

SUMMARY

▶ VC-Dimension and Theory of Generalization:

$$E_{out} \approx 0 \Rightarrow \underbrace{(E_{in} \approx 0)}_{\text{learning algorithms}} + \underbrace{(E_{in} \approx E_{out})}_{\text{theory of generalization}}$$

$$\rightarrow \text{Prob} [|E_{in}(g) - E_{out}(g)| > \underline{\epsilon}] \leq \frac{4 \cdot m_{\mathcal{H}}(2N) \cdot e^{-\frac{1}{8} \epsilon^2 N}}{\delta}$$

where, Growth function $m_{\mathcal{H}}(N) \leq \sum_{i=0}^{k-1} \binom{N}{i}$ with break point k

$$\boxed{m_{\mathcal{H}}(N) = O(N^{d_{vc}})} \Rightarrow m_{\mathcal{H}}(N) \leq \sum_{i=0}^{d_{vc}} \binom{N}{i} \text{ as } d_{vc} = k - 1$$

→ Generalization Bound: PAC

Ex: d -dimensional Perceptron ($d_{vc} = d + 1$)

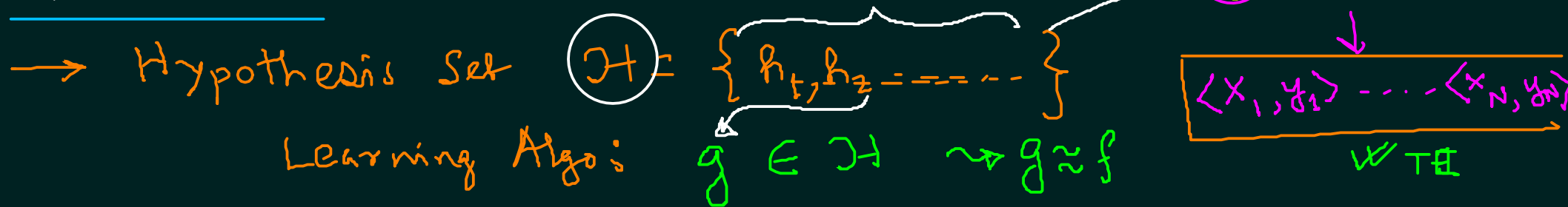
With probability / confidence $\geq 1 - \delta$ we find, $E_{out} - E_{in} \leq \epsilon$

$$\epsilon = \sqrt{\frac{8}{N} \ln \left(\frac{4m_{\mathcal{H}}(2N)}{\delta} \right)}$$

$N \geq 10 d_{vc}$
Practical EMP

$$\hookrightarrow E_{out} \leq E_{in} + \underbrace{\Omega(N, \mathcal{H}, \delta)}_{\text{Generalization Bound}}$$

Approximation vs. Generalization:



▶ Case-I: more general $\mathcal{H} \Rightarrow$ better chances of approx. f .

▶ Case-II: less general $\mathcal{H} \Rightarrow$ better chance of gen.

Ideal $\Rightarrow \mathcal{H} = \{f\}$

$$E_{in}(g) \approx E_{out}(g)$$

↑
best

→ How well \mathcal{H} approximates f ?

→ How can we find the best among \mathcal{H} ?

bias

vs

variance

→ [TODAY'S LECTURE]

$$\underbrace{E_{out}(g^{(D)})}_{\text{out}} = E_x [g^{(D)}(x) - f(x)]^2 \quad \boxed{E_x(f(x)) = \int_L^r \underline{f(x)} dx} \quad \vartheta' \rightarrow g'$$

$$E_D [E_{out}(g^{(D)})] = E_D [E_x (g^{(D)}(x) - f(x))^2] \\ = E_x [E_D (g^{(D)}(x) - f(x))^2]$$

