

# Nondeterminism and Subset Construction

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- A transition function is no longer required, should be a map, since there are many possibilities.
- We could guess where to start from; so, many start states are possible. No longer a single start state.

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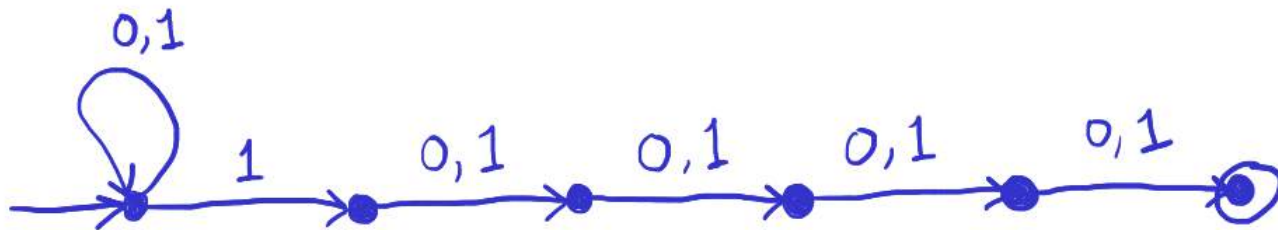
- The idea is that the automaton guesses a path in it and verifies whether that guess leads to a final state. The other paths may lead to non-final states or may end even before you finish reading the input (terminated).
- Note 1: You are allowed to put more than one arrows with the same label coming out of a state.
- Note 2: You are allowed to choose a set of start states.
- Note 3: Since we are relaxing the transition function to a transition map and allowing termination of a guess, we do not need to define transitions from a state for each possible input alphabet – there may be no option for a transition from a certain state on reading a certain alphabet!



# Nondeterministic Finite Automaton (NFA): Example

$$A = \{ x \in \{0,1\}^* \mid \text{the fifth symbol from the right is } 1 \}$$

N s.t N accepts A



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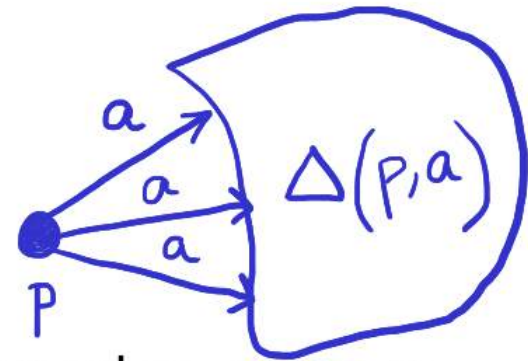
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- But does an NFA really have more computation power than a DFA?
- Can there be a language that is not a regular set (no DFA) but has an NFA?

# Formal definition of NFA

- $N = (Q, \Sigma, \Delta, S, F)$
- $Q$  – states
- $\Sigma$  – alphabet
- $\Delta : Q \times \Sigma \rightarrow 2^Q$ , all states that  $N$  is allowed to move to from state  $p$  on reading input  $a$ .
- $S$  – start states
- $F$  – final states.
- Again, finite encoding of an NFA possible.

