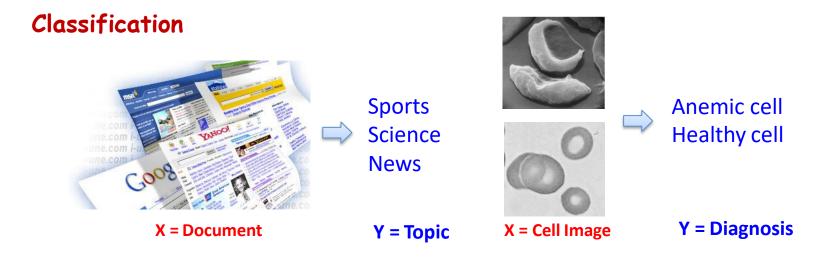
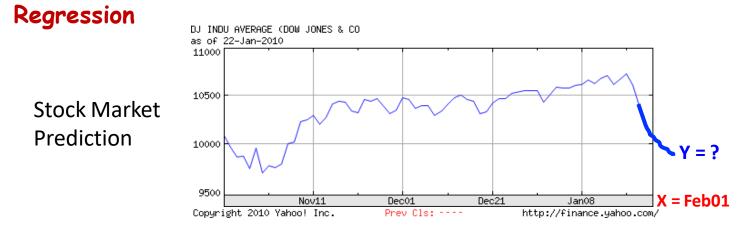
CS60020: Foundations of Algorithm Design and Machine Learning

Sourangshu Bhattacharya

Discrete and Continuous Labels





An example application

- An emergency room in a hospital measures 17 variables (e.g., blood pressure, age, etc) of newly admitted patients.
- A decision is needed: whether to put a new patient in an intensive-care unit.
- Due to the high cost of ICU, those patients who may survive less than a month are given higher priority.
- Problem: to predict high-risk patients and discriminate them from low-risk patients.

Another application

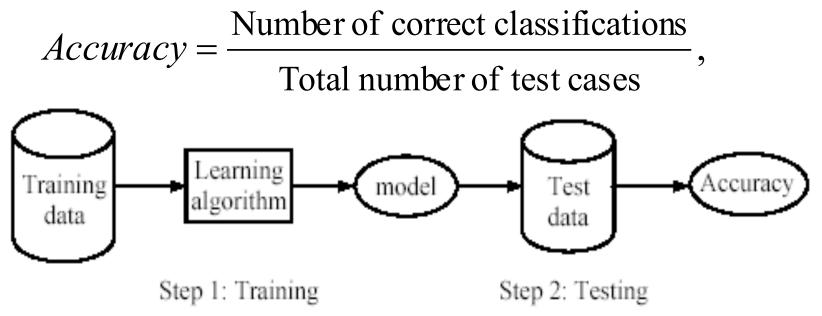
- A credit card company receives thousands of applications for new cards. Each application contains information about an applicant,
 - age
 - Marital status
 - annual salary
 - outstanding debts
 - credit rating
 - etc.
- Problem: to decide whether an application should approved, or to classify applications into two categories, approved and not approved.

The data and the goal

- Data: A set of data records (also called examples, instances or cases) described by
 - *k* attributes: $A_1, A_2, \ldots A_k$.
 - a class: Each example is labelled with a predefined class.
- Goal: To learn a classification model from the data that can be used to predict the classes of new (future, or test) cases/instances.

Supervised learning process: two steps

- Learning (training): Learn a model using the training data
- Testing: Test the model using unseen test data to assess the model accuracy



Least squares classification

- Binary classification.
- Each class is described by it's own linear model: $y(x) = w^T x + w_0$
- Compactly written as:

$$\mathbf{y}(\boldsymbol{x}) = \boldsymbol{W}^T \boldsymbol{x}$$

- **W** is $[w w_0]$.
- $E_D(W) = \frac{1}{2}(XW t)^T(XW t)$
- n^{th} row of **X** is x_n , the n^{th} datapoint.
- *t* is vector of +1, -1.