► Avg. Hypothesis

$$\mathcal{H} = \{h_1, \dots, h_M\}$$

$$\hookrightarrow \bar{g}(x) = E_D [g^{(D)}(x)]$$

Imagine $\vartheta_1, \dots, \vartheta_k$

$$\bar{g}(x) \approx \frac{1}{k} \sum_{k=1}^k g^{\vartheta_k}(x)$$

$$E_D [(g^{(D)}(x) - f(x))^2] \\ = E_D [(g^{(D)}(x) - \bar{g}(x) + \bar{g}(x) - f(x))^2] \\ = E_D [(g^{(D)}(x) - \bar{g}(x))^2 + (\bar{g}(x) - f(x))^2]$$

~~$$+ 2(g^{(D)}(x) - \bar{g}(x)) \cdot (\bar{g}(x) - f(x))$$~~

~~$$[E_D [g^{(D)}(x) - \bar{g}(x)]] \cdot 2 \cdot (\bar{g}(x) - f(x))$$~~

$\bar{g}(x) - \bar{g}(x)$

$$\mathbb{E}_D[(g^D(x) - f(x))^2] = \underbrace{\mathbb{E}_D[(g^D(x) - \bar{g}(x))^2]}_{\text{var}(x)} + \underbrace{(\bar{g}(x) - f(x))^2}_{\text{bias}(x)}$$

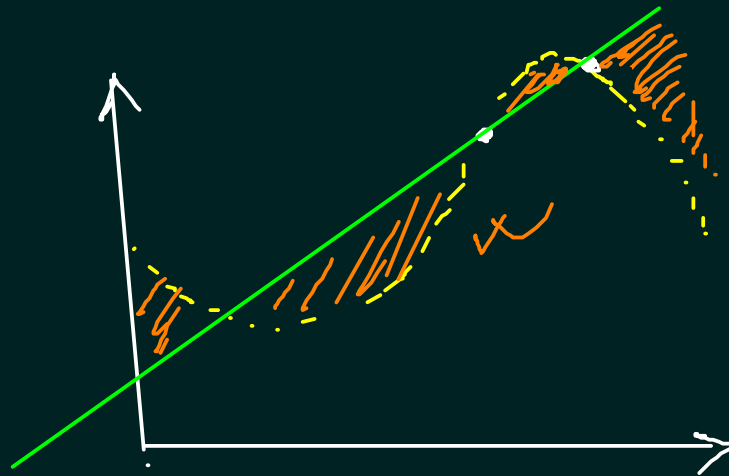
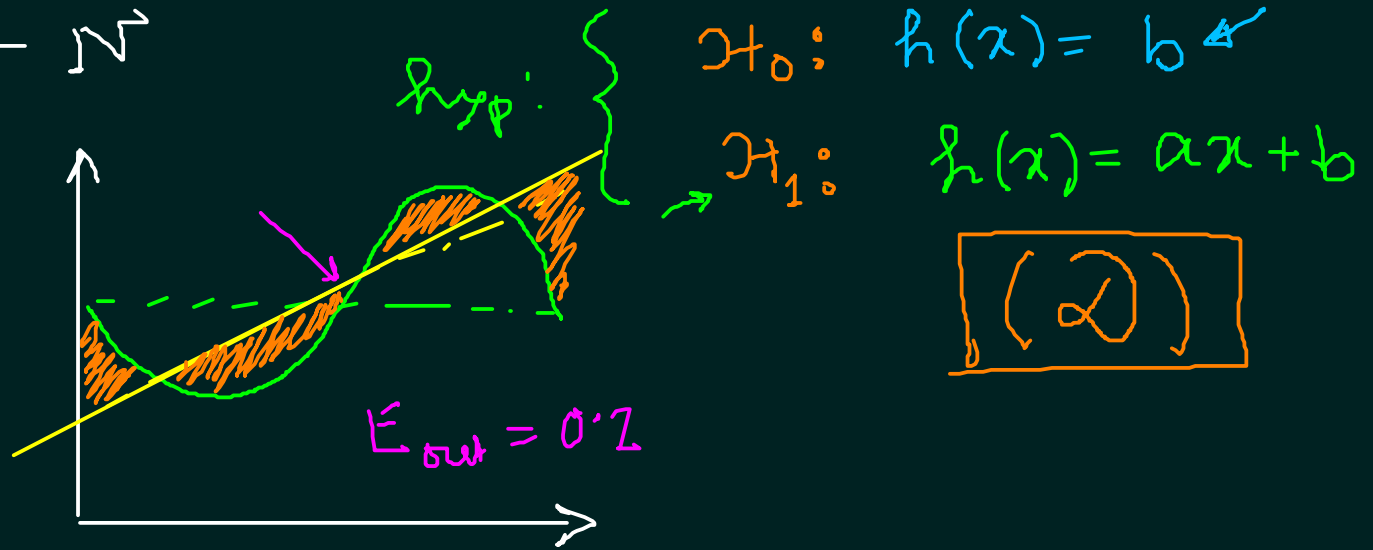
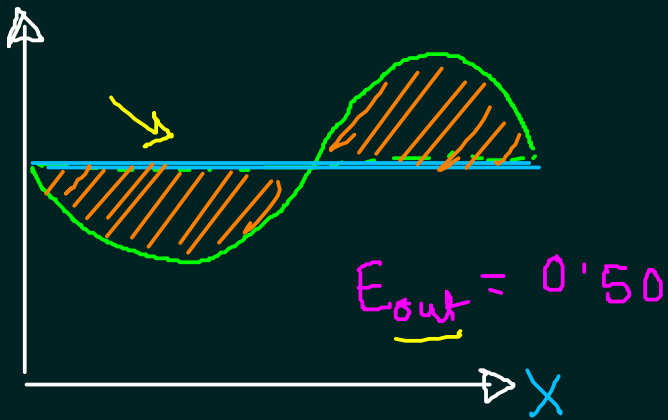
$$\begin{aligned} \mathbb{E}_D[\mathbb{E}_X[\mathbb{E}_{\text{out}}(g^D)]] \\ = \mathbb{E}_X[\mathbb{E}_D[(g^D(x) - \bar{g}(x))^2]] + \mathbb{E}_X[(\bar{g}(x) - f(x))^2] \end{aligned}$$

