

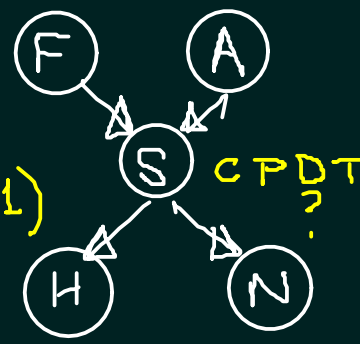
Expectation-Maximization:

SUMMARY

① Bayes Net: Fully Known
Data: Fully Observed

$$\theta_{s|ij} = P(S=1 | F=i, A=j)$$

$$= \frac{\sum_k \delta(f_k=i, a_k=j, S_k=1)}{\sum_k \delta(f_k=i, a_k=j)}$$



$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} [P[\text{Data}|\theta]]$$

MLE

② Bayes Net: Known
Data: Partially Obs.

→ E-step: $\operatorname{Exp}[Z | X, \theta]$

unobserved (pointing to Z) / observed (pointing to X)

$$\hat{\theta}' = \underset{\theta'}{\operatorname{argmax}} Q(\theta', \theta)$$

→ M-step: $Q(\theta', \theta) = E_{Z|X, \theta} \log[P(X, Z | \theta')]$

current M-step (pointing to the expectation operator)

↳ Bayesian Classifiers

↳ Unsupervised Learning

→ Clustering (where all o/p labels ??)

→ Gaussian Mixture Models:

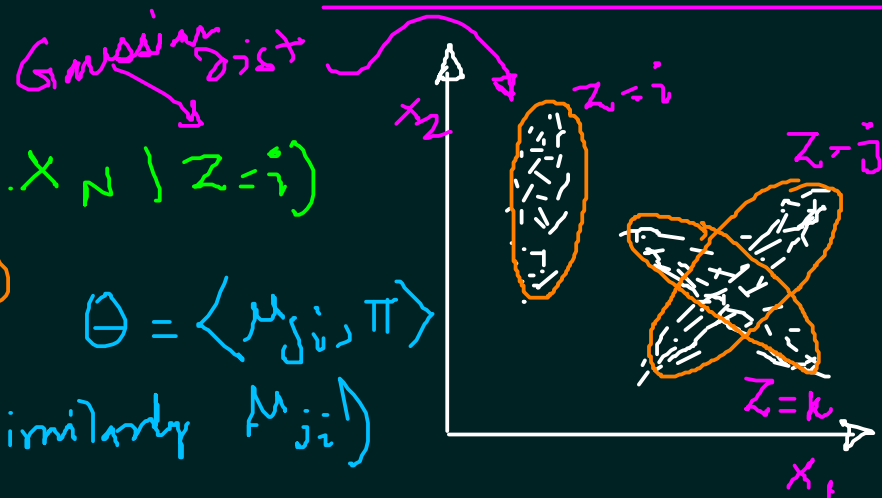
$$P(x_1, \dots, x_N) = \sum_i P(Z=i) P(x_1, \dots, x_N | Z=i)$$

