## TRAVELING

## SALESMAN PROBLEM <br> WITH TIME WINDOWS <br> (TSPTW)

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## TSP

- Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?
$\square$ The TSP has several applications even in its purest formulation, such as planning, logistics, and the manufacture of microchips.
$\square$ It is an NP-hard problem in combinatorial optimization


## TSP



An instance of the traveling-salesman problem. Shaded edges represent a minimum-cost tour, with cost 7.

## TSPTW - Definition

- A more difficult problem than TSP
- Involves the design of a minimum cost tour such that
- Every node is visited exactly once
- Service at a node must begin and end within the time interval specified at each node
$\square$ Incorporates service time at each node and travel time to visit from one node to other


## TSPTW - Motivation

- Practical applications in :
- Postal or office deliveries within specified timings for each
- School bus routing and scheduling
- Automated manufacturing environments
- Automated guided vehicles


## TSPTW - Formulation

- Consider a network $\mathrm{G}=(\mathrm{N}, \mathrm{A})$
- $\mathrm{N}=\{1,2,3, \ldots, \mathrm{n}\}$ is the set of nodes and A is the set of arcs
- Each node $i \in N$ is associated with
- A time window $\left[a_{i}, b_{i}\right]$
- A service time $\mathrm{s}_{\mathrm{i}}$
$\square$ Each arc is associated with a travel time $\mathrm{t}_{\mathrm{ij}}$ and a travel $\operatorname{cost} \mathrm{c}_{\mathrm{ij}}$

[10,30], 0.6


## Related Work

$\square$ Savelsbergh (1985) showed that even finding a feasible solution to TSPTW is an NP complete problem

- Bakers (1983) proposed an approach which performed well on problems with upto 50 nodes
- This work by Dumas et al. (1995) is successful in solving problems with upto 200 nodes and fairly wide time windows


## Approach

$\square$ Preprocessing to remove infeasible arcs

- Dynamic Programming
- Reduction of the state space via infeasibility tests
- Takes advantage of the time window constraints
- Performed during the execution of the algorithm


## Preprocessing

$\square$ An arc $(i, j) \in A$ is feasible if $a_{i}+s_{i}+t_{i j} \leq b_{i}$

For the edge $B C$ :

$$
\begin{aligned}
& a_{B}+s_{B}+t_{B C}=20+0.4+8 \\
& =28.4>b_{C}=25
\end{aligned}
$$

Edge $B C$ can be pruned!

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## Dynamic Programming

- Define $\boldsymbol{F}(\boldsymbol{S}, \boldsymbol{i}, \boldsymbol{t})$ as the least cost of a path starting at node 1 passing through every node of $S$ exactly once and ending at node $i \in S$ and ready to serve node $i$ at time $t$ or later.
- The function $F(S, j, t)$ can be computed by the recurrence
- $F(S, j, t)=\min _{(i, j) \in A}\left\{F\left(S-\{j\}, i, t^{\prime}\right)+c_{i j}\right\}$ where $\mathrm{t}^{\prime}+\mathrm{s}_{\mathrm{i}}+\mathrm{t}_{\mathrm{ij}} \leq t$ and $a_{i} \leq t^{\prime} \leq b_{i}$
- Base condition: $F(\{1\}, 1,0)=0$, since we start at node 1



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- Base condition: $F(\{1\}, 1,0)=0$, since we start at node 1
- The optimal TSPTW solution is given by:

$$
\min _{(j, 1) \in A}\left\{F(N, j, t)+c_{j 1}\right\} \text { s.t. } \quad a_{j} \leq t \leq b_{j}
$$



## Dynamic Programming

$\square$ Let $\boldsymbol{\xi}_{\mathbf{k}}$ be a state set which contains all feasible states $(S, i, t)$ s.t $|\mathbf{S}|=\mathbf{k}$

- $\varepsilon_{1}=\{\{\{1\}, 1,0)\}$
$\square$ For computing $\xi_{\mathrm{k}}$ from $\xi_{\mathrm{k}-1}$, do the following steps:
- For each $(S, i, t) \in \xi_{k-1}$, add the state $\left(S^{\prime}, j, t^{\prime}\right)$ to $\xi_{k}$ where
- $S^{\prime}=S \cup\{j\},(i, j) \in A$ and
- $t^{\prime}=\max \left(a_{j}, t+s_{i}+t_{i j}\right)$ and
- ( $\left.S^{\prime}, j, t^{\prime}\right)$ is a feasible expansion of $(S, i, t)$


## Algorithm

- Initialize $\left.\xi_{1}=\{\{1\}, 1,0)\right\}$ and $F(\{1\}, 1,0)=0$
- $\operatorname{for}(\mathrm{k}=2,3, \ldots . . \mathrm{n})$ do
$\square \quad$ for $(S, i, t) \in \xi_{k-1}$ do
$\square$ add the state $\left(S^{\prime}, j, t^{\prime}\right)$ to $\xi_{\mathrm{k}}$ only if $\left(S^{\prime}, j, t^{\prime}\right)$ passes elimination tests
$\square$ update $F\left(S^{\prime}, j, t^{\prime}\right)=F(S, i, t)+c_{i j}$
$\square$ The optimal solution is $\min _{(j, 1) \in A}\left\{F(N, j, t)+c_{j 1}\right\}$ s.t. $a_{j} \leq t \leq b_{\mathrm{j}}$


## Elimination/Infeasibility tests

- Test 1
- Test 2
- Test 3
- Dominance Tests


## Test 1

$\square \quad$ Let $\operatorname{FIRST}(\mathbf{S}, \mathrm{i})$ denotes the smallest time when a service can begin at node i
$\square \quad$ Let LDT(i, $j$ ) denote the latest departure time at i to begin service at node j s.t. time of service at j is feasible
$\square \quad \operatorname{Reject}(\mathrm{S}, \mathrm{i}, \mathrm{t}), \mathrm{a}_{\mathrm{i}} \leq t \leq \mathrm{b}_{\mathrm{i}}$ if

