CS60003 Algorithm Design and Analysis, Autumn 2010–11

Class test 2

Maximum marks: 20	Time: 08-Nov-2010	Duration: 1 hour
Roll no:	Name:	

[Write your answers in the question paper itself. Be brief and precise. Answer <u>all</u> questions.]

[*Flattest Pair*] You are given n points P₁, P₂,..., P_n in general position in the plane. Your task is to find out the pair P_i, P_j (with i ≠ j) such that the absolute slope of the straight line segment P_iP_j is as small as possible. Propose an O(n log n)-time algorithm to do this. Explain the correctness of your algorithm. (4)

The following figure shows five circles (of the same radius) in the plane. Draw the (boundary of the) smallest convex *region* enclosing these circles. Also indicate the convex hull of the centers (shown as solid dots) of the five circles.



3. You are given n straight line segments L_1, L_2, \ldots, L_n each connecting a point on y = 0 to a point on y = 1. It is given that these lines are non-intersecting with one another. These segments partition the strip between y = 0 and y = 1 into n + 1 regions $R_1, R_2, \ldots, R_{n+1}$. The following figure illustrates a case of n = 5 segments. Each region is specified by the left and the right bounding segments. The first and the last regions are unbounded on one side, denoted by -. The six regions (shaded alternately) in the following figure are $R_1 = (-, L_3), R_2 = (L_3, L_5), R_3 = (L_5, L_1), R_4 = (L_1, L_2), R_5 = (L_2, L_4)$ and $R_6 = (L_4, -)$.



(a) Write an $O(n \log n)$ -time algorithm to output the regions $R_1, R_2, \ldots, R_{n+1}$ from left to right. (4)

(b) Describe an $O(n \log n)$ -time algorithm to convert the sorted output of Part (a) to a binary search tree. (4)

(c) You are given a point P in the strip between y = 0 and y = 1, but not on any of the input segments L_i . Describe an $O(\log n)$ -time algorithm to identify the region R_k to which P belongs. Should you use the BST of Part (b), explain how the search for P is exactly carried out. (4)