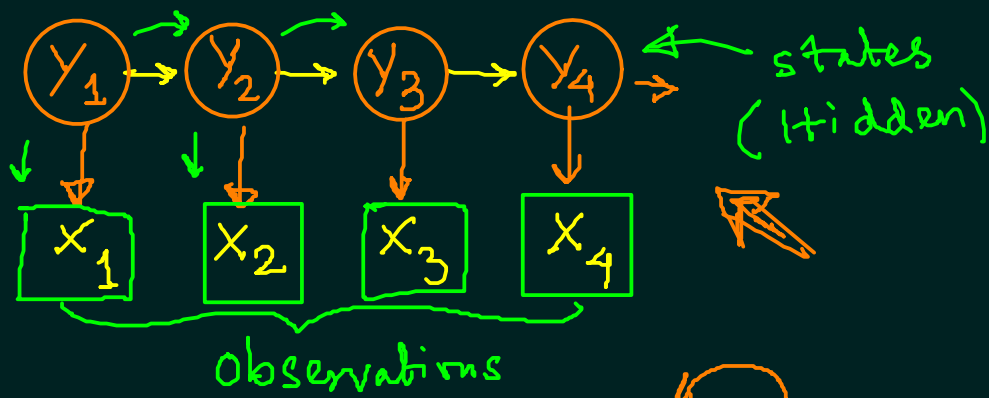
$$\sim \mathcal{N}(\mu_{ji}, \sigma)$$

→ E-step: $P(Z^{(n)} | x^{(n)}, \theta)$

$$\theta = \langle \mu_{ji}, \pi \rangle$$

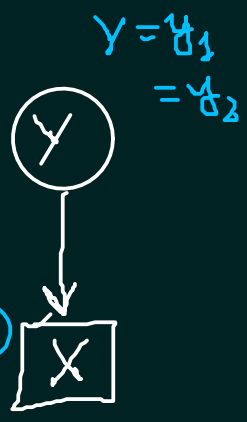
→ M-step: $\pi \leftarrow \frac{1}{N} \sum_n E[Z^{(n)}]$... (similarly μ_{ji})





Hidden Markov Models

(i) $Y \sim$ multinomial Distribution



(ii) $X|Y \sim$ Gaussian (cont) Distribution
 Multinomial (Discrete)

Markov process: $P(Y_{t+1} | Y_t, Y_{t-1}, \dots, Y_1)$
 $= P(Y_{t+1} | Y_t)$

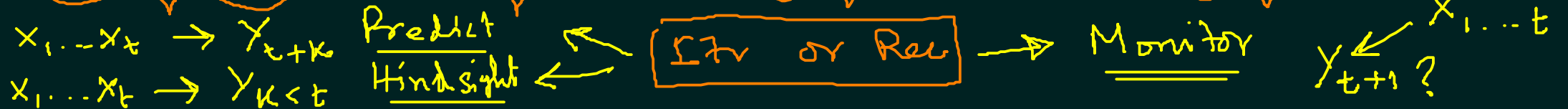
(ii)

HMM

- Initial distribution: $P(Y_t)$ ← Prior [multinomial]
- Transition dist: $P(Y_t | Y_{t-1}) \sim$ multinomial
- Emission dist: $P(X_t | Y_t)$
 - Gaussian (cont)
 - Multinomial (discrete)

Ex: $P(Y_{1 \dots t} X_{1 \dots t}) \Rightarrow$ JPDT

$$P(Y_{1 \dots t} X_{1 \dots t}) = P(Y_1) \prod_{i=1}^{t-1} P(Y_{i+1} | Y_i) \cdot \prod_{i=1}^t P(X_i | Y_i)$$



Monitoring: M^t $P(Y_t | X_1 \dots t) \propto P(x_t | y_t, x_1 \dots t-1) P(y_t | x_1 \dots t-1)$

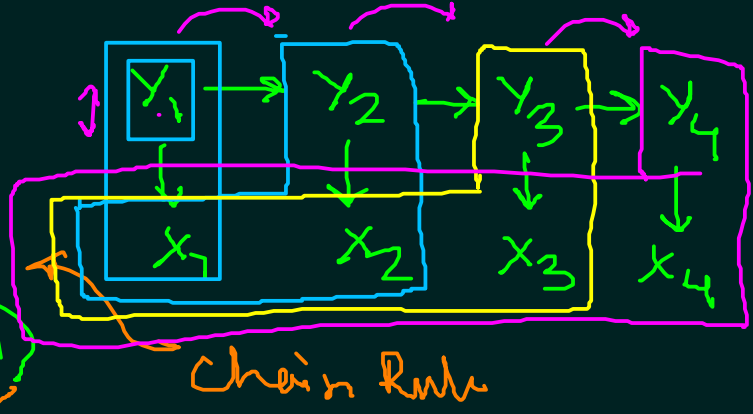
$= P(x_t | y_t) \cdot \sum_{y_{t-1}} P(y_t, y_{t-1} | x_1 \dots t-1)$