$$= \mathbb{E}_X[\text{var}(x)] + \mathbb{E}_X[\text{bias}(x)]$$



Example: $f: [-1, 1] \rightarrow \mathbb{R}^{[-1, -1]}$ where $f(x) = \sin(\pi x)$

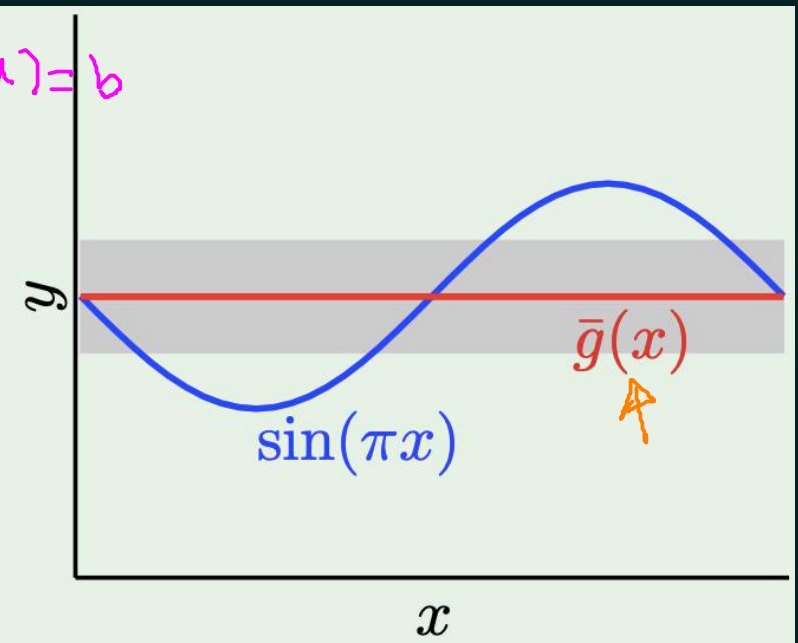
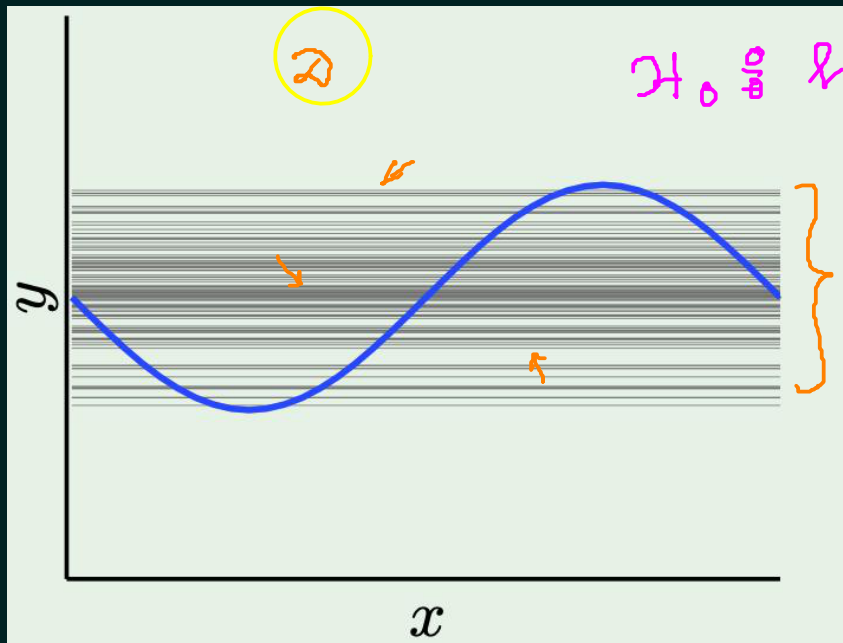
$\hookrightarrow \#TE = 2 \leftarrow \mathbb{N}$



$\mathcal{H} \uparrow$
 bias \downarrow
 var \uparrow

(Sample Model Complex)

$E_{out} \approx 0 \rightarrow \mathcal{H}_0$ vs \mathcal{H}_1 ($N=2$)

