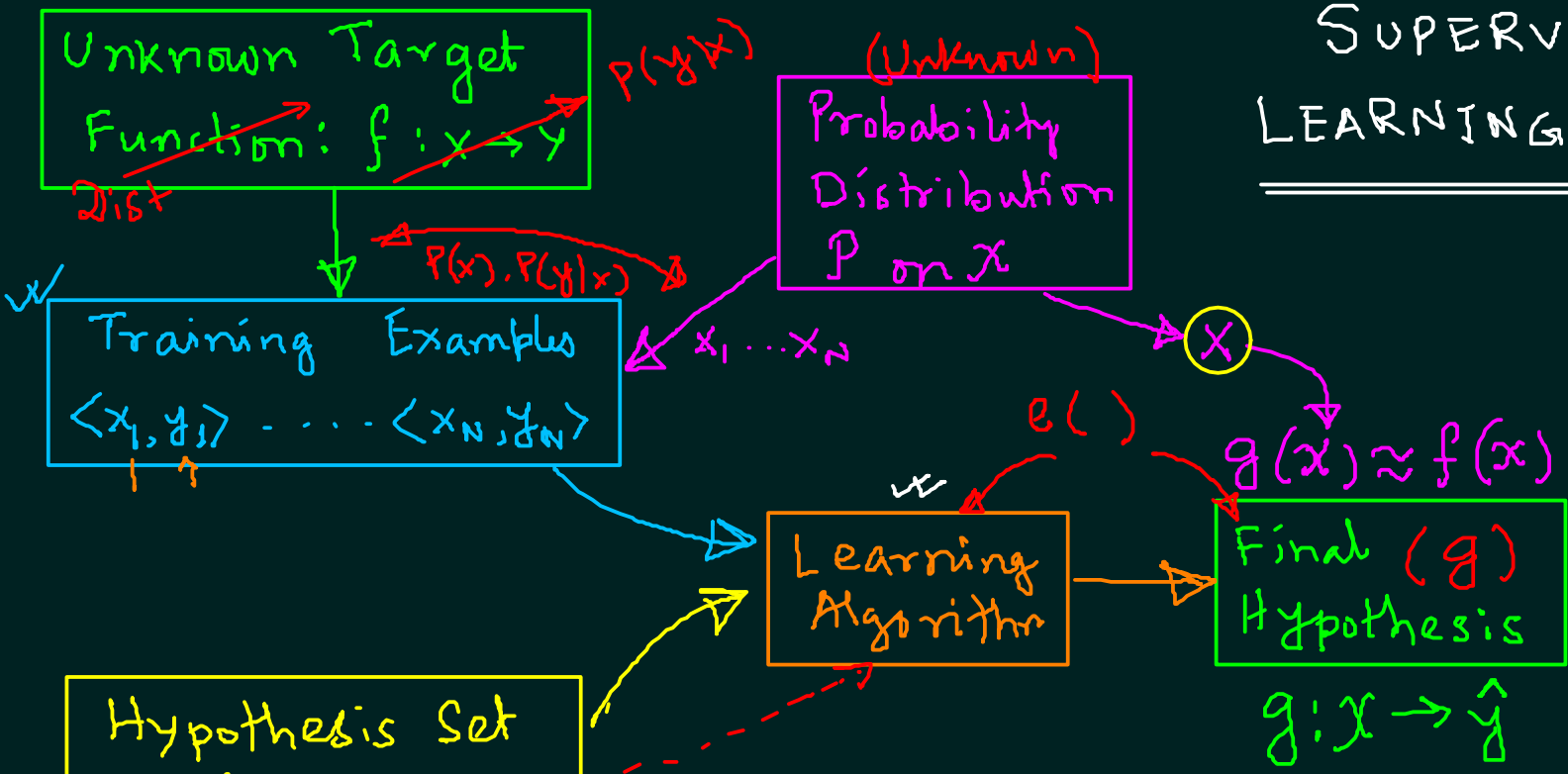


SUPERVISED LEARNING DIAGRAM



▶ In-Sample }
 ≡ Train }
 ▶ Out-of-Sample }
 ≡ Test }

Hypothesis Set
 $H = \{h_1, \dots, h_M\}$

→ What does $h \approx f$ mean?

