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CM and PB (IIT Kharagpur)

Section outline



- Selection Sort
- Bubble Sort
- Insertion Sort



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Motivation of Selection Sort

- Select smallest element
- Interchange with top element
- Repeat procedure leaving out the top element



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Recursive Selection Sort

Editor:

```
void selectionSortR(int Z[], int sz) {
 int sel, i, t;
   if (sz<=0) return;
   for (i=sz-1,minI=i,i--;i=>0;i--)
    // select the smallest element
    if (Z[i] < Z[minI]) minI = i;
    // interchange the min element with the top element
    t=Z[minI];
    Z[minI] = Z[0];
    Z[0]=t;
    // now sort the rest of the array
    selectionSortR(Z+1, sz-1);
```



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Iterative Selection Sort

Editor:

```
void selectionSortI(int Z[], int sz) {
 int sel, i, t;
 for (j=sz; j>0; j--) { // from full array, decrease
   for (i=sz-1, minI=i, i--; i=>sz-j; i--)
   // sz-j varies from 0 to sz-1 and i from sz-2 to sz-j
    // select the smallest element
    if (Z[i] < Z[minI]) minI = i;
    // interchange the min element with the top element
    t=Z[minI];
    Z[minI] = Z[sz-j];
    Z[sz-j]=t;
    // now sort the rest of the array
```

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Motivation of Bubble Sort

- Start from the bottom and move upwards
- If an element is smaller than the one over it, then interchange the two
- The smaller element bubbles up
- Smallest element at top at the end of the pass
- Repeat procedure leaving out the top element



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Recursive Bubble Sort

Editor:

```
void bubbleSortR(int Z[], int sz) {
 int i;
   if (sz<=0) return;
   for (i=sz-1;i>0;i--)
    // the smallest element bubbles up to the top
    if (Z[i]<Z[i-1]) {
      int t;
      t=Z[i];
      Z[i] = Z[i-1];
      Z[i-1]=t;
    }
    // now sort the rest of the array
    bubbleSortR(Z+1, sz-1);
```

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Iterative Bubble Sort

Editor:

```
void bubbleSortI(int Z[], int sz) {
 int i, j;
 for (j=sz; j>0; j--) // from full array, decrease
   for (i=sz-1;i>sz-j;i--)
    // the smallest element bubbles up to the top
    if (Z[i] < Z[i-1]) 
      int t;
      t=Z[i];
      Z[i] = Z[i-1];
      Z[i-1]=t;
```



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Insert sorted

Editor:

```
void insertSorted(int Z[], int ky, int sz) {
// insert ky at the correct place
// original array should have free locations
// sz is number of elements currently in the array
// sz is not the allocated size of the array
 int i, pos=searchBinRAF(Z, ky, sz, 0);
 if (pos<0) pos=-(pos+10);
 // compensation specific to searchBinRAF
 // now shift down all elements from pos onwards
 for (i=sz;i>pos;i--) // start from the end! (why?)
 Z[i] = Z[i-1];
 Z[pos]=ky; // now the desired position is available
```



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Insertion Sort

Editor:

```
void insertionSort(int Z[], int sz) {
  int i;
  for (i=1;i<sz;i++)
    // elements 0..(i-1) are sorted, element Z[i]
    // is to be placed so that elements 0..i are also
  sorted
    insertSorted(Z, Z[i], i);
}</pre>
```



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Section outline

Mergesort

- Merging two sorted arrays
- Merge sort

- Complexity of mergesort
- In-place merging
- Analysing mergesort with in-place merging



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Merged sequence



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First array 2 5 9 23 40

Merged sequence 1



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3 4 29 55 65 68 Second array

First array 5 9 23 40

Merged sequence 1 2



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3 4 29 55 65 68 Second array

First array 5 9 23 40

4 29 55 65 68 Second array

Merged sequence 1 2 3



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Merging two sorted arrays

First array 5 9 23 40

29 55 65 68 Second array

Merged sequence 1 2 3 4



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Merging two sorted arrays

First array 9 23 40

29 55 65 68 Second array

Merged sequence 1 2 3 4 5



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Image: A math

Merging two sorted arrays

First array 23 40

29 55 65 68 Second array

Merged sequence 1 2 3 4 5 9



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Image: A math

First array 40

29 55 65 68 Second array

Merged sequence 1 2 3 4 5 9 23



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Image: A math



55 65 68 Second array

Merged sequence 1 2 3 4 5 9 23 29



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Image: A math

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First array

55 65 68 Second array

Merged sequence 1 2 3 4 5 9 23 29 40



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Image: A math

First array

65 68 Second array

Merged sequence 1 2 3 4 5 9 23 29 40 55



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First array

68 Second array

Merged sequence 1 2 3 4 5 9 23 29 40 55 65



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First array

Second array

Merged sequence 1 2 3 4 5 9 23 29 40 55 65 68



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Image: A math

Recursive definition of merging

- M, N are number of elements in A and B, respectively
- Array indices start from 0
- Initial call: merge(*A*, *N*, 0, *B*, *M*, 0, *C*, 0)



(1.1)

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Recursive definition of merging