↑ Cond. Indep

← Bayes Theorem

$= P(x_t | y_t) \cdot \sum_{y_{t-1}} P(y_t | y_{t-1}, x_1 \dots t-1) \cdot P(y_{t-1} | x_1 \dots t-1)$

marginal



$= P(x_t | y_t) \sum_{y_{t-1}} P(y_t | y_{t-1}) M^{(t-1)}$

Rec

Monitoring

(Forward - Algo)

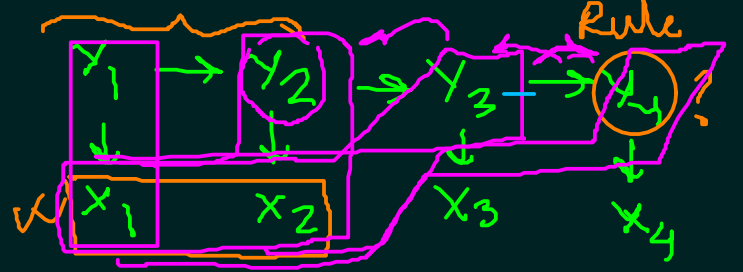
Prediction: P^k $P(y_{t+k} | x_1 \dots t)$ (where $k > 1$)

$= \sum_{y_{t+k-1}} P(y_{t+k}, y_{t+k-1} | x_1 \dots t)$ ← marginal

Forward also

$= \sum_{y_{t+k-1}} P(y_{t+k} | y_{t+k-1}, x_1 \dots t) \cdot P(y_{t+k-1} | x_1 \dots t)$ ← chain rule

$= \sum_{y_{t+k-1}} P(y_{t+k} | y_{t+k-1}) P^{(k-1)}$

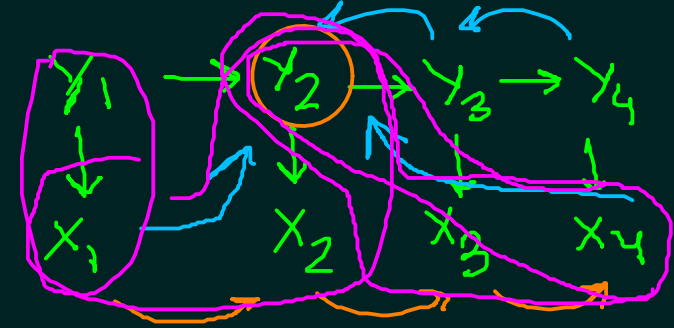


Hindsight:

$$P(Y_k | X_1 \dots t) \quad \boxed{k < t}$$

$$= P(Y_k \times_{k+1 \dots t} | X_1 \dots k) \quad \leftarrow \text{Cond. Ind. ?}$$

$$\stackrel{\text{Fwd}}{=} \underbrace{P(Y_k | X_1 \dots k)}_{M^k} \cdot \underbrace{P(X_{k+1} \dots t | Y_k)}_{I^k} \quad \leftarrow \text{Chain Rule}$$



