# Problem Solving by Search

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## Search Frameworks

State space search Uninformed / Blind search Informed / Heuristic search Problem reduction search Game tree search Advances Memory bounded search Multi-objective search

Learning how to search

# State space search

## Basic Search Problem:

- Given: [S, s, O, G]where
  - S is the (implicitly specified) set of states
  - s is the start state
  - O is the set of state transition operators
  - G is the set of goal states
- To find a sequence of state transitions leading from s to a goal state

# 8-puzzle problem

## State description (S)

- Location of each of the eight tiles (and the blank)
- Start state (s)
  - The starting configuration (given)
- Operators (O)
  - Four operators, for moving the blank left, right, up or down
- Goals (G)
  - One or more goal configurations (given)

## 8-queens problem

Placing 8 queens on a chess board, so that none attacks the other

#### Formulation – I

- A state is any arrangement of 0 to 8 queens on board
- Operators add a queen to any square

## 8-queens problem

#### Formulation – II

- A state is any arrangement of 0-8 queens with none attacked
- Operators place a queen in the left-most empty column

## 8-queens problem

#### Formulation – III

 A state is any arrangement of 8 queens, one in each column

 Operators move an attacked queen to another square in the same column

# Missionaries and cannibals

Three missionaries and three cannibals are on one side of a river, along with a boat that can hold one or two people. Find a way to get everyone to the other side, without ever leaving a group of missionaries outnumbered by cannibals

# **Missionaries and cannibals**

State: (#m, #c, 1/0)

- #m: number of missionaries in the first bank
- #c: number of cannibals in the first bank
- The last bit indicates whether the boat is in the first bank.

 Start state: (3, 3, 1) Goal state: (0, 0, 0)
 Operators: Boat carries (1, 0) or (0, 1) or (1, 1) or (2, 0) or (0, 2)

# Outline of a search algorithm

- 1. Initialize: Set OPEN = {s}
- **2. Fail:**

If OPEN = { }, Terminate with failure

- **3. Select:** Select a state, n, from OPEN
- 4. Terminate:

If  $n \in G$ , terminate with success

5. Expand:

Generate the successors of n using O and insert them in OPEN

6. Loop: Go To Step 2.

# Basics of the search algorithm

OPEN is a queue (FIFO) vs a stack (LIFO)
Is this algorithm guaranteed to terminate?
Under what circumstances will it terminate?

# Complexity

b: branching factor d: depth of the goal Breadth-first search: • Time:  $1 + b + b^2 + b^3 + ... + b^d = O(b^d)$ Space: O(b<sup>d</sup>) Depth-first search: **O(b<sup>m</sup>)**, ◆ Time: where m: depth of state space tree Space: O(bm)

# Tradeoff between space and time

 Iterative deepening
 Perform DFS repeatedly using increasing depth bounds
 Works in O(b<sup>d</sup>) time and O(bd) space

#### Bi-directional search

- Possible only if the operators are reversible
- Works in O(b<sup>d/2</sup>) time and O(b<sup>d/2</sup>) space

# Saving the explicit space

- 1. Initialize: Set OPEN = {s}, CLOSED = { }
- 2. Fail: If OPEN = { },
- Terminate with failure3. Select:Select a state, n, from OPEN and<br/>save n in CLOSED
- 4. Terminate: If  $n \in G$ , terminate with success
- **5.** Expand:

Generate the successors of n using O. For each successor, m, insert m in OPEN only if m  $\notin$  [OPEN  $\cup$  CLOSED]

6. Loop: Go To Step 2.

# Search and Optimization

- Given: [S, s, O, G]
- To find:
  - A minimum cost sequence of transitions to a goal state
  - A sequence of transitions to the minimum cost goal
  - A minimum cost sequence of transitions to a min cost goal

# **Uniform Cost Search**

This algorithm assumes that all operators have a cost:

- 1. Initialize: Set OPEN = {s}, CLOSED = { } Set C(s) = 0
- 2. Fail: If OPEN = { }, Terminate & fail
- 3. Select:

Select the minimum cost state, n, from OPEN and save n in CLOSED

4. Terminate:

If  $n \in G$ , terminate with success

## **Uniform Cost Search**

5. Expand:

Generate the successors of n using O. For each successor, m: If m ∉[OPEN ∪ CLOSED] Set C(m) = C(n) + C(n,m)and insert m in OPEN If  $m \in [OPEN \cup CLOSED]$ <u>Set C(m)</u> = min {C(m), C(n) + C(n,m)} If C(m) has decreased and  $m \in CLOSED$ , move it to OPEN

# Searching with costs

If all operator costs are positive, then the algorithm finds the minimum cost sequence of transitions to a goal.

No state comes back to OPEN from CLOSED

If operators have unit cost, then this is same as BFS

What happens if negative operator costs are allowed?

## Branch-and-bound

 Initialize: Set OPEN = {s}, CLOSED = { }. Set C(s) = 0, C\* = ∞
 Terminate: If OPEN = { }, then return C\*
 Select: Select a state, n, from OPEN and save in CLOSED
 Terminate: If n ∈ G and C(n) < C\*, then Set C\* = C(n) and Go To Step 2.

#### **Branch-and-bound**

- **Expand**: 5. If C(n) < C\* generate the successors of n For each successor, m: If m ∉[OPEN ∪ CLOSED] Set C(m) = C(n) + C(n,m) and insert m in **OPEN** If  $m \in [OPEN \cup CLOSED]$ **Set**  $C(m) = min \{C(m), C(n) + C(n,m)\}$ If C(m) has decreased and  $m \in CLOSED$ , move it to OPEN
- 6. Loop: Go To Step 2.