#### THE UNIVERSAL TURING MACHINE

#### AND DIAGONALIZATION PROOFS OF UNDECIDABILITY

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## **One machine for all problems**

- So far, we have built several machines, each solving a single problem.
- We have also embedded the finite control of a machine in the finite control of a simulating machine.
- Modern (stored-program) computers appear to be more flexible.
  - An executable file solves one problem.
  - The computer can run any executable file.
  - The executable file must be presented in a format understood by the CPU.
- Can we present the working of a Turing machine *M* as an executable file, and supply that executable file to the tape (not the finite control) of a Turing machine?
- The Universal Turing machine (UTM) U can do that.
- *M* must be **encoded** as a string that *U* can decode easily.
- *U* should also be supplied the input *x* for *M*.
- *U* simulates *M* on *x* by looking at the description (encoding) of *M* and *x*.
- *U* does not need to store the finite control of *M* in its own finite control.

### **Binary encoding of Turing machines and input strings**

- Let  $M = (Q, \Sigma, \Gamma, \vdash, \sqcup, \delta, s, t, r)$  be a TM.
- Let n = |Q|,  $m = |\Gamma|$ , and  $k = |\Sigma|$ .
- Take  $Q = \{0, 1, 2, \dots, n-1\}, \Sigma = \{0, 1, 2, \dots, k-1\}, \text{ and } \Gamma = \{0, 1, 2, \dots, m-1\}.$
- Then,  $\vdash$  and  $\square$  are two different integers *e* and *b* in the range [k, m-1].
- s, t, r are integers in the range [0, n-1].
- All the components of *M* except  $\delta$  can be specified by the string  $0^n 10^k 10^m 10^e 10^b 10^s 10^t 10^r 1$ .
- This is followed by the transitions of *M* listed one after another.
  - $\delta(p,a) = (q,b,L)$  is encoded as  $0^p 10^a 10^q 10^b 10$ .
  - $\delta(p,a) = (q,b,R)$  is encoded as  $0^p 10^a 10^q 10^b 11$ .
- Let  $x = a_1 a_2 \dots a_l \in \Sigma^*$ .
- Each  $a_i$  is an integer in the range [0, k-1].
- We encode x as  $0^{a_1}10^{a_2}1...10^{a_l}1$ .

# All binary strings are encodings

- We are able to encode each TM *M* and each input *x* for *M* as binary strings.
- Any string w over  $\{0, 1\}$  can be treated it as a binary encoding of a TM M.
- If *w* does not correspond to a valid encoding of a TM, we assume that *M* is a Turing machine that, on any input, immediately rejects and halts.
- This machine is represented by all invalid strings.
- Valid encodings are also not unique (rename states/symbols, rearrange transitions).
- Any string  $w \in \{0,1\}^*$  can be treated as a binary encoding of some  $x \in \Sigma^*$ .
- If *w* is invalid, we take  $x = \varepsilon$ .
- Multiple encodings (valid or invalid) may represent the same string *x*.
- Multiple encodings for a machine/string do not pose a problem.
- We can write the encoding of *M* and *x* as  $\langle M \rangle$  and  $\langle x \rangle$ .
- By an abuse of notation,  $\langle M \rangle$  and  $\langle x \rangle$  are usually written as *M* and *x*.

#### The Universal Turing Machine U

- *U* is designed as a 3-tape (or 3-track) TM.
- *M* and *x* are both binary strings, so we supply both as M # x on the first tape of *U*.
- Without loss of generality, we may assume that *M* is a DTM.
- U uses its second tape to simulate the tape of M.
- *U* uses its third tape to store the state of *M* and the head position of *M*.
- U checks whether M given on the first tape is a valid encoding of a Turing machine. If not, it rejects and halts.
- U then checks whether x is a valid encoding of an input for M.
  If not, it erases x on its first tape, so x becomes ε.
- U copies x to its second tape, and s and 0 to its third tape.
- *U* is now ready to start the simulation of *M* on *x*.

### The simulation of M on x by U

- *U* reads the state *p* of *M* from the third tape.
- *U* also knows the head position *h* from the third tape.
- U aligns its head to point to the *h*-th cell of the tape of M on its second tape.
- *M* reads the symbol *a* scanned by the head of *M* at position *h*.
- Since *M* is a valid encoding of a DTM, *U* locates the unique transition entry  $\delta(p,a) = (q,b,d)$  from its first tape.
- U replaces a by b on its second tape, relocating the contents to the right if  $a \neq b$ .
- U replaces p by q on its third tape.
- Finally, depending upon the direction d (L or R), U changes the head position of M on its third tape.
- This completes the simulation by *U* of one step of *M*.

# The language of U

- If *M* ever enters its accept state *t*, *U* accepts (and halts).
- If *M* ever enters its reject state *r*, *U* rejects (and halts).
- If *M* loops on *x*, *U* continues simulating the steps of *M* for ever.
- U is designed to detect whether M accepts x, that is, whether x is a member of  $\mathscr{L}(M)$ .
- *U* solves the **membership problem** for every TM *M* and for every input *x* for *M*.

• 
$$\operatorname{MP} = \mathscr{L}(U) = \Big\{ M \, \# \, x \mid x \in \mathscr{L}(M) \Big\} = \Big\{ (M, x) \mid x \in \mathscr{L}(M) \Big\}.$$

- U may be slightly modified to U' as follows.
- If M ever enters t or r, U' accepts (and halts).
- U' solves the **halting problem** for every TM *M* and for every input *x* for *M*.