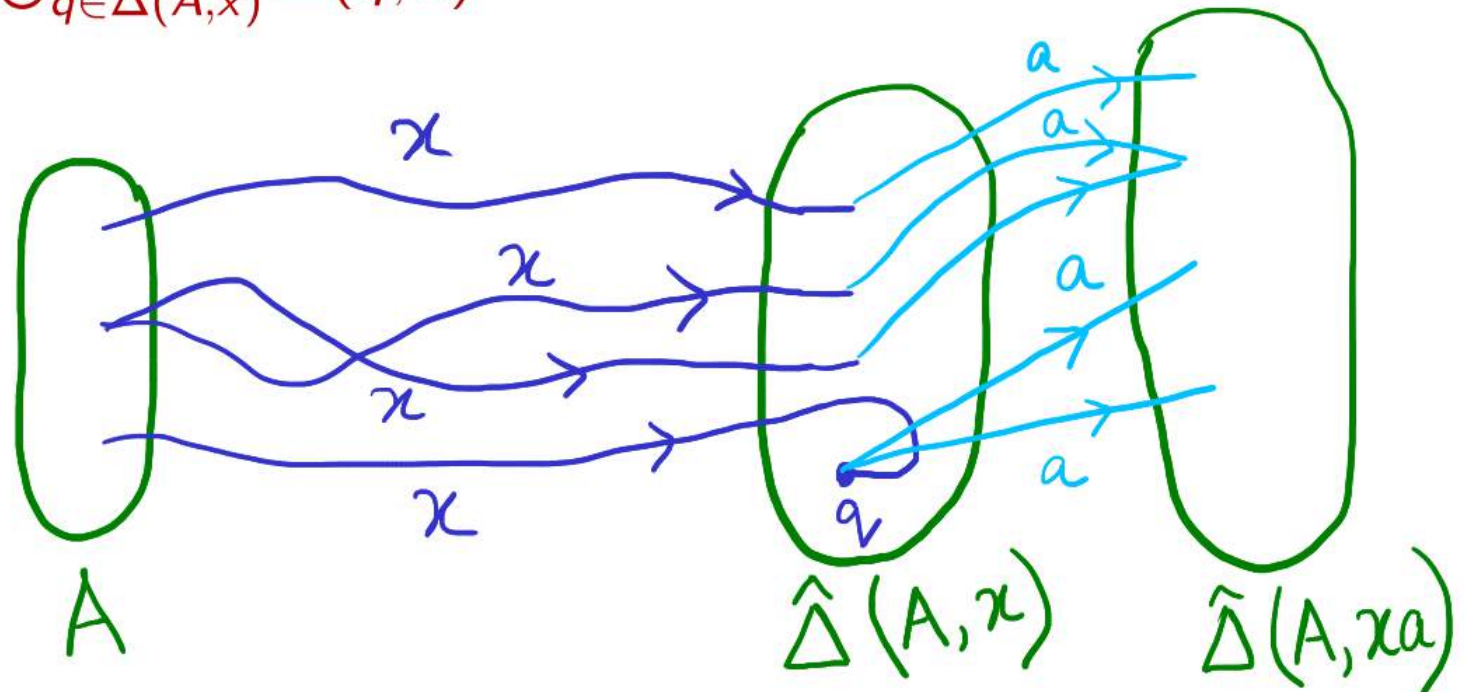


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- Image set of states = set of all states reachable from some state in  $A$  on reading input  $xa$ .
- State  $r \in \hat{\Delta}(A, xa)$  if there exists a  $q \in \hat{\Delta}(A, x)$  such that  $r \in \Delta(q, a)$ .

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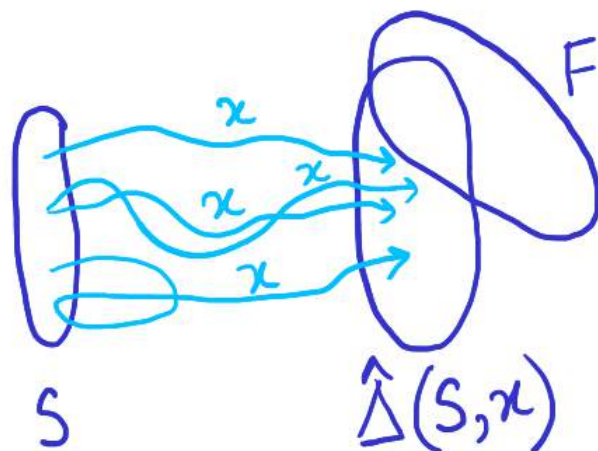
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- $L(N) = \{x \mid N \text{ accepts } x\}$

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- Base:  $y = \epsilon$   
 $\hat{\Delta}(A, x.\epsilon)$   
 $= \hat{\Delta}(A, x)$   
 $= \hat{\Delta}(\hat{\Delta}(A, x), \epsilon)$  [By definition].



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 $= \bigcup_{q \in \hat{\Delta}(\hat{\Delta}(A, x), y)} \Delta(q, a)$  [I.H]  
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# Do NFAs have more power than DFAs?

- A DFA can be thought of as an NFA:  $(Q, \Sigma, \Delta, \{s\}, F)$  such that  $\Delta(p, a) = \{\delta(p, a)\}$ . If a set is accepted by a DFA then it is also accepted by an NFA.

