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# Time Complexity

## CS60001: Foundations of Computing Science

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# Measuring Complexity

## □ Definition

- Let  $M$  be a deterministic Turing machine that halts on all inputs. The *running time* or *time complexity* of  $M$  is the function  $f: \mathcal{N} \rightarrow \mathcal{N}$ , where  $f(n)$  is the running time of  $M$ , we say that  $M$  runs in time  $f(n)$  and that  $M$  is an  $f(n)$  time Turing machine. Customarily we use  $n$  to represent the length of the input

## □ Complexity Analysis

- Worst-case Analysis
  - Longest running time of all inputs of a particular length
- Average-case Analysis
  - Average of all the running times of inputs of a particular length

# Big-O and Small-o Notations

## □ Asymptotic Upper Bound ( $O$ )

- Let  $f$  and  $g$  be functions  $f, g: \mathcal{N} \rightarrow \mathcal{R}^+$ . Say that  $f(n) = O(g(n))$  if positive integers  $c$  and  $n_0$  exist such that for every integer  $n \geq n_0$

$$f(n) \leq c.g(n)$$

- When  $f(n) = O(g(n))$  we say that  $g(n)$  is an upper bound for  $f(n)$ , or more precisely, that  $g(n)$  is an asymptotic upper bound for  $f(n)$ , to emphasize that we are suppressing constant factors

## □ Asymptotic Strict-Upper Bound ( $o$ )

- Let  $f$  and  $g$  be functions  $f, g: \mathcal{N} \rightarrow \mathcal{R}^+$ . Say that  $f(n) = o(g(n))$  if

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$$

- In other words,  $f(n) = o(g(n))$  means that, for any real number  $c > 0$ , a number  $n_0$  exist, where  $f(n) < c.g(n)$  for all  $n \geq n_0$

# Analyzing Algorithms

- Let  $t: \mathcal{N} \rightarrow \mathcal{R}^+$  be a function. Define the *time complexity class*,  $TIME(t(n))$ , to be the collection of all languages that are decidable by an  $O(t(n))$  time Turing machine
  
- **Example**
  - Analyze the TM algorithm for the language  $\mathcal{A} = \{0^k 1^k \mid k \geq 0\}$
  - There can be different TM constructions ( $M_1, M_2, M_3$ ) deciding the language [see Sipser's Book, pp. 207-209]
  - The total-time taken by them is different
    - $M_1$  decides  $\mathcal{A}$  in time  $O(n^2)$ , therefore  $\mathcal{A} \in TIME(n^2)$
    - $M_2$  decides  $\mathcal{A}$  in time  $O(n \log n)$ , therefore  $\mathcal{A} \in TIME(n \log n)$
    - $M_3$  decides  $\mathcal{A}$  in time  $O(n)$ , therefore  $\mathcal{A} \in TIME(n)$

# Complexity Relationships among Models

## □ Definition

- Let  $N_{TM}$  be a non-deterministic Turing machine that is a decider. The running time of  $N_{TM}$  is the function  $f: \mathcal{N} \rightarrow \mathcal{N}$ , where  $f(n)$  is the maximum number of steps that  $N_{TM}$  uses on any branch of its computation on any input  $n$

## □ Theorems

- Let  $t(n)$  be a function, where  $t(n) \geq n$ . Then every  $t(n)$  time multi-tape Turing machine has an equivalent  $O(t^2(n))$  time single-tape Turing machine
- Let  $t(n)$  be a function, where  $t(n) \geq n$ . Then every  $t(n)$  time non-deterministic single-tape Turing machine has an equivalent  $2^{O(t(n))}$  time deterministic single-tape Turing machine

# The Class P (Polynomial Time)

## □ Definition

- $P$  is the class of languages that are decidable in polynomial time on a deterministic single-tape Turing machine. In other words,

$$P = \bigcup_k \text{TIME}(n^k)$$

## □ The role of P in theory:

- $P$  is invariant for all models of computation that are polynomially equivalent to the deterministic single-tape Turing machine
- $P$  roughly corresponds to the class of problems that are realistically solvable on a computer

## □ Examples of Problems in P

- $\text{PATH} = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t \}$
- $\text{RELATIVE\_PRIME} = \{ \langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime} \}$
- Every **context-free language** is a member of  $P$

# The Class NP (Non-deterministic Polynomial Time)

## □ Definitions

- A **verifier** for a language  $\mathcal{A}$  is an algorithm  $V$ , where

$$\mathcal{A} = \{w \mid V \text{ accepts } \langle w, c \rangle \text{ for some string } c\}.$$

We measure the time of a verifier only in terms of the length of  $w$ , so a **polynomial time verifier** runs in polynomial time in the length of  $w$ .