▶ Out-of-Sample

$E(h, f) = \text{error} = e(h(x), f(x)) \rightarrow \text{point wise}$

→ Squared
 $(h(x) - f(x))^2$

→ Binary $\begin{pmatrix} +1 \\ -1 \end{pmatrix}$
 $\mathbb{I} [h(x) \neq f(x)]$

$E_{\text{out}}(h)$
 $= \text{Exp}_x [e(h(x), f(x))]$

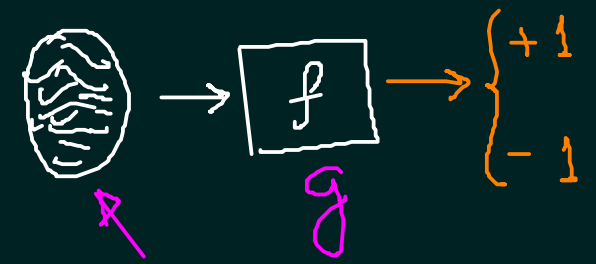
▶ In-Sample Error $E_{\text{in}}(h) = \frac{1}{N} \sum_{n=1}^N e(h(x_n), f(x_n))$

Ex: fingerprint recog.

		+1	f	-1
h	+1	—w	false accept	X
	-1	false reject	—w	X

error

		+1	f	-1
h	+1	0	1000	5
	-1	1	0	

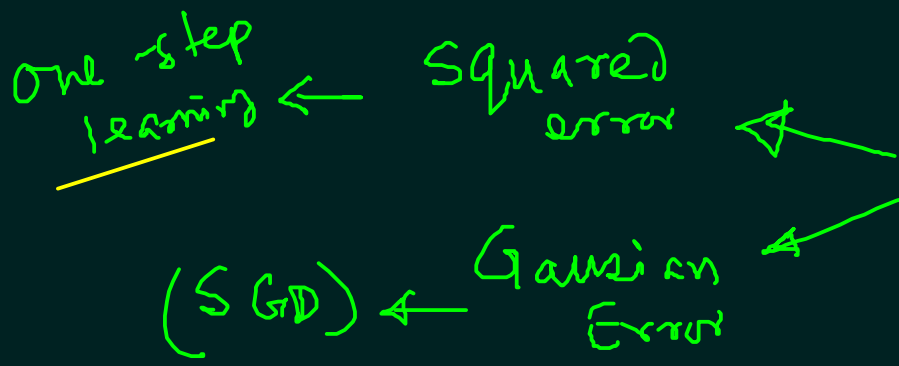


Wisely choose the penalty

▶ Intruder is entering }
IB office

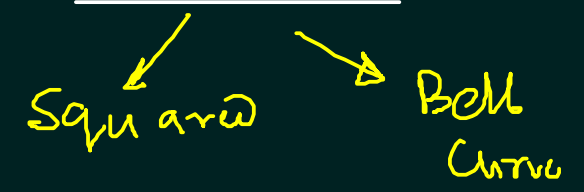
▶ Supermarket Discount }

Choice of error function



plausible Measure

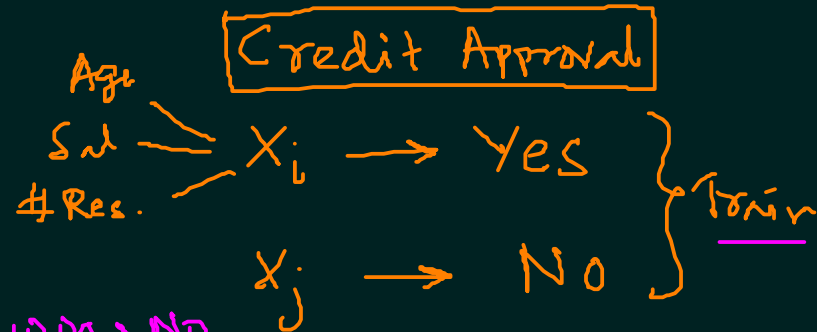
friendly error



$$f: X \rightarrow y$$

→ Noise

↳ unknown function