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- Suppose  $N = (Q_N, \Sigma, \Delta_N, S_N, F_N)$  is an NFA and  $L(N)$  is the set accepted by  $N$ .

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- $\delta_M(A, a) = \hat{\Delta}_N(A, a)$

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- Base:  $x = \epsilon$ .  
 $\hat{\delta}_M(A, \epsilon) = A = \hat{\Delta}_N(A, \epsilon)$  [Definition]

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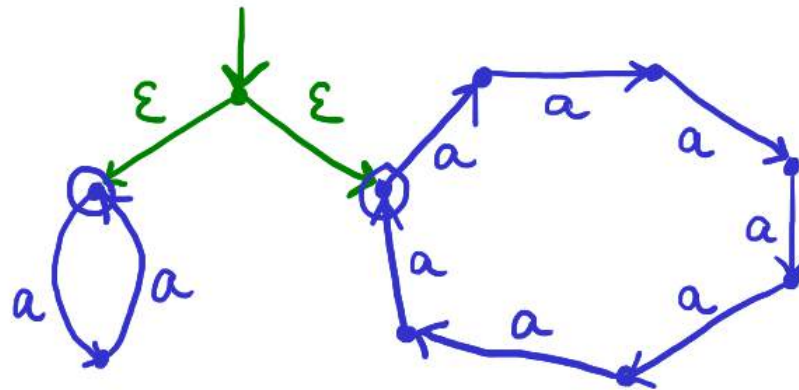
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- So DFA and NFA have the same power. **NFAs accept regular sets.**

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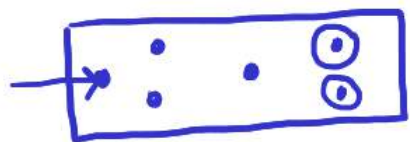


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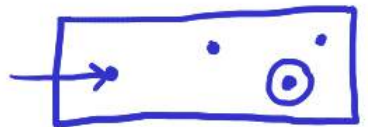
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- They do not add any power. (Prove this.)

# Revisiting Closure Properties of Regular Sets

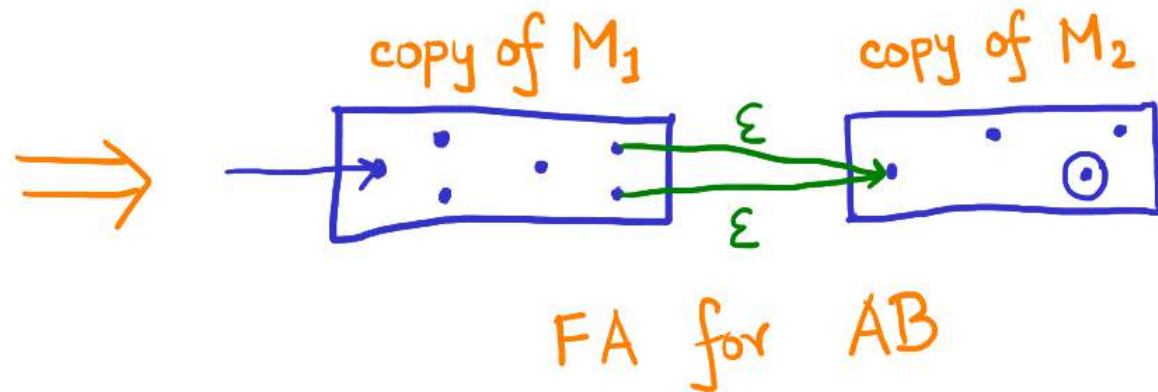
- Construction of DFA/NFA for  $AB$  when  $A$  and  $B$  are regular:  
Construct an NFA with  $\epsilon$ -transition.  
DFAs  $M_1$  for  $A$  and  $M_2$  for  $B$ .  
 $\epsilon$ -transition between end states of  $A$  and start state of  $B$ .



$$L(M_1) = A$$



$$L(M_2) = B$$



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- If  $A$  is regular then so is  $A^*$ : Create new start state;  
Add  $\epsilon$ -transitions from new start state to old start state, and  
from old final states to new start state  
Make new start state new final state as well.