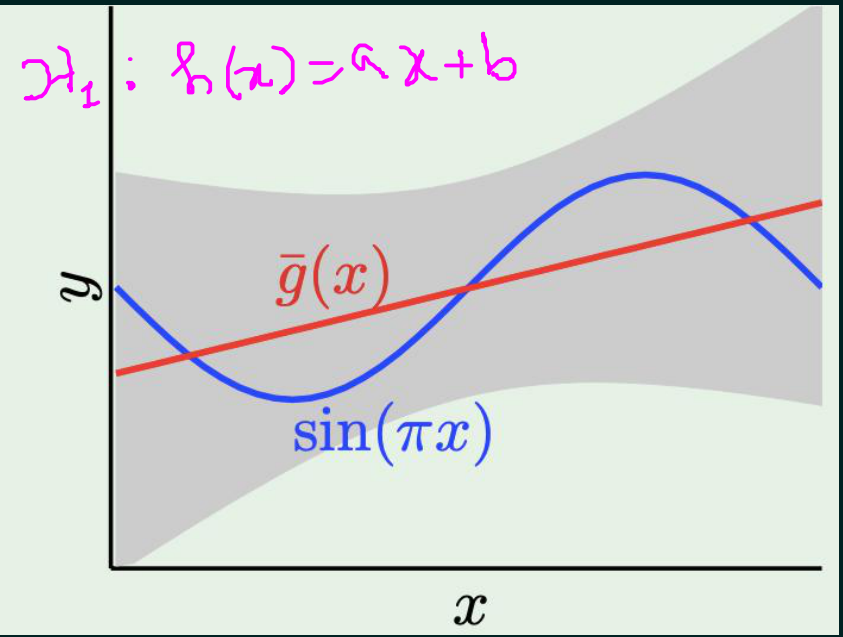
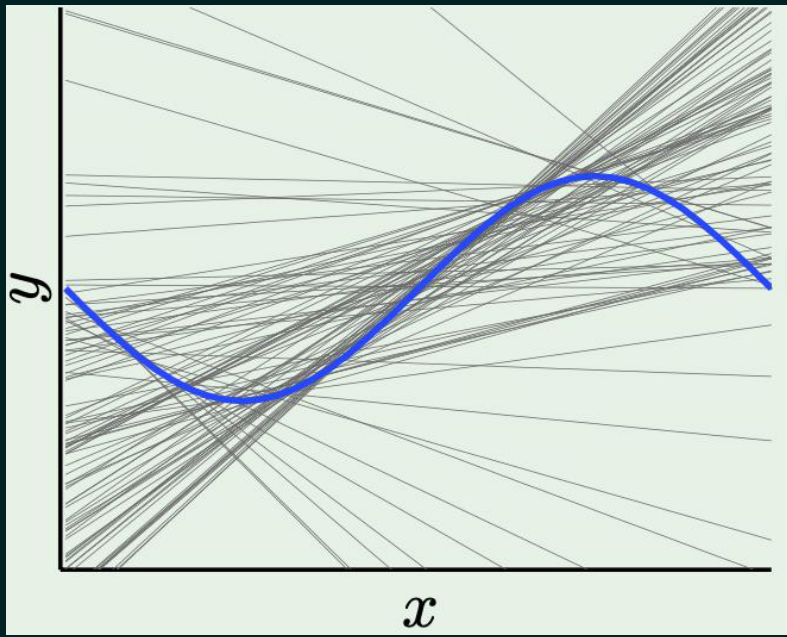