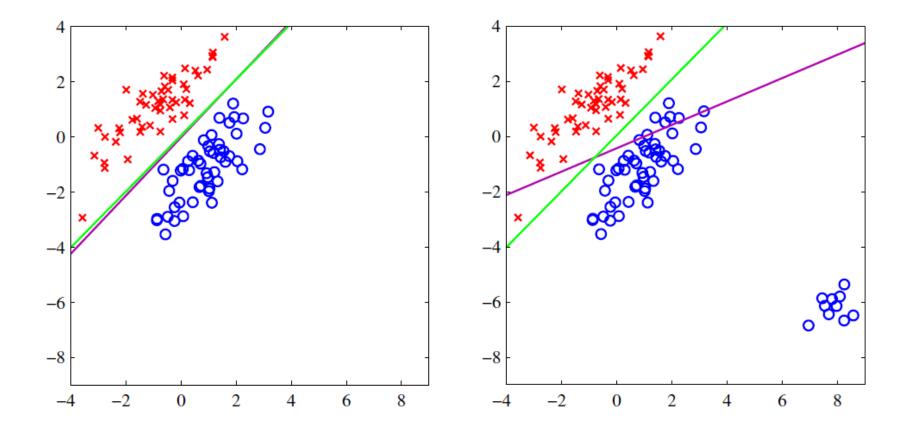
Least squares classification

• Least squares *W* is:

$$W = \left(X^T X\right)^{-1} X^T t$$

• Problem is affected by outliers.

Least squares classification



Fisher's linear discriminant

- Predictor: $y = w^T x$.
- If $y > w_0$ predict C_1 else C_2 .
- Training dataset has N₁ points from C₁ and N₂ points from C₂.

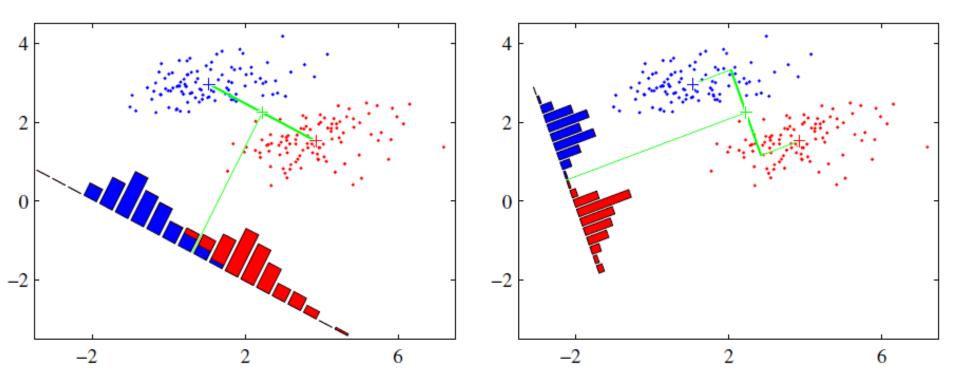
•
$$m_1 = \frac{1}{N_1} \sum_{n \in C_1} x_n$$
 and $m_2 = \frac{1}{N_2} \sum_{n \in C_2} x_n$

• Maximize separation of projected means: $m_2 - m_1 = \mathbf{w}^T (\mathbf{m}_2 - \mathbf{m}_1)$

Fisher's linear discriminant

- This measure can increase arbitrarily by increasing ||w||.
- Constrain: $||w||^2 = 1$
- Lagrangian: $L(w, \lambda) = w^T(m_2 m_1) + \lambda(||w||^2 1).$
- Solution: $w \propto (m_2 m_1)$.

Fisher linear discriminant



Fisher's linear discriminant

- Maximize separation between means while minimizing within class variance.
- Within class variance:

$$s_k^2 = \sum_{n \in C_k} (y_n - m_k)^2$$

• Objective:

$$J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}$$

Fisher's linear Discriminant

• Same as:

$$J(w) = \frac{w^T S_B w}{w^T S_w w}$$

• Between class variance:

$$S_B = (m_2 - m_1)(m_2 - m_1)^T$$

• Within class variance: S_W $= \sum_{n \in C_1} (x_n - m_1)(x_n - m_1)^T + \sum_{n \in C_2} (x_n - m_2)(x_n - m_2)^T$

Fisher's linear discriminant

• Same as:

$$\max_{w} w^{T} S_{B} w$$

s.t. $w^{T} S_{W} w = 1$

- Solution given by generalized eigenvalue problem: $S_B w = \lambda S_w w$
- Or

$$(S_W)^{-1}S_Bw = \lambda w$$

• Solution:

$$w \propto (S_W)^{-1}(m_2 - m_1)$$

From Linear to Logistic Regression

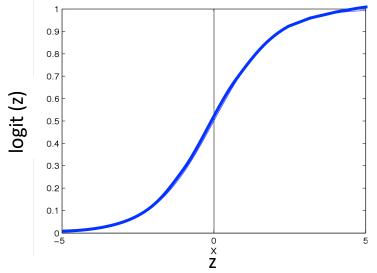
Assumes the following functional form for P(Y|X):

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Logistic function applied to a linear function of the data

Logistic function (or Sigmoid): $\frac{1}{1 + exp(-z)}$

Features can be discrete or continuous!



Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

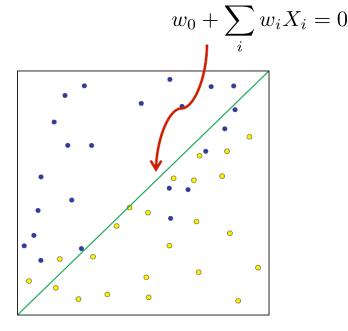
 $P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$

Decision boundary:

$$P(Y=0|X) \stackrel{0}{\underset{1}{\gtrless}} P(Y=1|X$$

$$w_0 + \sum_i w_i X_i \overset{0}{\underset{1}{\gtrless}} 0$$

(Linear Decision Boundary)



Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow P(Y = 0|X) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow \frac{P(Y=0|X)}{P(Y=1|X)} = \exp(w_0 + \sum_i w_i X_i) \quad \stackrel{0}{\underset{1}{\gtrless}} 1$$
$$\Rightarrow w_0 + \sum_i w_i X_i \quad \stackrel{0}{\underset{1}{\gtrless}} 0$$

- Label t \in {+1, -1}modeled as: $P(t = 1 | x, w) = \sigma(w^T x)$
- $P(y|x,w) = \sigma(yw^T x), y \in \{+1, -1\}$
- Given a set of parameters w, the probability or likelihood of a datapoint (x,t): $P(t|x,w) = \sigma(tw^T x)$

Given a training dataset {(x₁, t₁), ..., (x_N, t_N)},
 log likelihood of a model w is given by:

$$L(w) = \sum_{n} \ln(P(t_n | x_n, w))$$

• Using principle of maximum likelihood, the best w is given by:

$$w^* = \arg\max_w L(w)$$

• Final Problem:

$$\max_{w} \sum_{i=1}^{n} -\log(1 + \exp(-t_n w^T x_n))$$

Or,
$$\min_{w} \sum_{i=1}^{n} \log(1 + \exp(-t_n w^T x_n))$$

• Error function:

$$E(w) = \sum_{i=1}^{n} \log(1 + \exp(-t_n w^T x_n))$$

• E(w) is convex.

• Final Problem:

$$\max_{w} \sum_{i=1}^{n} -\log(1 + \exp(-t_n w^T x_n))$$

• Regularized Version:

$$\max \sum_{i=1}^{n} -\log(1 + \exp(-t_n w^T x_n)) - \lambda w^T w$$

Or, $\min_{w} \sum_{i=1}^{n} \log(1 + \exp(-t_n w^T x_n)) + \lambda ||w||^2$

Properties of Error function

• Derivatives:

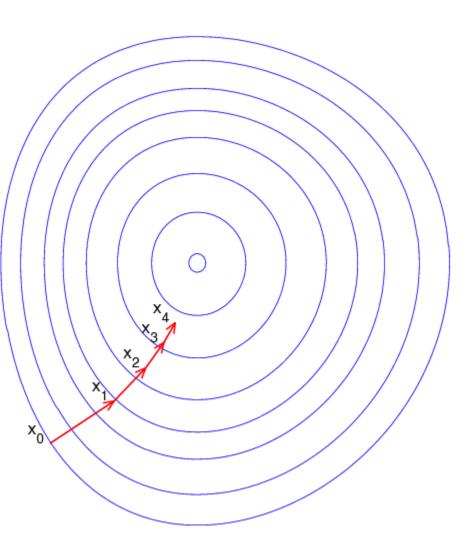
$$\nabla E(w) = \sum_{i=1}^{n} -(1 - \sigma(t_i w^T x_i))(t_i x_i)$$

$$\nabla E(w) = \sum_{i=1}^{n} (\sigma(w^T x_i) - t_i) x_i$$

$$\nabla^2 E(w) = \sum_{i=1}^n \sigma(t_i w^T x_i) \left(1 - \sigma(t_i w^T x_i)\right) x_i x_i^T$$

Gradient Descent

- Problem: min f(x)
- f(x): differentiable
- g(x): gradient of f(x)
- Negative gradient is steepest descent direction.
- At each step move in the gradient direction so that there is "sufficient decrease".