• HP = 
$$\mathscr{L}(U') = \Big\{ M \, \# \, x \mid M \text{ halts on } x \Big\} = \Big\{ (M, x) \mid M \text{ halts on } x \Big\}.$$

# An immediate question

- The UTM solves the membership (or halting) problem by blindly simulating *M* on *x*.
- In particular, if *M* does not halt *x*, the simulation by *U* also does not halt.
- U is a recognizer, not a decider.
- Is there a more intelligent way to solve the problem(s)?
- In special cases, the problem can be solved without a simulation.
  - The encoding of *M* is invalid, so no simulation is necessary.
  - *M* has no transitions of the form  $\delta(p, a) = (t, b, d)$ .
  - *M* never writes a symbol *A* (not in Σ∪ {⊢, ⊥}) on its tape, but the only transitions that allow *M* to accept are of the form δ(*p*,*A*) = (*t*,*b*,*d*).
  - ...
- In general, there is no better way of solving the membership (or halting) problem than doing blind simulation.
- Theorem: MP and HP are (recursively enumerable but) not recursive.

#### HP is not recursive: Preparation for the proof

- A similar proof works for MP as well.
- $\{0,1\}^*$  is countably infinite.
- Let  $\alpha_1, \alpha_2, \alpha_3, \ldots$  be an exhaustive enumeration of all the binary strings.
- Example:  $\varepsilon$ , 0, 1, 00, 01, 10, 11, 000, 001, 010, 011, 100, 101, 110, 111, 0000, ...
- Every  $\alpha \in \{0,1\}^*$  (even if invalid) is the encoding of a Turing machine  $M_{\alpha}$ .
- Every  $\alpha \in \{0,1\}^*$  (even if invalid) is the encoding of an input  $x_{\alpha}$  for any TM.
- $\alpha_1, \alpha_2, \alpha_3, \ldots$  is an exhaustive list of all Turing machines.
- There are repetitions in the list, but there are **no other Turing machines**.
- $\alpha_1, \alpha_2, \alpha_3, \dots$  is an exhaustive list of all inputs.
- There are repetitions in the list, but there are **no other inputs**.

# A diagonalization proof

- Suppose that HP is recursive. Let *D* be a decider for HP.
- Given any two binary strings  $\alpha_i, \alpha_j$ , the hypothetical TM *D* decides (in finite time) whether  $M_{\alpha_i}$  halts on  $x_{\alpha_i}$ .
- Consider a two-dimensional table of all machines on all inputs.

	$x_{\alpha_1}$	$x_{\alpha_2}$	$x_{\alpha_3}$	•••	$x_{\alpha_n}$	
$M_{\alpha_1}$	Η	Η	Η	•••	Η	•••
$M_{lpha_2}$	H	L	L	•••	H	•••
$M_{lpha_3}$	L	L	H	•••	L	•••
÷	÷	÷	÷		÷	
$M_{lpha_n}$	L	H	H	• • •	H	• • •
÷	÷	÷	÷		÷	
E	L	Н	L	•••	L	•••

• Given any  $\alpha_i$  and  $\alpha_j$ , *D* can compute the (i,j)-th entry of the table in finite time.

# **Converting** *D* to a Turing machine *E*

- *E* takes a single binary string  $\alpha$  as input.
- *E* generates the input  $\alpha \# \alpha$  for *D*.
- *E* simulates *D* on this input.
- D is a decider, so a finite-time simulation gives the answer H (accept) or L (reject).
- If *D* outputs *H*, then *E* forcibly enters an infinite loop (like always move right in a looping state).
- If D outputs L, then E immediately accepts and halts.
- *E* is a Turing machine, so can be found (at least once) in the exhaustive list of TM encodings. Let *E* have an encoding  $\alpha_n$ .
- The rows marked  $M_{\alpha_n}$  and *E* must be identical.
- But the rows must differ in the *n*-th column, a contradiction.
- So *E* cannot exist, and so *D* cannot exist too.

#### **Tutorial exercises**

- 1. Modify the diagonalization proof for HP to prove that MP is not recursive.
- 2. Use a diagonalization argument to prove that the following language is not recursive.

 $\left\{ M \# x \mid M \text{ reenters its start state on input } x \right\}$ 

**3.** For two languages A and B over the same alphabet  $\Sigma$ , define the language

$$A/B = \Big\{ \alpha \in \Sigma^* \mid \alpha \beta \in A \text{ for some } \beta \in B \Big\}.$$

Prove that if A and B are recursively enumerable, then so also is A/B. Prove/disprove: If A and B are recursive, then so also is A/B.

**4.** A *shuffle* of two strings  $\alpha$  and  $\beta$  is a string  $\gamma$  of length  $|\alpha| + |\beta|$ , in which  $\alpha$  and  $\beta$  are non-overlapping subsequences (not necessarily substrings). For example, all shuffles of *ab* and *cd* are *abcd*, *cabd*, *cdab*, *acbd*, *acdb*, and *cadb*. For two languages *A* and *B*, we define shuffle(*A*, *B*) as the language consisting of all shuffles of all  $\alpha \in A$  and all  $\beta \in B$ . Prove that recursively enumerable languages are closed under the shuffle operation, that is, if *A* and *B* are r.e. languages, then so also is the language

shuffle
$$(A,B) = \{ \gamma \mid \gamma \text{ is a shuffle of some } \alpha \in A \text{ and } \beta \in B \}.$$

Is shuffle(A, B) recursive if A and B are recursive? Justify.