$\text{Prob}(y|X)$ ← target distribution
unknown

< 1000 → NO
> 1000 → YES
948 → YES

$T_1: 1000 \rightarrow \text{Yes}$
 $T_2: 1000 \rightarrow \text{No}$

TE: $\langle x_1, y_1 \rangle \dots \langle x_N, y_N \rangle$

Prob dist of X

$x_1 \dots x_N$

$P(y|x)$

by Joint distribution
 $P(x), P(y|x) = P(x,y)$

Special case of noisy target

Noisy Target = deterministic target + Noise

$y = f(x) \rightarrow P(y|x) = \delta$
except $y = f(x)$

$$f(x) = E(y|x) + (y - f(x))$$

$$E_{out}(g) \approx E_{in}(g)$$

← Inductive Learning Principle

Lecture 2

Learning is Feasible

$$\Rightarrow \text{Prob}[|E_{out} - E_{in}| > \epsilon] \leq$$

$$\frac{2M}{\epsilon} e^{-\epsilon^2 N}$$

$$E_{out}(g) \approx 0$$

— final aim

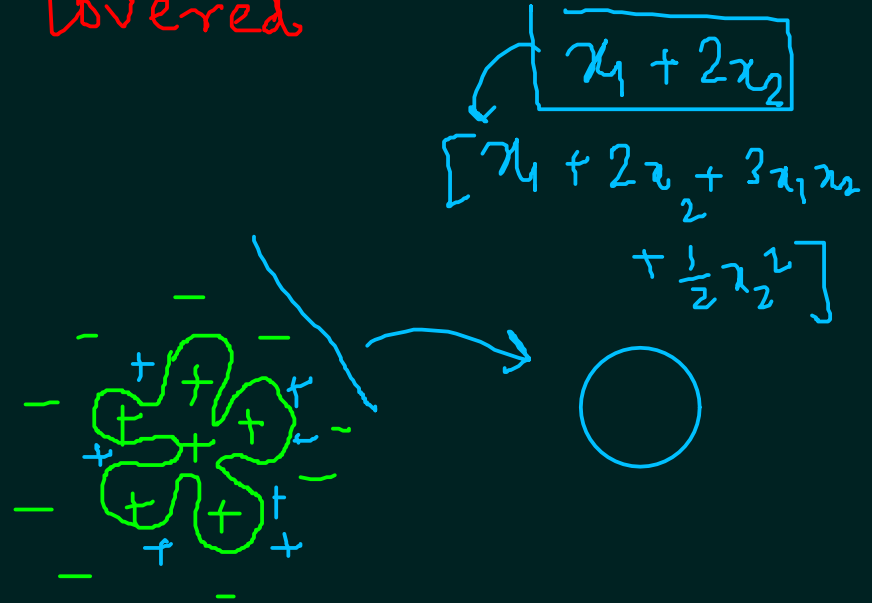
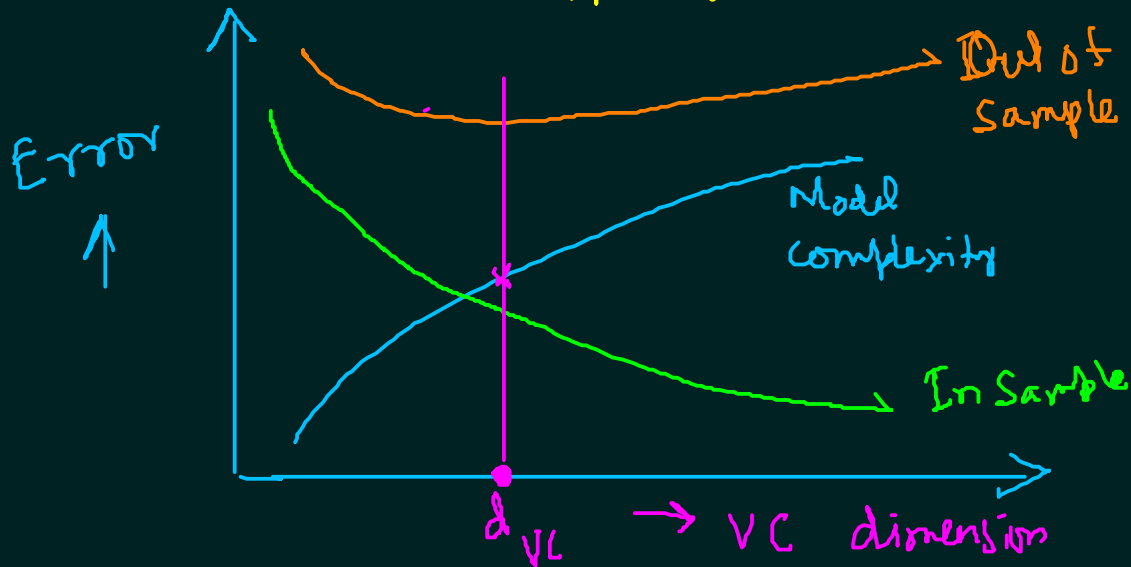
---> all other lecture