Gradient Descent

input : Function f, Gradient ∇f **output**: Optimal solution w^* Initialize $w_0 \leftarrow 0, k \leftarrow 0$ while $|\nabla f_k| > \epsilon$ do Compute $\alpha_k \leftarrow \text{linesearch}(f, -\nabla f_k, w_k)$ Set $w_{k+1} \leftarrow w_k - \alpha_k \nabla f_k$ Evaluate ∇f_{k+1} $k \leftarrow k+1$ end $w^* \leftarrow w_k$

Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow P(Y = 0|X) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow \frac{P(Y=0|X)}{P(Y=1|X)} = \exp(w_0 + \sum_i w_i X_i) \quad \stackrel{0}{\underset{1}{\gtrless}} 1$$
$$\Rightarrow w_0 + \sum_i w_i X_i \quad \stackrel{0}{\underset{1}{\gtrless}} 0$$

Logistic Regression for more than 2 classes

Logistic regression in more general case, where
 Y {y₁,...,y_K}

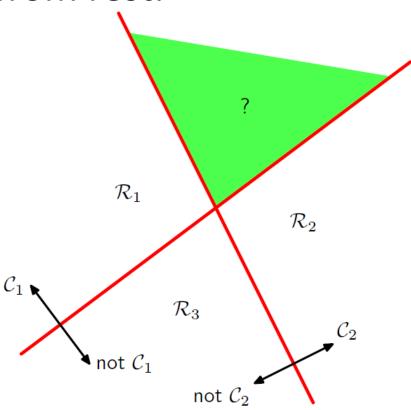
for kP(Y = y_k | X) = \frac{\exp(w_{k0} + \sum_{i=1}^{d} w_{ki} X_i)}{1 + \sum_{j=1}^{K-1} \exp(w_{j0} + \sum_{i=1}^{d} w_{ji} X_i)}

for *k*=*K* (normalization, so no weights for this class)

$$P(Y = y_K | X) = \frac{1}{1 + \sum_{j=1}^{K-1} \exp(w_{j0} + \sum_{i=1}^{d} w_{ji} X_i)}$$

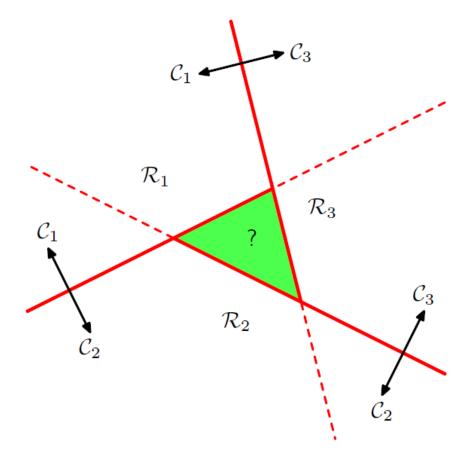
Multiple classes

- One-vs-all: K 1 hyperplanes each separating C_1, \ldots, C_{K-1} classes from rest.
- Otherwise C_K
- Low number of classifiers.



Multiple classes

- One-vs-one: Every pair $C_i C_j$ get a boundary.
- Final by majority vote.
- High number of classifiers.



Multiple classes

• K-linear discriminant functions:

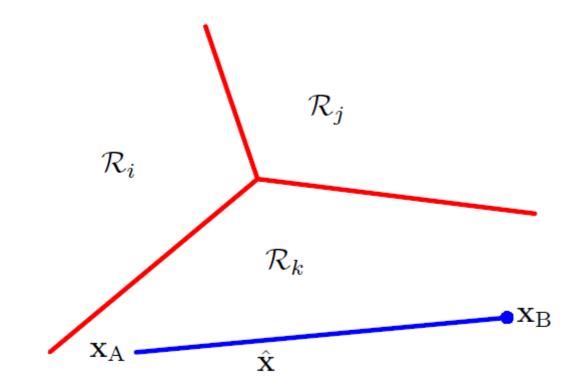
$$y_k(x) = w_k^T x + w_{k0}$$

- Assign x to C_k if $y_k(x) \ge y_j(x)$ for all $j \ne k$
- Decision boundary:

$$(w_k - w_j)^T x + (w_{k0} - w_{j0}) = 0$$

- Decision region is singly connected: $x = \lambda x_A + (1 - \lambda) x_B$
- If x_A and x_B have same label, so does x.