- $\operatorname{FIRST}(S, i)>\min _{j \notin S} L D T(i, j)$
$\operatorname{Let} \xi_{\mathrm{k}}=\{(\{1,2\}, 2,11), \quad(\{1,2\}, 2,12)\}$
$\operatorname{FIRST}(\{1,2\}, 2)=11>\operatorname{LDT}(2,3)=9$
Can remove $(\{1,2\}, 2,11)$ and $(\{1,2\}, 2,12)$


## Test 2

$\square$ Let BEFORE(j) denote the set of nodes which must be visited before visiting the node j
$\square \quad \operatorname{Reject}(\mathrm{S}, \mathrm{i}, \mathrm{t}), \mathrm{a}_{\mathrm{i}} \leq t \leq \mathrm{b}_{\mathrm{i}} \mathrm{if}$

- $\exists \mathrm{j} \notin \mathrm{S}$ and $(\mathrm{i}, \mathrm{j}) \in \mathrm{A}$ and $\operatorname{BEFORE}(\mathrm{j}) \not \subset \mathrm{S}$

Let $\xi_{\mathrm{k}}=\{(\{1,2,3\}, 3,12),(\{1,5,3\}, 3,13)\}$
$\operatorname{BEFORE}(4)=\{1,2,5\}$


## Test 3

$\square \quad$ Reject $\left(S^{\prime}, \mathrm{j}, \mathrm{t}^{\mathrm{t}}\right), \mathrm{a}_{\mathrm{j}} \leq t^{\prime} \leq \mathrm{b}_{\mathrm{j}}$ if

- $\exists(S, i, t) s . t \mathrm{j} \notin S,(\mathrm{i}, \mathrm{j}) \in \mathrm{A}, \mathrm{t} \leq \operatorname{LDT}(\mathrm{i}, \mathrm{j})$ and
- $\quad \forall k$ s.t $\mathrm{k} \notin \mathrm{S}$ and $\mathrm{t}+\mathrm{t}_{\mathrm{ij}}>\operatorname{LDT}(\mathrm{j}, \mathrm{k})$

Let $(S, i, t)=(\{1,2\}, 2,18)$ and $\left(S^{\prime}, j, t^{\prime}\right)=(\{1,2,3\}, 3,22)$
$\operatorname{LDT}(2,3)=20$ and $\operatorname{LDT}(3,4)=12$ and $\mathrm{t}_{23}=4$
$(2,3)$ can be feasible since $\mathrm{t}=18 \leq \mathrm{LDT}(2,3)=20$ but
$(3,4)$ is infeasible since $\mathrm{t}^{+} \mathrm{t}_{23}=18+4=22>\operatorname{LDT}(3,4)=12$


## Dominance Test

$\square \operatorname{Reject}\left(S, i, t^{\prime}\right) \in \xi_{k}$ if $\exists(S, i, t) \in \xi_{k}$ s.t

- $\mathrm{F}(\mathrm{S}, \mathrm{i}, \mathrm{t}) \leq F\left(S, i, t^{\prime}\right)$
- $t \leq t^{\prime}$


## Experimental results

- Variation of CPU time with number of nodes

| $n$ | $\left\|A^{\prime}\right\|$ | $\|(S, i, t)\|$ | CPU time |
| :--- | :--- | :--- | :--- |
| 20 | 34.2 | 4.4 | 0.02 |
| 40 | 121.8 | 16.0 | 0.08 |
| 60 | 226.0 | 21.8 | 0.15 |
| 80 | 362.6 | 49.8 | 0.35 |
| 100 | 510.0 | 45.0 | 0.62 |
| 150 | 975.8 | 326.8 | 2.44 |


| $n$ | $\left\|A^{\prime}\right\|$ | $\|(S, i, t)\|$ | CPU time |
| :--- | :--- | :--- | :--- |
| 20 | 115.2 | 35.6 | 0.14 |
| 40 | 404.2 | 554.0 | 4.37 |
| 60 | 670.6 | 1344.4 | 6.84 |
| 80 | 1149.6 | 7716.8 | 55.32 |
| 100 | 1731.4 | 6804.8 | 107.95 |
| 150 | 2953.6 | 26351.0 | 462.97 |

## Experimental results

- Comparison of number of labels removed by each test

|  | w | Test 1 | Test 2 | Test 3 |
| :--- | :--- | :--- | :--- | :--- |
| $(\mathrm{S}, \mathrm{i}, \mathrm{t})$ | 20 | 21.8 | 3716.4 | 37.4 |
| CPU time |  | 0.15 | 6.20 | 0.17 |
| (S,i,t) | 40 | 145.8 | 18520.5 | 229.0 |
| CPU time |  | 0.91 | 49.23 | 0.98 |

$$
n=60
$$

## Conclusion

$\square$ For a given problem size, problem difficulty increases with the time windows
$\square$ For narrow widths, its behavior is less than exponential allowing large size problems to be solved.

- E.g. a 250 node problem with $w=20$ is solved in less than 10 sec.
- The algorithm can accommodate additional costs for waiting at a node such as total schedule time.
- The algorithm works for larger problem sizes and time windows than any previous work.


## References

$\square$ Research papers:
■ http://pubsonline.informs.org/doi/pdf/10.1287/opre.43.2.367

- http://www.jstor.org/stable/pdfplus/172015.pdf?\&acceptTC=true\&jpdConfirm=true


## Thank you

Questions / Comments?