- A language  $\mathcal{A}$  is **polynomially verifiable** if it has a polynomial time verifier.
- **NP** is the class of languages that have polynomial time verifiers

## □ Examples of Problems in NP

- **HAM\_PATH** =  $\{\langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t\}$
- **COMPOSITES** =  $\{x \mid x = pq, \text{ for integers } p, q > 1\}$
- **CLIQUE** =  $\{\langle G, k \rangle \mid G \text{ is an undirected graph with } k\text{-clique}\}$
- **SUBSET-SUM** =  $\{\langle S, t \rangle \mid S = \{x_1, x_2, \dots, x_k\} \text{ and for some } \{y_1, y_2, \dots, y_l\} \subseteq \{x_1, x_2, \dots, x_k\}, \text{ we have } \sum y_i = t\}$

# The Class NP (contd...)

## □ Theorem

- A language is in **NP** if and only if it is decided by some non-deterministic polynomial time Turing machine

## □ Definition

- Non-deterministic time complexity class is defined as,

$$\text{NTIME}(t(n)) = \{L \mid L \text{ is a language decided by a } O(t(n)) \text{ time non-deterministic Turing machine}\}$$

## □ Corollary:

$$\text{NP} = \bigcup_k \text{NTIME}(n^k)$$

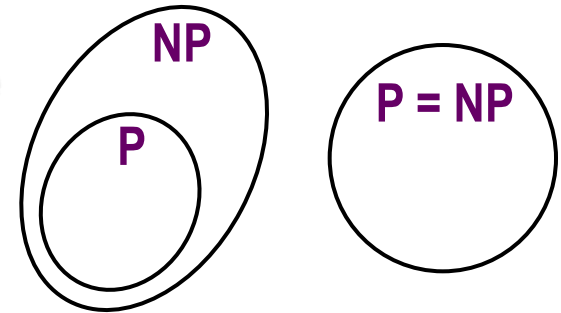


# The P Versus NP Question

- Referring (loosely) to polynomial time solvable as solvable “quickly”,
  - $P$  = the class of languages for which membership can be decided quickly
  - $NP$  = the class of languages for which membership can be verified quickly

- Unsolved Problem in Theoretical Computer Science

- $P = NP?$  OR  $P \neq NP?$
- One of these two possibilities is correct →



- Best method known for solving languages in  $NP$  deterministically uses exponential time. In other words, we can prove that

$$NP \subseteq \text{EXPTIME} = \bigcup_k \text{TIME}(2^{nk})$$

But, we do not know whether  $NP$  is contained in a smaller deterministic time complexity class

# NP-Completeness

## □ Polynomial Time Reducibility

- A function  $f: \Sigma^* \rightarrow \Sigma^*$  is a *polynomial time computable* function if some polynomial time Turing machine  $M$  exists that halts with just  $f(w)$  on its tape, when started on any input  $w$
- Language  $\mathcal{A}$  is *polynomial time mapping reducible*, or simply *polynomial time reducible*, to language  $\mathcal{B}$ , written  $\mathcal{A} \leq_p \mathcal{B}$ , if a polynomial time computable function  $f: \Sigma^* \rightarrow \Sigma^*$  exists, where for every  $w$ ,

$$w \in \mathcal{A} \Leftrightarrow f(w) \in \mathcal{B}$$

The function  $f$  is called the *polynomial time reduction* of  $\mathcal{A}$  to  $\mathcal{B}$

## □ Theorem

- If  $\mathcal{A} \leq_p \mathcal{B}$  and  $\mathcal{B} \in \mathcal{P}$ , then  $\mathcal{A} \in \mathcal{P}$
- **3SAT** is polynomial time reducible to **CLIQUE**

# NP-Completeness (contd...)

## □ Definition

- A language  $\mathcal{B}$  is **NP-complete** if it satisfies two conditions:
  - $\mathcal{B}$  is in  $NP$ , and
  - Every  $\mathcal{A}$  in  $NP$  is polynomial time reducible to  $\mathcal{B}$

## □ Theorems

- If  $\mathcal{B}$  is NP-complete and  $\mathcal{B} \in P$ , then  $P = NP$
- If  $\mathcal{B}$  is NP-complete and  $\mathcal{B} \leq_p \mathcal{C}$  for  $\mathcal{C}$  in  $NP$ , then  $\mathcal{C}$  is NP-complete

## □ COOK-LEVIN's Theorem

- **SAT** is NP-complete (other form:  $SAT \in P$  if and only if  $P = NP$ )
- **Corollary: 3SAT** is NP-complete

# Additional NP-Complete Problems

## □ Examples of NP-complete Problems

- **CLIQUE** =  $\{ \langle G, k \rangle \mid G \text{ is an undirected graph with } k\text{-clique} \}$
- **VERTEX-COVER** =  $\{ \langle G, k \rangle \mid G \text{ is an undirected graph that has a } k\text{-node vertex cover} \}$
- **HAM\_PATH** =  $\{ \langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t \}$
- **UHAM\_PATH** = Hamiltonian path in undirected graph
- **SUBSET-SUM** =  $\{ \langle S, t \rangle \mid S = \{x_1, x_2, \dots, x_k\} \text{ and for some } \{y_1, y_2, \dots, y_l\} \subseteq \{x_1, x_2, \dots, x_k\}, \text{ we have } \sum y_i = t \}$