Multiple Classes



NAÏVE BAYES

Generative vs. Discriminative Classifiers

Discriminative classifiers (e.g. Logistic Regression)

- Assume some functional form for P(Y|X) or for the decision boundary
- Estimate parameters of P(Y|X) directly from training data

Generative classifiers (e.g. Naïve Bayes)

- Assume some functional form for P(X,Y) (or P(X|Y) and P(Y))
- Estimate parameters of P(X|Y), P(Y) directly from training data

arg max_Y $P(Y|X) = \arg \max_Y P(X|Y) P(Y)$

A text classification task: Email spam filtering

```
From: ``' <takworlld@hotmail.com>
Subject: real estate is the only way... gem oalvgkay
Anyone can buy real estate with no money down
Stop paying rent TODAY !
There is no need to spend hundreds or even thousands for
similar courses
I am 22 years old and I have already purchased 6 properties
using the
methods outlined in this truly INCREDIBLE ebook.
Change your life NOW !
```

Click Below to order: http://www.wholesaledaily.com/sales/nmd.htm

How would you write a program that would automatically detect and delete this type of message?

Formal definition of TC: Training

Given:

A document set X

 Documents are represented typically in some type of highdimensional space.

•A fixed set of classes $C = \{c_1, c_2, \ldots, c_J\}$

The classes are human-defined for the needs of an application (e.g., relevant vs. nonrelevant).

■A training set D of labeled documents with each labeled document $\langle d, c \rangle \in X \times C$ Using a learning method or learning algorithm, we then wish to learn a classifier Y that maps documents to classes:

 $\Upsilon:X\to C$

Formal definition of TC: Application/Testing

Given: a description $d \in X$ of a document Determine: $\Upsilon(d) \in C$, that is, the class that is most appropriate for d

Examples of how search engines use classification

Language identification (classes: English vs. French etc.)

- The automatic detection of spam pages (spam vs. nonspam)
- Topic-specific or vertical search restrict search to a "vertical" like "related to health" (relevant to vertical vs. not)

Derivation of Naive Bayes rule

We want to find the class that is most likely given the document:

$$egin{argammatrix} c_{\mathsf{map}} &= rg\max_{c\in\mathbb{C}} P(c|d) \ \end{split}$$

Apply Bayes rule

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}:$$

$$c_{\text{map}} = \arg \max_{c \in \mathbb{C}} \frac{P(d|c)P(c)}{P(d)}$$

Drop denominator since P(d) is the same for all classes:

$$c_{\max} = rg \max_{c \in \mathbb{C}} P(d|c)P(c)$$

Too many parameters / sparseness

$$c_{map} = \underset{c \in \mathbb{C}}{\arg \max} P(d|c)P(c)$$

=
$$\underset{c \in \mathbb{C}}{\arg \max} P(\langle t_1, \dots, t_k, \dots, t_{n_d} \rangle | c)P(c)$$

There are too many parameters $P(\langle t_1, \ldots, t_k, \ldots, t_{n_d} \rangle | c)$, one for each unique combination of a class and a sequence of words.

•We would need a very, very large number of training examples to estimate that many parameters.

This is the problem of data sparseness.

Naive Bayes conditional independence assumption

To reduce the number of parameters to a manageable size, we make the Naive Bayes conditional independence assumption:

$$P(d|c) = P(\langle t_1, \ldots, t_{n_d} \rangle | c) = \prod_{1 \leq k \leq n_d} P(X_k = t_k | c)$$

We assume that the probability of observing the conjunction of attributes is equal to the product of the individual probabilities $P(X_k = t_k | c)$.