$$E_{in}(g) \approx E_{out}(g)$$

— is close enough???

$$E_{in}(g) \approx 0$$

✓ covered



Testing :

$$P[|E_{out} - E_{in}| > \epsilon] \leq 2 e^{-2\epsilon^2 N}$$

how you learn \leftarrow how you gave final exam

Training :

$$P[|E_{in} - E_{out}| > \epsilon] \leq 2 M e^{-2\epsilon^2 N}$$

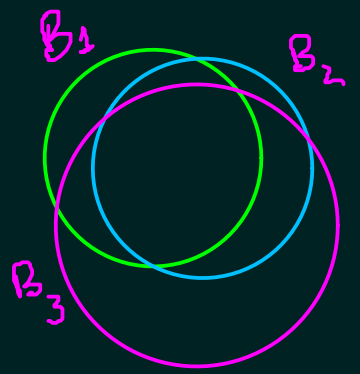
Solve Mode Test

final exam

theory of generalization

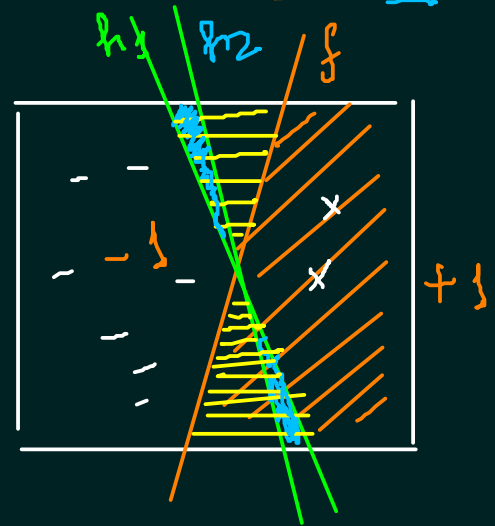
$$M = (\infty)$$

$$f(N)$$



$$P(B_1 \text{ or } B_2 \text{ or } B_3)$$

$$\leq P(B_1) + P(B_2) + \dots$$



$$|E_{in}(h_1) - E_{out}(h_1)|$$

$$\approx |E_{in}(h_2) - E_{out}(h_2)|$$

hope!