bias = 0.50

var = 0.25

0.75

f

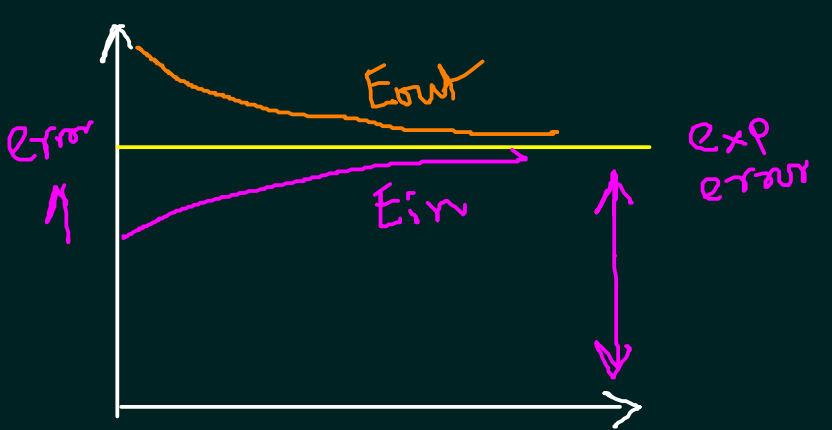


bias = 0.21

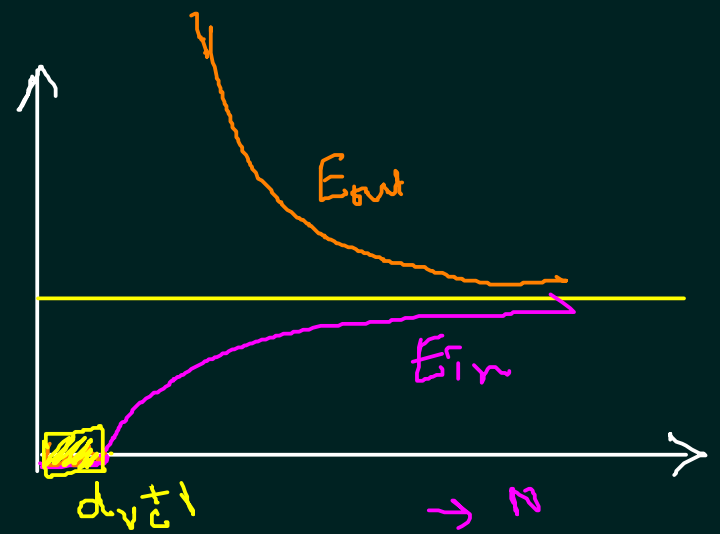
var = 1.69

1.90

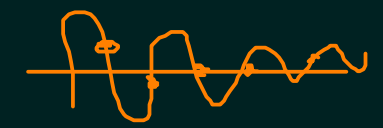
$E_x [\bar{g}(x) - f(x)]^2$



(M0) Simple Model

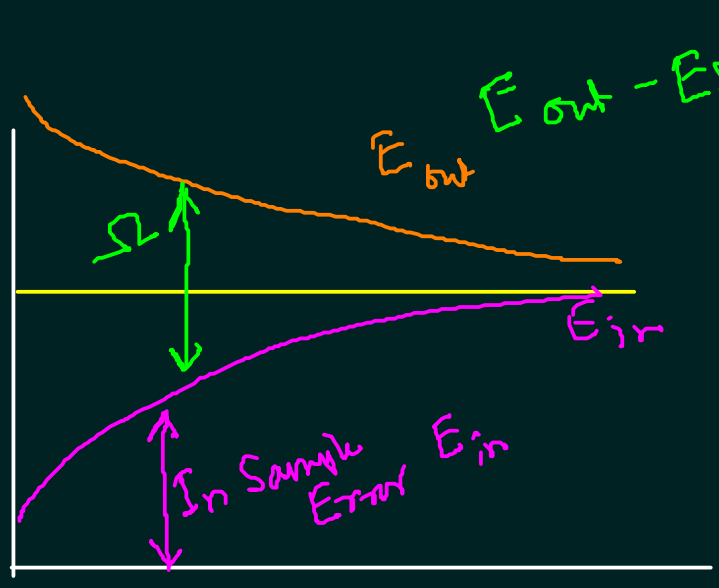


(M1) Complex Model



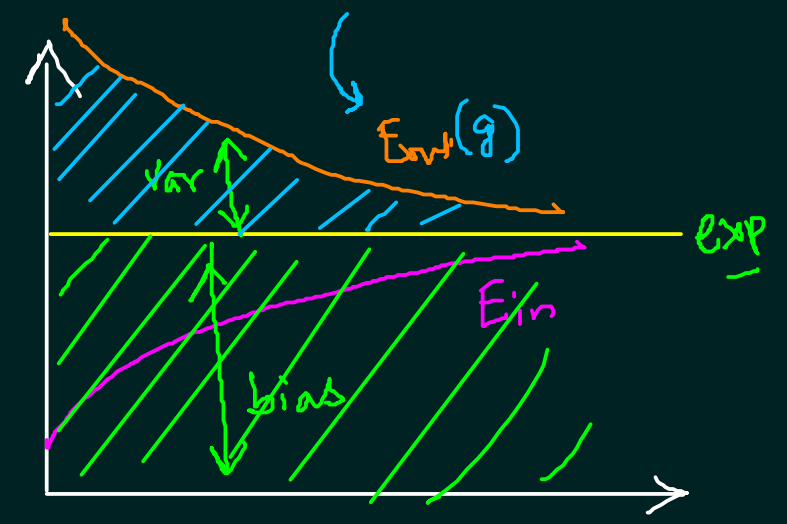
SQ-error

bias(x)
 $= \left[\bar{g}(x) - f(x) \right]^2$



$E_{out} - E_{in} \leq \Omega$

Ex: Linear Reg.
 (02)



$E_{out}(g) \leq E_{in}(g) + \Omega$

$E_{out}(g) \leq \underline{\text{bias}} + \underline{\text{var}}$