The Naive Bayes classifier

- The Naive Bayes classifier is a probabilistic classifier.
- We compute the probability of a document *d* being in a class *c* as follows:

$$P(c|d) \propto P(c) \prod_{1 \leq k \leq n} P(t_k|c)$$

- n_d is the length of the document. (number of tokens)
- • $P(t_k | c)$ is the conditional probability of term t_k occurring in a document of class c
- • $P(t_k | c)$ is a measure of how much evidence t_k contributes that c is the correct class.
- •P(c) is the prior probability of c.
- If a document's terms do not provide clear evidence for one class vs. another, we choose the c with highest P(c).

Maximum a posteriori class

•Our goal in Naive Bayes classification is to find the "best" class.

The best class is the most likely or maximum a posteriori (MAP) class *c*map:

$$c_{\mathsf{map}} = rg\max_{c \in \mathbb{C}} \hat{P}(c|d) = rg\max_{c \in \mathbb{C}} \hat{P}(c) \prod_{1 \leq k \leq n_d} \hat{P}(t_k|c)$$

Taking the log

- Multiplying lots of small probabilities can result in floating point underflow.
- Since log(xy) = log(x) + log(y), we can sum log probabilities instead of multiplying probabilities.
- Since log is a monotonic function, the class with the highest score does not change.

So what we usually compute in practice is:

$$c_{ ext{map}} = rg\max_{c \in \mathbb{C}} \left[\log \hat{P}(c) + \sum_{1 \leq k \leq n_d} \log \hat{P}(t_k | c)
ight]$$

Naive Bayes classifier

Classification rule:

$$c_{\mathsf{map}} = \operatorname*{arg\,max}_{c \in \mathbb{C}} \left[\log \hat{P}(c) + \sum_{1 \leq k \leq n_d} \log \hat{P}(t_k | c)
ight]$$

Simple interpretation:

- •Each conditional parameter log $\hat{P}(t_k|c)$ is a weight that indicates how good an indicator t_k is for c.
- The prior log $\tilde{P}(c)$ is a weight that indicates the relative frequency of c.
- The sum of log prior and term weights is then a measure of how much evidence there is for the document being in the class.

We select the class with the most evidence.

Parameter estimation take 1: Maximum likelihood

•Estimate parameters $\hat{P}(c)$ and $\hat{P}(t_k|c)$ from train data: How?

$$\hat{P}(c) = \frac{N_c}{N}$$

N_c : number of docs in class c; N: total number of docs

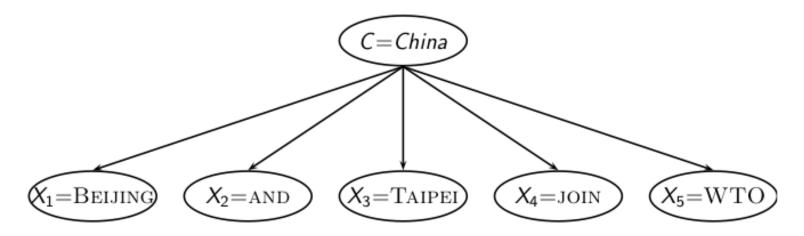
Conditional probabilities:

$$\hat{P}(t|c) = \frac{T_{ct}}{\sum_{t' \in V} T_{ct'}}$$

T_{ct} is the number of tokens of *t* in training documents from class *c* (includes multiple occurrences)

We've made a Naive Bayes independence assumption here:

The problem with maximum likelihood estimates: Zeros



P(China|d) ∝ P(China) • P(BEIJING|China) • P(AND|China) • P(TAIPEI|China) • P(JOIN|China) • P(WTO|China)

If WTO never occurs in class China in the train set:

$$\hat{P}(\text{WTO}|\text{China}) = \frac{T_{China,\text{WTO}}}{\sum_{t' \in V} T_{China,t'}} = \frac{0}{\sum_{t' \in V} T_{China,t'}} = 0$$

The problem with maximum likelihood estimates: Zeros (cont)

If there were no occurrences of WTO in documents in class China, we'd get a zero estimate:

$$\hat{P}(\text{WTO}|China) = \frac{T_{China,WTO}}{\sum_{t' \in V} T_{China,t'}} = 0$$

• \rightarrow We will get P(China|d) = 0 for any document that contains WTO!

Zero probabilities cannot be conditioned away.