- M, N are number of elements in A and B, respectively
- Array indices start from 0
- Initial call: merge(*A*, *N*, 0, *B*, *M*, 0, *C*, 0)

$$merge(A, N, i, B, M, j, C, k)$$

$$= \begin{cases}
if (i \ge N \land j \ge M) \text{ then done} & (1.2) \\
else if (i \ge N) \text{ then merge}(A, N, i, B, M, j + 1, C, k + 1), \\
st C[k] = B[j] & (1.3) \\
else if (j \ge M) \text{ then merge}(A, N, i + 1, B, M, j, C, k + 1), \\
st C[k] = A[i] & (1.4) \\
else if (A[i] \le B[j]) \text{ then merge}(A, N, i + 1, B, M, j, C, k + 1), \\
st C[k] = A[i] & (1.5) \\
otherwise merge(A, N, i, B, M, j + 1, C, k + 1), \\
st C[k] = B[j] & (1.6)
\end{cases}$$

Definition is tail recursive

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(1.1)

Recursive function for merging

Editor:

```
void merge(int A[], int N, int i,
    int B[], int M, int j, int C[], int k) {
  if (i >= N && j >= M) return; // by clause (2)
  else if (i >= N) { // by clause (3)
    C[k] = B[j];
   merge (A, N, i, B, M, j + 1, C, k + 1);
  } else if (j \ge M) \{ // by clause (4) \}
   C[k] = A[i];
   merge(A, N, i + 1, B, M, j, C, k + 1);
  \} else if (A[i] <= B[j]) \{ // by clause (5) \}
    C[k] = A[i];
   merge(A, N, i + 1, B, M, j, C, k + 1);
  else \{ // by clause (6)
    C[k] = B[j];
   merge(A, N, i, B, M, j + 1, C, k + 1);
```

Testing the recursive merging

Editor:

```
#include <stdio.h>
void showIArr(int A[], int n) {
  int i;
  for (i=0; i<n; i++) printf("%d ", A[i]);</pre>
 printf("\n");
}
int main() {
  int A[]={2, 5, 9, 23, 40};
  int B[]={1, 3, 4, 29, 55, 65, 68};
  int C[12];
  printf("after merging "); showIArr(A,5);
  printf("and "); showIArr(B,7);
  merge(A, 5, 0, B, 7, 0, C, 0);
  showIArr(C, 12);
return 0; }
```

Results of test

Shell:

\$ make mergeSort ; ./mergeSort cc mergeSort.c -o mergeSort after merging 2 5 9 23 40 and 1 3 4 29 55 65 68 1 2 3 4 5 9 23 29 40 55 65 68



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Iterative function for merging

Editor:

```
void mergeI(int A[], int N, int B[], int M, int C[]) {
  int i=0, j=0, k=0; // by clause (1)
  do {
    if (i >= N && j >= M) break; // by clause (2)
    else if (i >= N) { // by clause (3)
      C[k] = B[j]; j++, k++;
    else if (j >= M) { // by clause (4)}
      C[k] = A[i]; i++; k++;
    } else if (A[i] <= B[j]) { // by clause (5)
      C[k] = A[i]; i++; k++;
    else \{ // by clause (6)
      C[k] = B[j]; j++; k++;
  } while (1);
```

Testing the iterative merging

```
Editor:
void showIArr(int A[], int n) {
  int i;
  for (i=0; i<n; i++) printf("%d ", A[i]);</pre>
 printf("\n");
}
int main() {
  int A[]={2, 5, 9, 23, 40};
  int B[]={1, 3, 4, 29, 55, 65, 68};
  int C[12];
  printf("after merging "); showIArr(A,5);
  printf("and "); showIArr(B,7);
  printf ("by mergeR "); mergeR(A, 5, 0, B, 7, 0, C, 0);
  showIArr(C, 12);
  printf ("by mergeI "); mergeI(A, 5, B, 7, C);
    a = T  a = 1 
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```

Results of test

Shell:

\$ make mergeSort ; ./mergeSort cc mergeSort.c -o mergeSort after merging 2 5 9 23 40 and 1 3 4 29 55 65 68 by mergeR 1 2 3 4 5 9 23 29 40 55 65 68 by mergeI 1 2 3 4 5 9 23 29 40 55 65 68



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Given array •

23 5 40 2 9 68 55 4 3 1 65 29



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- Given array 2 9 68 55 4 3 1 65 29 23 5 40
- Split given array into two parts



- Given array 2 9 68 55 4 3 1 23 5 40 65 29
- Split given array into two parts 23 5 40 2 9 68 55 4 3 65 29



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- Given array 2 9 68 55 4 3 1 23 5 40 65 29
- Split given array into two parts 40 2 9 68 23 5 55 43 65 29
- Sort first part



< A
- Given array 2 9 68 55 4 3 1 23 5 40 65 29
- Split given array into two parts 23 5 40 2 9 68 55 43 65 29
- Sort first part 2 5 9 23 40 68



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A.

- Given array 23 5 40 2 9 68 55 4 3 1 65 29
- Split given array into two parts 23 5 40 2 9 68 55 3 65 29 4
- Sort first part 2 5 9 23 68 40
- Sort second part



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- Given array 23 5 40 2 9 68 55 4 3 1 65 29
- Split given array into two parts 23 5 40 2 9 68 55 3 65 29 4
- Sort first part 2 5 9 23 40 68
- Sort second part 4 29 55 65 3



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- Given array 2 9 68 55 4 3 1 23 5 40 65 29
- Split given array into two parts 23 5 40 2 9 68 55 3 65 29 4
- Sort first part 2 9 40 68 23
- Sort second part 29 55 65 3 4
- After sorting the two parts:

First 2 5 9 23 40 68



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- Given array
 23 5 40 2 9 68 55 4 3 1 65 29
- Split given array into two parts
 23 5 40 2 9 68 55 4 3 1 65 29
- Sort first part
 2 5 9 23 40 68
- Sort second part
 1 3 4 29 55 65
- After sorting the two parts:

First 2 5 9 23 40 68 1 3 4 29 55 65 Second

Merge the two sorted sequences

A B > A B >

< A >

- Given array
 23 5 40 2 9 68 55 4 3 1 65 29
- Split given array into two parts
 23 5 40 2 9 68 55 4 3 1 65 29
- Sort first part
 2 5 9 23 40 68
- Sort second part
 1 3 4 29 55 65
- After sorting the two parts:

First 2 5 9 23 40 68 1 3 4 29 55 65 Second

 Merge the two sorted sequences merge (A, nA, B, nB, C)

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- Given array
 23 5 40 2 9 68 55 4 3 1 65 29
- Split given array into two parts
 23 5 40 2 9 68 55 4 3 1 65 29
- Sort first part
 2 5 9 23 40 68
- Sort second part
 1 3 4 29 55 65
- After sorting the two parts:

First 2 5 9 23 40 68 1 3 4 29 55 65 Second

- Merge the two sorted sequences merge (A, nA, B, nB, C)
- After merging the two sorted parts (the required result)

 2 3 4 5 9 23 29 40 55 65 68



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Algorithms

January 23, 2023

Recursive definition of mergesort

- N is the number of elements in A
- Array indices start from 0



Recursive definition of mergesort

- N is the number of elements in A
- Array indices start from 0

 $mergeSort(A, N, C) \\ = \begin{cases} \text{if } (N \le 1) \text{ then done} & (2.1) \\ \text{let } M = N/2 & (2.2) \\ \text{do mergeSort}(A, M, C) & (2.3) \\ \text{do mergeSort}(A + M, N - M, C) & (2.4) \\ \text{do merge}(A, M, A + M, N - M, C) & (2.5) \\ \text{do copyBack}(A, C, N) & (2.6) \end{cases}$



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Code for mergeSort

Editor:

}