$$P(Y_k | X_1 \dots k, X_{k+1} \dots t) = P(Y_k \otimes | X_1 \dots k)$$

$$\Rightarrow P(X_{k+1} \dots t | Y_k)$$

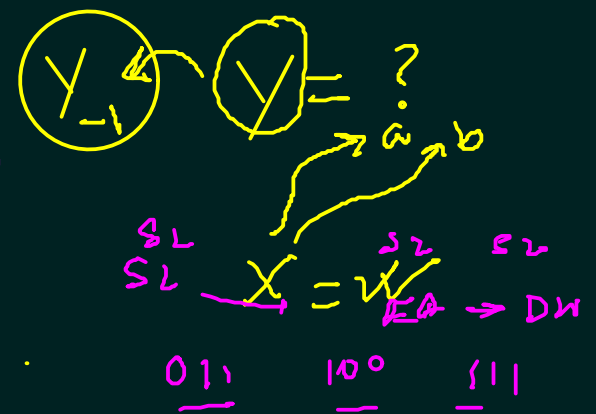
$$= \sum_{Y_{k+1}} P(Y_{k+1}, X_{k+1} \dots t | Y_k) \quad \leftarrow \text{marginals}$$

$$= \sum_{Y_{k+1}} P(Y_{k+1} | Y_k) \cdot \underbrace{P(X_{k+1} | Y_{k+1}) \cdot P(X_{k+2} \dots t | Y_{k+1})}_{I^{k+1}} \quad \leftarrow \text{Chain Rule}$$

↳ Forward-Backward Algo.

$$\rightarrow \max_{Y_1 \dots t} P(Y_1 \overset{abrac}{} \dots t | X_1 \dots t)$$

most likely exp.

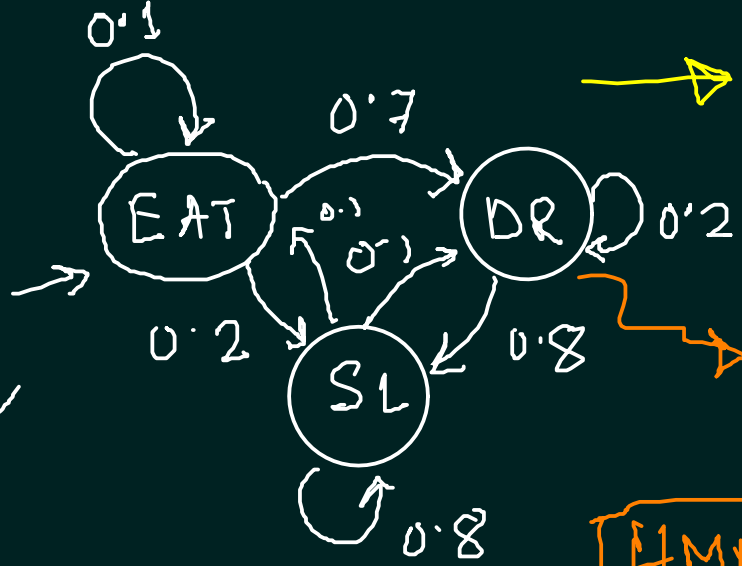
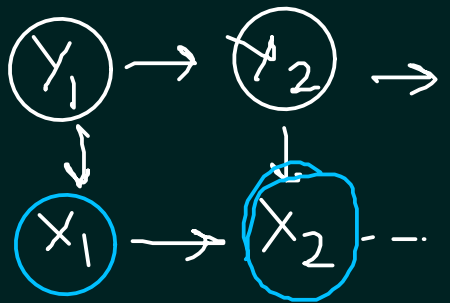


$$\max_{y_{1..t}} P(y_{1..t} | x_{1..t}) = \max_{y_t} P(x_t | y_t) \cdot \max_{y_{1..t-1}} P(y_{1..t-1} | x_{1..t-1})$$

(Dynamic Prog.)

→ Viterbi Algo

$y_1 = a?$ → $y_2 = a?$ → $x_3 = a?$
 $y_1 = b?$ → $y_2 = b?$ → $y_3 = b?$



\downarrow $P(x_1=0)$ $P(x_2=1)$
 \downarrow \downarrow

$P(x_1 | DR) = ?$
 $P(x_2 | DR) = ?$

HMM

→ Exp } (EM)
 → Max }

$P(y)$ ✓
 $P(y_t | x_{t+1})$ ✓
 $P(x_t | x_t)$ ✓

(Partial Files) } MLE