To avoid zeros: Add-one smoothing

Before:

$$\hat{P}(t|c) = \frac{T_{ct}}{\sum_{t' \in V} T_{ct'}}$$

Now: Add one to each count to avoid zeros:

B is the number of different words (in this case the size of the vocabulary: |V| = B)

$$\hat{P}(t|c) = \frac{T_{ct} + 1}{\sum_{t' \in V} (T_{ct'} + 1)} = \frac{T_{ct} + 1}{(\sum_{t' \in V} T_{ct'}) + B}$$

To avoid zeros: Add-one smoothing

Estimate parameters from the training corpus using add-one smoothing

- •For a new document, for each class, compute sum of (i) log of prior and (ii) logs of conditional probabilities of the terms
- Assign the document to the class with the largest score

Exercise

	docID	words in document	in $c = China?$
training set	1	Chinese Beijing Chinese	yes
	2	Chinese Chinese Shanghai	yes
	3	Chinese Macao	yes
	4	Tokyo Japan Chinese	no
test set	5	Chinese Chinese Chinese Tokyo Japan	?

Estimate parameters of Naive Bayes classifier

Classify test document

Example: Parameter estimates

Priors: $\hat{P}(c) = 3/4$ and $\hat{P}(\overline{c}) = 1/4$ Conditional probabilities:

$$\begin{split} \hat{P}(\text{Chinese}|c) &= (5+1)/(8+6) = 6/14 = 3/7\\ \hat{P}(\text{Tokyo}|c) &= \hat{P}(\text{Japan}|c) &= (0+1)/(8+6) = 1/14\\ \hat{P}(\text{Chinese}|\overline{c}) &= (1+1)/(3+6) = 2/9\\ \hat{P}(\text{Tokyo}|\overline{c}) &= \hat{P}(\text{Japan}|\overline{c}) &= (1+1)/(3+6) = 2/9 \end{split}$$

The denominators are (8 + 6) and (3 + 6) because the lengths of *text_c* and *text_c* are 8 and 3, respectively, and because the constant *B* is 6 as the vocabulary consists of six terms.

Example: Classification

$$\hat{P}(c|d_5) \propto 3/4 \cdot (3/7)^3 \cdot 1/14 \cdot 1/14 \approx 0.0003$$

 $\hat{P}(\overline{c}|d_5) \propto 1/4 \cdot (2/9)^3 \cdot 2/9 \cdot 2/9 \approx 0.0001$

Thus, the classifier assigns the test document to c = China. The reason for this classification decision is that the three occurrences of the positive indicator CHINESE in d_5 outweigh the occurrences of the two negative indicators JAPAN and TOKYO.

Class Conditional Probabilities

To compute, $P(x_k|C_i)$

A_k is categorical:

the number of tuples of class C_i in D having the value x_k for A_k

 $P(x_k|C_i) =$

the number of tuples of class C_i in D.

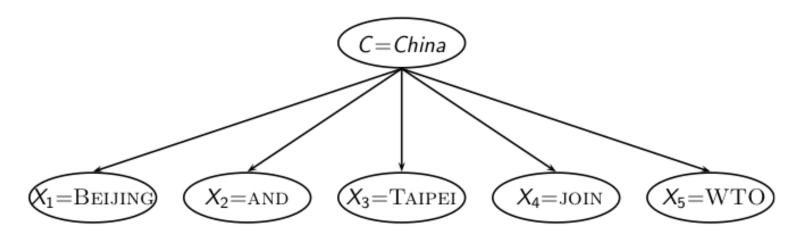
A_k is continuous:

A continuous-valued attribute is typically assumed to have a Gaussian distribution with a mean μ and standard deviation σ

$$g(x,\mu,\sigma) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-\mu)^2}{2\sigma^2}},$$

$$P(x_k|C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i}).$$

Generative model



$$P(c|d) \propto P(c) \prod_{1 \leq k \leq n_d} P(t_k|c)$$

Generate a class with probability P(c)

•Generate each of the words (in their respective positions), conditional on the class, but independent of each other, with probability $P(t_k | c)$

To classify docs, we "reengineer" this process and find the class that is most likely to have generated the doc.

On naïve Bayesian classifier

- Advantages:
 - Easy to implement
 - Very efficient
 - Good results obtained in many applications
- Disadvantages
 - Assumption: class conditional independence, therefore loss of accuracy when the assumption is seriously violated (those highly correlated data sets)