



CS31001 COMPUTER ORGANIZATION AND ARCHITECTURE

Debdeep Mukhopadhyay,
CSE, IIT Kharagpur



Assembler

Steps in Transforming an Assembly Language

- ❑ Assembly languages have been developed that allow the use of symbolic names for instructions and memory locations.
- ❑ Assemblers convert instruction sequences in assembly languages to machine language.
- ❑ Assemblers accept numbers in a variety of simple and natural representations, and automatically convert them to required machine formats.
- ❑ Further, assemblers allow pseudo-instructions and macros.

Linkers and Loaders

- ❑ Multiple program modules are assembled independently.
- ❑ They, along with the library routines are linked subsequently by the linker.
- ❑ The linked routine forms a complete executable program which is then loaded to the memory.

Simulators

- ❑ Instead of loading the machine language instructions, they are often interpreted by a simulator.
- ❑ It examines each instructions, and carries out its functions by updating variables and data structures, that correspond to registers, and other machine parts.
- ❑ These simulators are needed in the design phase.

The assembly process

- ❑ Two passes exist.
- ❑ First pass: main function is to construct a symbol table.
- ❑ A symbol is a string of characters that is used as an instruction label.
- ❑ As instructions are read, the assembler maintains an instruction location counter that determines the relative position of the instruction.
- ❑ It is assumed that the program is loaded in a memory with address 0.
- ❑ There is also an additional relocation information produced by the assembler, which is used by the loader according to the eventual location in memory.

Example

- check: `beq $t0,$t1,loop`
- The assembler detects the operation symbol, “beq”
- The register symbols, \$t0 and \$s0 are also read.
- The labels “check” and “loop” are also read.
- However if “loop” refers to an backward memory location, it already exists in the symbol table.
- Else, we put it in the symbol table with its location blank.
- We solve these missing locations in a second pass.

Assembler Directives

- Provides the assembler with information on how to translate the program but does not themselves lead to the generation of machine instructions.
 - may specify the layout of data in the program’s data segment
 - define variables with symbolic names and desired initial values
- Assembler reads this directives and takes them while executing the rest of the programs.

Some examples

```
,macro                #start macro
.end_macro            #end macro
.text                 #start program's text segment
...
.data                 #start program's data segment
tiny: .byte 156, 0x7a #name and initialize data byte(s)
max: .word 1000000    #name and initialize data words(s)
small: float 2E-3     #name short float
big: .double 2E-3     #name long float
    .align 2          #align next item on word boundary
array: .space 600     #reserve space for 150 words
str1: .ascii "a*b"    #name and initialize ASCII string
str2: .asciiz "xyz"   #null-terminated ASCII string
.global main         #consider main as a global name
```

The .byte directive

- tiny .byte 156 0x7a
 - a byte holding 156 followed by a second byte containing 0x7a
 - tiny(\$s0), refer to the first byte if \$s0 is 0, second byte if \$s0 is 1 and so on.
- The directives .word, .float and .double are similar, except that they define words, short float, and long float respectively
- .float f1,..., fn Store the *n* floating-point single precision numbers (32 bits) in successive memory locations.
- double is for double precision (64 bits)

Pseudo-instructions

- Pseudo-instructions allow us to formulate computations and decisions in alternative forms not directly supported by hardware.
- The assembler takes care of translating these to basic hardware supported instructions.
- Example: MIPS lacks a logical NOT instruction.
 - same effect can be achieved by **nor \$s0,\$s0,\$zero**

The abs instruction

- Some pseudo-instructions need more than one instruction.
- **abs \$t0,\$s0 #put |\$s0| into \$t0**
- The assembler translates this into:
 - add \$t0,\$s0,\$zero**
 - slt \$at,\$t0,\$zero**
 - beq \$at,\$zero,+4**
 - sub \$t0,\$zero,\$s0**



Some conversions

- `neg $t0,$s0: sub $t0,$zero,$s0`
- `rem $t0,$s0,$s1: div $s0,$s1
mfhi $t0`
- `li $t0,imm:`
 - `addi $t0,$zero,imm` #if imm fits in 16 bits
 - `lui $t0,upperhalf` #if imm needs 32 bits
`ori $t0,lowerhalf`
- `blt $s0,$s1,label`
 - `slt $at,$s0,$s1`
 - `bne $at,$zero,label`

Macro-instructions

- A mechanism to give a name to an often used sequence of instructions (helps like a short form).
- `.macro(arg list)`
...
`.end_macro`

Two important points

- How is a macro different from a pseudo-instruction?
 - Pseudo-instructions are a part of the assembler design. They are fixed for a user. On the other hand, macros are user defined.
 - Further, a pseudo-instruction looks exactly like an instruction. We can say by looking that `move/not/li/la` are pseudo-instructions. But a macro is more like a high level language code.

The other question.

- How is a macro different from a procedure?
 - A procedure execution takes place by at least two jump instructions (jal and jr).
 - A macro is just a short hand for several lines of assembly.
 - The macro is replaced by the assembler with the equivalent lines of code for each time the macro is called.
 - After that there is no trace of macro in the final assembly.

Example

- Determine the largest of three values in registers and put the result in a fourth register. Write a macro for this.

```
.macro max3reg(m,a1,a2,a3)
    move m,a1
    bge m,a2,+4
    move m,a2
    bge m,a3,+4
    move m,a3
.end_macro
```

When the macro is used like

`max3reg($t0,$s0,$s4,$s3)`, the assembler simply replaces the arguments `m,a1,a2`, and `a3` in the text of the macro with these registers.