$ to N such that N faces a dilemma on input ε if and only if M halts on w . Here, M is considered to be a DTM (this is how HP was defined).

N , on input v , does the following.

1. Simulate M on w .
2. If the simulation halts, make a nondeterministic choice to jump to the accept or to the reject state.
3. Accept/Reject depending on the choice, and halt.

Since M is a DTM, the simulation of Step 2 never faces a dilemma. Therefore if M does not halt on w , N never faces a dilemma. Conversely, if M halts on w , N faces a dilemma in Step 3 on all inputs, and in particular on ε .

- (b) Prove that $\text{DILEMMA}_{\text{ALL}}$ is not recursively enumerable. (5)

Solution We propose a reduction $\overline{\text{HP}} \leq \text{DILEMMA}_{\text{ALL}}$ taking $M \# w$ to N such that N faces a dilemma on all inputs if and only if M does not halt on w . Here again, we take M to be DTM.

N , on input v , does the following.

1. Simulate M on w for $|v|$ steps.

2. If the simulation of Step 1 does not halt, make a nondeterministic choice to jump to the accept or to the reject state. Accept/Reject depending on the choice, and halt.
3. If the simulation of Step 1 halts, reject and halt.

Since M is a DTM, the simulation of Step 1 never faces a dilemma. Any dilemma that N faces must be in Step 2. If M does not halt on w , then it does not halt in any finite number (like $|v|$) steps, so a nondeterministic choice is made by N in Step 2, that is, N faces a dilemma on any input v . On the other hand, if M halts on w in s steps, then Step 2 is executed if and only if $|v| < s$. If $|v| \geq s$, then Step 3 is executed, and N never faces a dilemma. Therefore in this case N faces a dilemma not on all inputs.

4. Let G be a context-free grammar over an input alphabet Σ , accepting the language $L = \mathcal{L}(G)$. Also, let F be a finite non-empty subset of Σ^* . Prove/Disprove whether each of the following two problems is decidable.
- (a) Given G and F , determine whether $L = F$. (5)

Solution [Decidable]

First, note that the membership problem for a CFG is decidable. So for each $w \in F$, determine whether $w \in L$. If some $w \in F$ is not in L , reject.

Convert G to CNF, and derive a pumping-lemma constant k for L . If some string in F is of length $\geq k$, then L is infinite (you can pump in), so reject. Otherwise, check whether G can generate any string of length $< k$ other than those in F . If yes, reject. Finally, check whether G can generate any string of length in the range $[k, 2k)$. If yes, reject.

If the reject decision is not yet taken, accept.

- (b) Given G and F , determine whether $L = \Sigma^* - F$. (5)

Solution [Undecidable]

[Proof based on reduction]

Assume that the given problem has a decider D . Using this, we prepare a decider D' for the problem whether $L' = \mathcal{L}(G') = \Sigma^*$, where G' is a CFG over Σ . D' runs the following steps.

1. Decide whether $\varepsilon \in L'$. If not, reject.
2. Invoke the decider D with input $G = \text{CNF}(G')$ and $F = \{\varepsilon\}$.
3. Accept if D accepts, or reject if D rejects.

Step 1 is decidable, because we have seen a marking algorithm for the membership of ε in the language of a CFG. We have also seen that the general membership problem whether a CFG G can generate a given string w is decidable.

Step 2 is executed if and only if $\varepsilon \in L'$. In that case, $L = \mathcal{L}(G) = \mathcal{L}(G') - \{\varepsilon\} = L' - F$. If $L' = \Sigma^*$, we have $L = \Sigma^* - F$. Conversely, if $L' \neq \Sigma^*$, there exists a non-empty $w \in \Sigma^*$ such that $w \notin L'$ (we have $\varepsilon \in L'$). But then $w \notin L' - F = L$, that is, $L \neq \Sigma^* - F$. Therefore the above three steps decide the full-ness of G' , a contradiction to the fact the CFL full-ness is undecidable.

[Proof based on valid computation histories]

This is similar to the reduction from $\overline{\text{HP}}$ to the given language $\{G \# F \mid \mathcal{L}(G) = \Delta^* - F\}$, where G is a CFG over Δ . Given $M \# w$, a CFG G is to be prepared such that $L = \mathcal{L}(G) = \Delta^* - F$ if and only if M does not halt on w . Take $F = \{\varepsilon\}$,

$$\text{VALCOMP}^+(M, w) = \{\varepsilon\} \cup \text{VALCOMP}(M, w),$$

and

$$L = \overline{\text{VALCOMP}^+(M, w)} = \overline{\text{VALCOMP}(M, w)} \cap \Delta^+.$$

First, note that L is a CFL because it is the intersection of a CFL $\overline{\text{VALCOMP}(M, w)}$ and a regular set Δ^+ . A total TM can design a DFA for Δ^+ , and then a PDA for L using a product construction on this DFA and a PDA

for $\overline{\text{VALCOMP}(M, w)}$. The TM then uses the PDA-to-CFG conversion procedure to generate a CFG G for L . This completes the reduction $M \# w \mapsto G \# F$.

If M does not halt on w , then $\text{VALCOMP}(M, w) = \emptyset$, so $L = \overline{\emptyset} \cap \Delta^+ = \Delta^* \cap \Delta^+ = \Delta^+ = \Delta^* - \{\varepsilon\} = \Delta^* - F$. Conversely, if M halts on w , there are infinitely many (non-empty) computation histories of M on w , so L is a proper subset of (and so not equal to) $\Delta^+ = \Delta^* - F$.