```
void mergeSort(int A[], int N, int C[]) {
    int M;
    if (N<=1) return; // by clause (1)
    M = N/2; // by clause (2)
    mergeSort(A, M, C); // by clause (3)
    mergeSort(A + M, N - M, C); // by clause (4)
    mergeI(A, M, A + M, N - M, C); // by clause (5)
    copyBack(A, C, N); // by clause (6)</pre>
```

Code for mergeSort

Editor:

```
void mergeSort(int A[], int N, int C[]) {
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 mergeSort(A, M, C); // by clause (3)
 mergeSort (A + M, N - M, C); // by clause (4)
 mergeI(A, M, A + M, N - M, C); // by clause (5)
  copyBack(A, C, N); // by clause (6)
}
void copyBack(int A[], int C[], int N) {
  int i:
  for (i=0;i<N;i++) A[i]=C[i];</pre>
}
```

Merge sort

Testing mergeSort

Editor:

```
int main() {
    int A[]={23,5,40,2,9,68,55,4,3,1,65,29};
    int C[12];
    printf("after sorting by mergeSort ");
    mergeSort(A, 12, C);
    printf("\n"); showIArr(A,12);
return 0; }
```



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Results of testing mergeSort

Shell:

\$ make mergeSort ; ./mergeSort cc mergeSort.c -o mergeSort after sorting by mergeSort 1 2 3 4 5 9 23 29 40 55 65 68



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Complexity of mergesort

- $T(n) = T(n/2) + T(n/2) + \Theta(n) = 2T(n/2) + \Theta(n)$
- $T(0) = \Theta(1)$
- $T(n) = \Theta(n \lg n)$
- Given implementation requires extra storage space (equal to size of input)
- In-place version not trivial if O(N lg N) is to be preserved
- Simple in-place version to be studied next

Complexity of mergesort

- $T(n) = T(n/2) + T(n/2) + \Theta(n) = 2T(n/2) + \Theta(n)$
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- Given implementation requires extra storage space (equal to size of input)
- In-place version not trivial if O(N lg N) is to be preserved
- Simple in-place version to be studied next
- Mergesort was invented by John von Neumann in 1945



In-place merging

- *M* is number of elements in the first half of *A*
- N is the total number of elements in A
- Array indices start from 0
- Initial call: merge(A, M, N)

(4.1)



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In-place merging

- M is number of elements in the first half of A
- N is the total number of elements in A
- Array indices start from 0
- Initial call: merge(A, M, N)

```
mergeInPl(A, M, N)
```

- $= \begin{cases} \text{if } (M \le 0 \lor M \ge N \lor N \le 0) \text{ then done} & (4.2) \\ \text{else if } (A[0] \le A[M]) \text{ then mergeInPl}(A+1, M-1, N-1) & (4.3) \\ \text{else mergeInPl}(\text{cpySft}(A, M), M, N-1) & (4.4) \end{cases}$



(4.1)

In-place merging

- M is number of elements in the first half of A
- N is the total number of elements in A
- Array indices start from 0
- Initial call: merge(A, M, N)

```
mergeInPl(A, M, N)
```

- $= \begin{cases} \text{if } (M \le 0 \lor M \ge N \lor N \le 0) \text{ then done} & (4.2) \\ \text{else if } (A[0] \le A[M]) \text{ then mergelnPl}(A+1, M-1, N-1) & (4.3) \\ \text{else mergelnPl}(\text{cpySft}(A, M), M, N-1) & (4.4) \end{cases}$

Editor:

```
void mergeInPl(int A[], int M, int N) {
  if (M \le 0 or M \ge N or N \le 0) return;
  else if ( A[0] <= A[M] ) mergeInPl(A+1, M-1, N-1);
  else { // cpySft() is inlined
    int i, T = A[M];
    for (i=M; i; i--) A[i] = A[i-1];
   A[0] = T; mergeInPl(A+1, M-1, N-1);
  ]]
```

(4.1)

Analysing mergesort with in-place merging

$$T(n) = \begin{cases} a & n = 1\\ 2T\left(\frac{n}{2}\right) + bn + cn^2 + d & n > 1, n = 2^d, d \ge 0 \end{cases}$$



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Analysing mergesort with in-place merging

$$T(n) = \begin{cases} a & n = 1\\ 2T\left(\frac{n}{2}\right) + bn + cn^2 + d & n > 1, n = 2^d, d \ge 0 \end{cases}$$

Let *n* = 8



$$b \times \frac{n}{1} \times 1 + c \times \frac{n^2}{1^2} \times 1 + d \times 1$$

$$b \times \frac{n}{2} \times 2 + c \times \frac{n^2}{2^2} \times 2 + d \times 2$$

$$b \times \frac{n}{4} \times 4 + c \times \frac{n^2}{4^2} \times 4 + d \times 4$$

$$a \times 8$$

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Analysing mergesort with in-place merging

$$T(n) = \begin{cases} a & n = 1\\ 2T\left(\frac{n}{2}\right) + bn + cn^2 + d & n > 1, n = 2^d, d \ge 0 \end{cases}$$

Let n = 8



$$b \times \frac{n}{1} \times 1 + c \times \frac{n^2}{1^2} \times 1 + d \times 1$$

$$b \times \frac{n}{2} \times 2 + c \times \frac{n^2}{2^2} \times 2 + d \times 2$$

$$b \times \frac{n}{4} \times 4 + c \times \frac{n^2}{4^2} \times 4 + d \times 4$$

$$a \times 8$$

• $\lg n \times b \times n + (1 + \frac{1}{2} + \ldots + \frac{1}{2^{\lg n-1}}) \times c \times n^2 + (n-1) \times d + n \times a =$ $\lg n \times b \times n + 2 \times (1 - 2^{-\lg n}) \times c \times n^2 + (n-1) \times d + n \times a =$ $\lg n \times b \times n + 2 \times (\frac{n-1}{n}) \times c \times n^2 + (n-1) \times d + n \times a$

• Asymptotic bound: $T(n) \in \Theta(n^2)$

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Section outline

Quicksort

- Simple version of quicksort
- In-place Version of Quick Sort

- Worst and best cases of complexity of quicksort
- Average case complexity of quicksort
- Upper bound on harmonic series



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Simple version of quicksort

Partitioning Leading to Sorting

- 23 5 40 2 9 68 55 4 3 1 65 29 ۲
- Pick up any element p, say 9



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- 23 5 40 2 9 68 55 4 3 1 65 29 ۲
- Pick up any element p, say 9
- Partition all elements in the array into two sets,



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B b

- 23 5 40 2 9 68 55 4 3 1 65 29 ۲
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are ,

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A 34 b

- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set



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- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set
- First set 5 2 4 3 1

- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set
- First set 5 2 4 3 1

23 40 68 55 65 29 second set



- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set
- First set 5 2 4 3 1

23 40 68 55 65 29 second set

Sort first set

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- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set
- First set 5 2 4 3 1

• Sort first set

9



- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set





- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set



Sort second set



- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set



- 23 5 40 2 9 68 55 4 3 1 65 29
- Pick up any element p, say 9
- Partition all elements in the array into two sets, first set: elements that are p (> 9)
- Disregard ordering of elements within each set



Outline of Quicksort

- Given an array A of N elements
- Pick up a suitable element *p* from the array

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- Given an array A of N elements
- Pick up a suitable element p from the array
- Simple choice is to pick up the first element
- Partition the elements of A based on p
- Let first part be all elements
- Second part all elements > p

A B > A B >

- Given an array A of N elements
- Pick up a suitable element p from the array
- Simple choice is to pick up the first element
- Partition the elements of A based on p
- Let first part be all elements
- Second part all elements > p
- Sort the two parts (does not matter which part is sorted first)

- Given an array A of N elements
- Pick up a suitable element p from the array
- Simple choice is to pick up the first element
- Partition the elements of A based on p
- Let first part be all elements
- Second part all elements > p
- Sort the two parts (does not matter which part is sorted first)
- Now the whole of A is sorted

- Given an array A of N elements
- Pick up a suitable element p from the array
- Simple choice is to pick up the first element
- Partition the elements of A based on p
- Let first part be all elements
- Second part all elements > p
- Sort the two parts (does not matter which part is sorted first)
- Now the whole of A is sorted
- Quicksort was invented by Tony Hoare in 1960

4 B 6 4 B 6

- Elements are originally in an array A

 23
 5
 40
 2
 9
 68
 55
 4
 3
 1
 65
 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller

Larger



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- Elements are originally in an array A
 5 40 2 9 68 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller





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- Elements are originally in an array **A** 40 2 9 68 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5





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- Elements are originally in an array **A** 2 9 68 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5





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- Elements are originally in an array **A** 9 68 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2





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- Elements are originally in an array **A** 68 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2





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- Elements are originally in an array **A** 55 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array **B**: Smaller 5 2



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- Elements are originally in an array **A** 4 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array **B**: Smaller 5 2





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- Elements are originally in an array A
 3 1 65 29
- Let pivot element be 9
- Partitioning is done in another array **B**: Smaller 5 2 4





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- Elements are originally in an array A 1 65 29
- Let pivot element be 9
- Partitioning is done in another array **B**: Smaller 5 2 4 3





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- Elements are originally in an array A
 65 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2 4 3 1





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- Elements are originally in an array A
 29
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2 4 3 1





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4 E 5

- Elements are originally in an array A
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2 4 3 1





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(4) (E) (b)

- Elements are originally in an array A
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2 4 3 1 29 65 55 68 40 23 Larger 9

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4 E 5

- Elements are originally in an array A
- Let pivot element be 9
- Partitioning is done in another array B: Smaller 5 2 4 3 1
 9 29 65 55 68 40 23 Larger
- Need to be careful while partitioning to avoid getting into an infinite loop
- Can be ensured by getting out at least one copy of the pivot



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Recursive Definition of Simple Partitioning

- Assume that all elements are distinct
- *M* is the number of elements in *A*
- Array indices start from 0
- Initial call: simPartR(A, N, 0, B, -1, N, p)
- Last clause skips over the pivot
- At termination, pivot should be at B[j + 1], where it is explicitly assigned

(1.1)

B N 4 B N

Recursive Definition of Simple Partitioning

- Assume that all elements are distinct
- *M* is the number of elements in *A*
- Array indices start from 0
- Initial call: simPartR(A, N, 0, B, -1, N, p)
- Last clause skips over the pivot
- At termination, pivot should be at B[j + 1], where it is explicitly assigned

$$\begin{split} & \mathsf{simPartR}(A, N, i, B, j, k, p) \\ & = \begin{cases} & \text{if } (i \geq N) \text{ then } (j+1) \text{ st } B[j+1] = p & (1.2) \\ & \text{else if } (A[i] < p) \text{ then } \text{simPartR}(A, N, i+1, B, j+1, k, p) \\ & \text{st } B[j+1] = A[i] & (1.3) \\ & \text{else if } (A[i] > p) \text{ then } \text{simPartR}(A, N, i+1, B, j, k-1, p) \\ & \text{st } B[k-1] = A[i] & (1.4) \\ & \text{otherwise } \text{simPartR}(A, N, i+1, B, j, k-1, p) & (1.5) \end{cases}$$



(1.1)

Recursive Definition of Simple Partitioning

- Assume that all elements are distinct
- M is the number of elements in A
- Array indices start from 0
- Initial call: simPartR(A, N, 0, B, -1, N, p)
- Last clause skips over the pivot
- At termination, pivot should be at B[j + 1], where it is explicitly assigned

simPartR(
$$A, N, i, B, j, k, p$$
)

$$= \begin{cases} \text{ if } (i \ge N) \text{ then } (j+1) \text{ st } B[j+1] = p \quad (1.2) \\ \text{else if } (A[i] < p) \text{ then simPartR}(A, N, i+1, B, j+1, k, p) \\ \text{ st } B[j+1] = A[i] \quad (1.3) \\ \text{else if } (A[i] > p) \text{ then simPartR}(A, N, i+1, B, j, k-1, p) \\ \text{ st } B[k-1] = A[i] \quad (1.4) \\ \text{ otherwise simPartR}(A, N, i+1, B, j, k-1, p) \quad (1.5) \end{cases}$$

Definition is tail recursive

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(1.1)

Recursive Code for Simple Partitioning

Editor:

```
int simPartR(int A[], int N, int i,
              int B[], int j, int k, int p) {
  if (i >= N) {
   B[j+1] = p;
   return (j+1); // by clause (2)
  } else if (A[i] < p) {
   B[i+1] = A[i];
   return simPartR(A, N, i+1, B, j+1, k, p);
   // by clause (3)
  { else if (A[i] > p) {
   B[k-1] = A[i];
    return simPartR(A, N, i+1, B, j, k-1, p);
   // by clause (4)
  } else // by clause (5)
   return simPartR(A, N, i+1, B, j, k, p);
```

Recursive Definition of Simple Quick Sort

- N is the number of elements in A
- Array indices start from 0
- Recursive simple partitioning is used

Recursive Definition of Simple Quick Sort

- N is the number of elements in A
- Array indices start from 0
- Recursive simple partitioning is used

$$quickSimSort(A, N, B)$$

$$= \begin{cases} if (N \le 1) \text{ then done} (1.1) \\ let p = simPartR(A, N, 0, B, -1, N, A[0]) \\ do copyBack(A, B, N) (1.2) \\ do quickSimSort(A, p, B) (1.3) \\ do quickSimSort(A + p + 1, N - p - 1, B) (1.4) \end{cases}$$



Code for Simple Quick Sort

Editor:

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void quickSimSort(int A[], int N, int B[]) {
 int pPos;

```
if (N<=1) return;
pPos = simPartR (A, N, 0, B, -1, N, A[0]);
// printf("p=%d, pPos=%d, A[N=%d]: ", p, pPos, N);
// showIArr(A,N);
// pPos = simPartI (A, N, B, A[0]);
copyBack(A, B, N);
quickSimSort(A, pPos, B);
quickSimSort(A+pPos+1, N-pPos-1, B);
```

Simple version of quicksort

Result of running Simple Quick Sort

Editor:

```
int main() {
    int A[]={23,5,40,2,9,68,55,4,3,1,65,29};
    int B[12];
    quickSimSort(A, 12, B);
    printf("after sorting by quickSimSort \n\t");
    showIArr(A,12);
return 0; }
```

Shell:

Iterative Code for Simple Partitioning

Editor:

```
int simPartI(int A[], int N, int B[], int p) {
 int i=0, j=-1, k=N; // // by clause (1)
 for (;;) {
    if (i >= N) {
     B[j+1]=p;
     return (j+1); // by clause (2)
    else if (A[i] < p) {
     B[j+1] = A[i]; // by clause (3)
     i++; j++;
    else if (A[i] > p) {
     B[k-1] = A[i]; // by clause (4)
     i++; k--;
    } else i++; // by clause (5)
```

Code & Results for Simple Quick Sort

Editor:

```
void quickSimSort(int A[], int N, int B[]) {
    int pPos;
    if (N<=1) return;
    pPos = simPartI (A, N, B, A[0]);
    copyBack(A, B, N);
    quickSimSort(A, pPos+1, B);
    quickSimSort(A+pPos+1, N-pPos-1, B);
}</pre>
```

Shell:

- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:
 23 5 40 2 9 68 55 4 3 1 65 29



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:
 23 5 40 2 9 68 55 4 3 1 65 29 as 29@h > 9



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:
 23 5 40 2 9 68 55 4 3 1 65 29 as 65@h > 9



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:
 23 5 40 2 9 68 55 4 3 1 65 29 stuck, 23@I > 1@h



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- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:

1 5 40 2 9 68 55 4 3 23 65 29

after interchange

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



Algorithms

- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:

1 5 40 2 9 68 55 4 3 23 65 29

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



as 1@l < 9

Algorithms

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- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: as 5@| < 9

5 40 2 9 68 55 4 3 23 65 29

Invariant Elements to the left of the pivot are no smaller **Invariant** Elements to the right of the pivot are larger **Invariant** Comparison of elements in between not known


- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: as 23@h > 9

5 40 2 9 68 55 4 3 23 65 29



- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 40 2 9 68 55 4 3 23 65 29 stuck. 40@I > 3@h

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



Algorithms

- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 3 2 9 68 55 4 40 23 65 29 after interchange



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: 153296855440236529 as 3@I < 9

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



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Algorithms

- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: 153296855440236529 as 2@I < 9



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: 153296855440236529 as 40@h > 9



- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 3 2 9 68 55 4 40 23 65 29 stuck, 9@I > 4@h

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



CM and PB (IIT Kharagpur)

Algorithms

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- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 3 2 4 68 55 9 40 23 65 29 after interchange



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: 1 5 3 2 4 68 55 9 40 23 65 29 as 4@I < 9



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: 153246855940236529 stuck. 68@I > 9@h



- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 3 2 4 9 55 68 40 23 65 29 after interchange



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: as 68@h > 9

5 3 2 4 9 55 68 40 23 65 29

Invariant Elements to the left of the pivot are no smaller **Invariant** Elements to the right of the pivot are larger **Invariant** Comparison of elements in between not known



Algorithms

- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: as 55@h > 9

5 3 2 4 9 55 68 40 23 65 29



- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot: $15324 \cdot 9$ 556840236529 stuck. 9@I > 4@h



- Let pivot element be 9
- Elements in array A are they are partitioned using the pivot:
 1 5 3 2 4 9 55 68 40 23 65 29 as A[I]=A[h]

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



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Algorithms

- Let pivot element be 9
- Elements in array **A** are they are partitioned using the pivot:

 5 3 2 4 9 55 68 40 23 65 29 as A[I]=A[h], end as I > h
- Partitioning now terminates
- Skip over smaller elements on the left: 1++
- Skip over larger elements on the right: r -
- When A[1] == A[h] == p, skip from left: 1++
- Stuck if A[1]>=p, A[h]<=p, A[1]!=A[h]: interchange</p>
- Position of pivot element is (I-1) or (h) at termination

Invariant Elements to the left of the pivot are no smaller Invariant Elements to the right of the pivot are larger Invariant Comparison of elements in between not known



Algorithms

auckson in-place version of Quick Son

Code for Recursive In-place Partitioning

Editor:

```
int partitionR(int A[], int N, int l, int h, int p) {
  if (l > h) return (l-1);
  else if (A[l] < p) // skip smaller
    return partitionR(A, N, 1+1, h, p);
  else if (A[h] > p) // skip larger
    return partitionR(A, N, 1, h-1, p);
  else if (A[1]==A[h]) // A[1]==A[h]==p
  // only skip copy of p in the left part
    return partitionR(A, N, l+1, h, p);
  else { // stuck: A[1]>=p, A[h]<=p, A[1]!=A[h]</pre>
    int t=A[1]; A[1]=A[h]; A[h]=t;
    // after interchange: A[1]<p, A[h]>=p
    // if A[1] was p, then it is moved right
    return partitionR(A, N, l, h, p);
```

Code for Iterative In-place Partitioning

Editor:

```
int partitionI(int A[], int N, int p) {
  int l=0, h=N-1;
  for (;;) {
    if (l > h) return h; // instead of (l-1)
    else if (A[1] < p) l++;
    else if (A[h] > p) h--;
    else if (A[1]==A[h]) 1++;
    else {
      int t=A[1]; A[1]=A[h]; A[h]=t;
    }
```



Code for Quicksort with In-place Partitioning

Editor:

```
void quickSort(int A[], int N) {
    int pPos;
```

```
if (N<=1) return;
pPos = partitionR (A, N, 0, N-1, A[0]);
quickSort(A, pPos);
quickSort(A+pPos+1, N-pPos-1);
```

Editor:

```
void quickSort(int A[], int N) {
    int pPos;
```

```
if (N<=1) return;
pPos = partitionI (A, N, A[0]);
quickSort(A, pPos);
quickSort(A+pPos+1, N-pPos-1);
```

Testing Quick Sort

Editor:

```
int main() {
    int A[]={23,5,40,2,9,68,55,4,3,1,65,29};
    int B[12];
    quickSimSort(A, 12, B);
    printf("after sorting by quickSimSort \n\t");
    showIArr(A,12);
    quickSort(A, 12);
    printf("after sorting by quickSort \n\t");
    showIArr(A,12);
    return 0; }
```



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Results of Running Quick Sort

Shell:



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Worst and best cases of complexity of quicksort

Worst case Pivot is placed at one of the two ends

•
$$T(n) = T(n-1) + \Theta(n)$$

•
$$T(0) = \Theta(1)$$

•
$$T(n) = \Theta(n^2)$$

Best case Pivot is placed in the middle to generates sub-sroblem of the same size

• $T(n) = T(n/2) + T(n/2) + \Theta(n) = 2T(n/2) + \Theta(n)$ • $T(0) = \Theta(1)$

•
$$T(n) = \Theta(n \lg n)$$

About

- It is an in-place sorting algorithm
 - It is an unstable sorting algorithm elements of the same value may be re-orded
 - Worst case when the pivot element get place at one of the ends Happens when the array is already sorted



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Algorithms

Pivot may be anywhere with a uniform distribution



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A B > A B >

< A >

- Pivot may be anywhere with a uniform distribution
- $T(n) = \sum_{k=1}^{k=n} \Pr[p = k] \{cn + T(k-1) + T(n-k)\}$ with T(0) as a constant



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- Pivot may be anywhere with a uniform distribution
- $T(n) = \sum_{k=1}^{k=n} \Pr[p=k] \{cn + T(k-1) + T(n-k)\}$ with T(0) as a constant

•
$$T(n) = cn + \frac{1}{n} \sum_{k=1}^{k=n} \{T(k-1) + T(n-k)\} = cn + \frac{2}{n} \sum_{k=1}^{k=n} T(k-1)$$



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•
$$nT(n) = cn^2 + 2\sum_{k=1}^{k=n} T(k-1)$$



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•
$$nT(n) = cn^2 + 2\sum_{k=1}^{k=n} T(k-1)$$

•
$$(n-1)T(n-1) = c(n-1)^2 + 2\sum_{k=1}^{k=n-1} T(k-1)$$
, substituting $n-1$ for n



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, substituting $n-1$ for n

•
$$nT(n) - (n-1)T(n-1) = c(2n-1) + 2T(n-1)$$
, after substraction

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- Pivot may be anywhere with a uniform distribution
- $T(n) = \sum_{k=1}^{k=n} \Pr[p = k] \{cn + T(k-1) + T(n-k)\}$ with T(0) as a constant

•
$$T(n) = cn + \frac{1}{n} \sum_{k=1}^{k=n} \{T(k-1) + T(n-k)\} = cn + \frac{2}{n} \sum_{k=1}^{k=n} T(k-1)$$

•
$$nT(n) = cn^2 + 2\sum_{k=1}^{k=n} T(k-1)$$

•
$$(n-1)T(n-1) = c(n-1)^2 + 2\sum_{k=1}^{k=n-1} T(k-1)$$
, substituting $n-1$ for n

•
$$nT(n) - (n-1)T(n-1) = c(2n-1) + 2T(n-1)$$
, after substraction

•
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, substituting $n-1$ for n
• $nT(n) = (n-1)T(n-1) = c(2n-1) + 2T(n-1)$, after substraction

•
$$nT(n) = (n+1)T(n-1) + c(2n-1)$$

• $\frac{T(n)}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n}$

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• Let
$$S(n) = \frac{T(n)}{n+1}$$
, then $S(0) = \frac{T(0)}{1} = T(0)$ and

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- Pivot may be anywhere with a uniform distribution
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• $\frac{T(n)}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n}$

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$$S(n) \le S(n-1) + \frac{2c}{n} \le S(n-2) + \frac{2c}{n-1} + \frac{2c}{n} \le T(0) + \left(\frac{2c}{1} + \ldots + \frac{2c}{n}\right) = T(0) + 2cH_n$$

- Pivot may be anywhere with a uniform distribution
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$$T(n) = cn + \frac{1}{n} \sum_{k=1}^{k=n} \{T(k-1) + T(n-k)\} = cn + \frac{2}{n} \sum_{k=1}^{k=n} T(k-1)$$

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, substituting $n-1$ for n

•
$$nT(n) - (n-1)T(n-1) = c(2n-1) + 2T(n-1)$$
, after substraction

•
$$nI(n) = (n+1)I(n-1) + c(2n-1)$$

• $\frac{T(n)}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n+1} \le \frac{T(n-1)}{n} + \frac{2c}{n}$

• Let
$$S(n) = \frac{T(n)}{n+1}$$
, then $S(0) = \frac{T(0)}{1} = T(0)$ and

•
$$S(n) \le S(n-1) + \frac{2c}{n} \le S(n-2) + \frac{2c}{n-1} + \frac{2c}{n} \le T(0) + \left(\frac{2c}{1} + \dots + \frac{2c}{n}\right) = T(0) + 2cH_n$$

• Thus $T(n) \le (n+1)(T(0) + 2cH) \le (n+1)T(0) + 2c(n+1)[c(n+1)] \le O(n|c|n)$

Thus, $T(n) \le (n+1)(T(0) + 2cH_n) \le (n+1)T(0) + 2c(n+1)\lg(n+1) \in O(n\lg n)$ ۲

Upper bound on harmonic series

• Consider H_n where $n = 2^k - 1$

Now,

$$H_{n} = \underbrace{\frac{1}{1}}_{1} + \underbrace{\frac{1}{2} + \frac{1}{3}}_{2} + \underbrace{\frac{1}{4} + \frac{1}{5} + \frac{1}{6} + \frac{1}{7}}_{4} + \dots + \underbrace{\frac{1}{\frac{n+1}{2}} + \dots + \frac{1}{n-1} + \frac{1}{n}}_{2^{k-1}}$$

$$\leq \underbrace{\frac{1}{1}}_{1} + \underbrace{\frac{1}{2} + \frac{1}{2}}_{2} + \underbrace{\frac{1}{4} + \frac{1}{4} + \frac{1}{4} + \frac{1}{4}}_{4} + \dots + \underbrace{\frac{1}{\frac{n+1}{2}} + \dots + \frac{1}{\frac{n+1}{2}} + \frac{1}{\frac{n+1}{2}}}_{2^{k-1}}$$

$$= \underbrace{\frac{1}{2^{0}}}_{2^{0}} + \underbrace{\frac{1}{2^{1}} + \frac{1}{2^{2}}}_{2^{k}} + \dots + \underbrace{\frac{1}{2^{k-1}}}_{2^{k-1}}$$

$$= k$$

• Total number of terms $n = 1 + 2 + ... + 2^{k-1} = 2^k - 1$

• Also, $2^{k-1} = \frac{n+1}{2}$ and $\frac{1}{2^{k-1}} = \frac{1}{\frac{n+1}{2}}$

• Thus,
$$k = \lg(n+1)$$
 and $H_n \le k = \lg(n+1)$

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Quicksort with In-place Partitioning – Showing Details

Editor:

```
void quickSort(int A[], int N) {
    int pPos; int p;
```

```
if (N<=1) return;
printf("before partition: "); showIArr(A,N);
pPos = partitionI (A, N, p=A[0]);
printf(" after pPos =%3d: ", pPos);
showIArr(A,N); printf("\n");
quickSort(A, pPos);
quickSort(A+pPos+1, N-pPos-1);
```



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A Detailed Run of Quicksort

Shell:

```
$ make quickSort ; ./quickSort
cc quickSort.c -o quickSort
before partition: 23 5 40 2 23 9 68 55 4 3 1 65 29 23
after pPos = 8: 23 5 1 2 23 9 3 4 23 55 68 65 29 40
before partition: 23 5 1 2 23 9 3 4
after pPos = 7: 4 5 1 2 23 9 3 23
before partition: 4 5 1 2 23 9 3
after pPos = 3: 3 2 1 4 23 9 5
before partition: 3 2 1
after pPos = 2: 1 2 3
before partition: 1 2
after pPos = 0: 1 2
```

A Detailed Run of Quicksort (Contd.)

Shell:

```
before partition: 23 9 5
after pPos = 2: 5 9 23
before partition: 5 9
after pPos = 0:59
before partition: 55 68 65 29 40
after pPos = 2: 40 29 55 65 68
before partition: 40 29
after pPos = 1: 29 40
before partition: 65 68
after pPos = 0:6568
after sorting by quickSort
        1 2 3 4 5 9 23 23 23 29 40 55 65 68
```

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Faulty Partitioning

Editor:

```
int partitionI(int A[], int N, int p) {
    int l=0, h=N-1;
    for (;;) {
        if (l > h) return h;
        else if (A[l] <= p) l++;
        else if (A[h] > p) h--;
        else {
            int t=A[l]; A[l]=A[h]; A[h]=t;
        }
    }
}
```



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Details of a Faulty Run of Quicksort

Shell:

```
$ make guickSort ; ./guickSort
cc quickSort.c -o quickSort
before partition: 23 5 40 2 23 9 68 55 4 3 1 65 29 23
after pPos = 8: 23 5 23 2 23 9 1 3 4 55 68 65 29 40
before partition: 23 5 23 2 23 9 1 3
after pPos = 7: 23 5 23 2 23 9 1 3
before partition: 23 5 23 2 23 9 1
after pPos = 6: 23 5 23 2 23 9 1
before partition: 23 5 23 2 23 9
after pPos = 5: 235 232 239
before partition: 23 5 23 2 23
after pPos = 4: 23 5 23 2 23
before partition: 23 5 23 2
after pPos = 3: 23 5 23 2
```

Details of a Faulty Run of Quicksort (Contd.)

Editor:

<pre>before partition: after pPos = 2:</pre>		
<pre>before partition: after pPos = 1:</pre>		
<pre>before partition: after pPos = 2:</pre>		
<pre>before partition: after pPos = 1:</pre>		
<pre>before partition: after pPos = 0:</pre>		
after sorting by 23 5 23 2	quickSort 23 9 1 3 4 55 40 29 65 68	
		¥7.

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