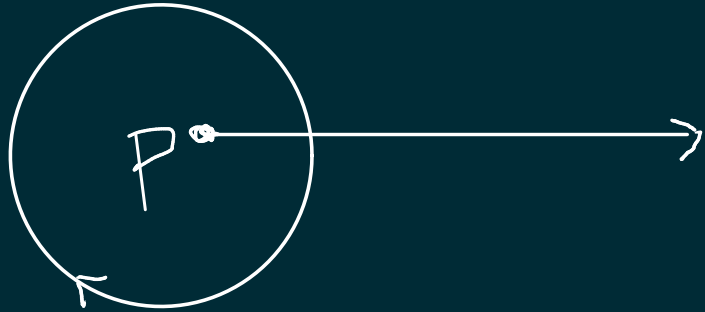
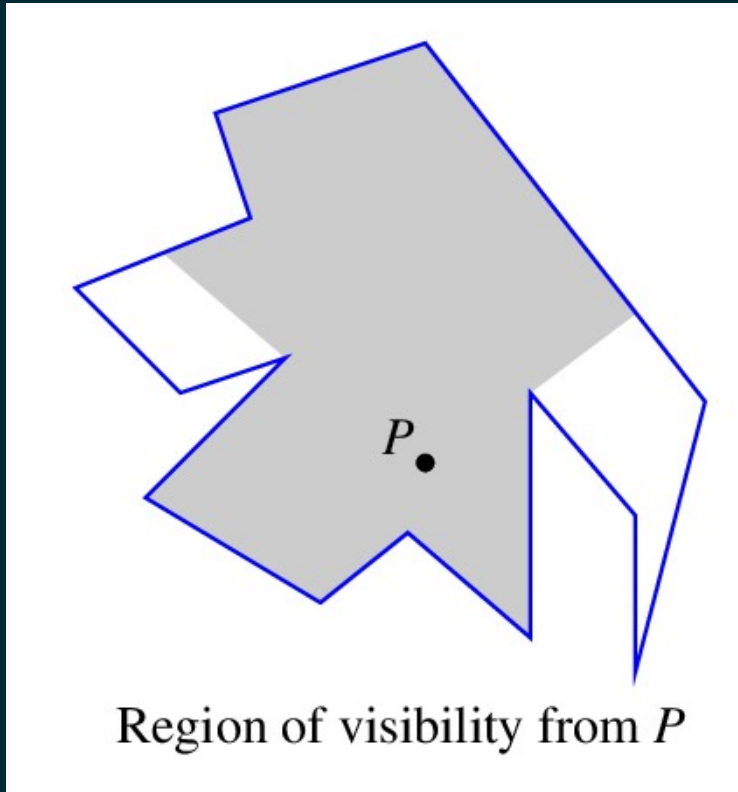


Visibility polygon

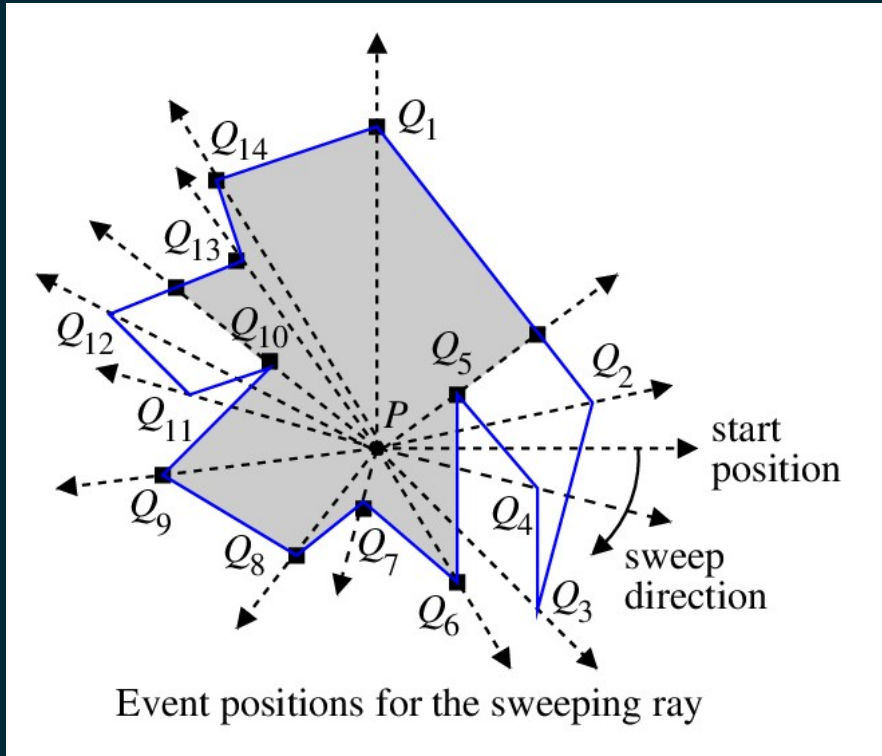
Ray sweep algorithm





Input: A simple polygon specified by a "clockwise" listing of the vertices.

If the i/p is convex, the o/p is in name as the i/p. A point P in the interior. Output: The region in the interior visible to P .



Events: The corners of the i/p polygon.

S : Sweep ray information

The set of active edges of the i/p polygon.

$$Q = Q_i$$

$$Q_- = Q_{i-1}$$

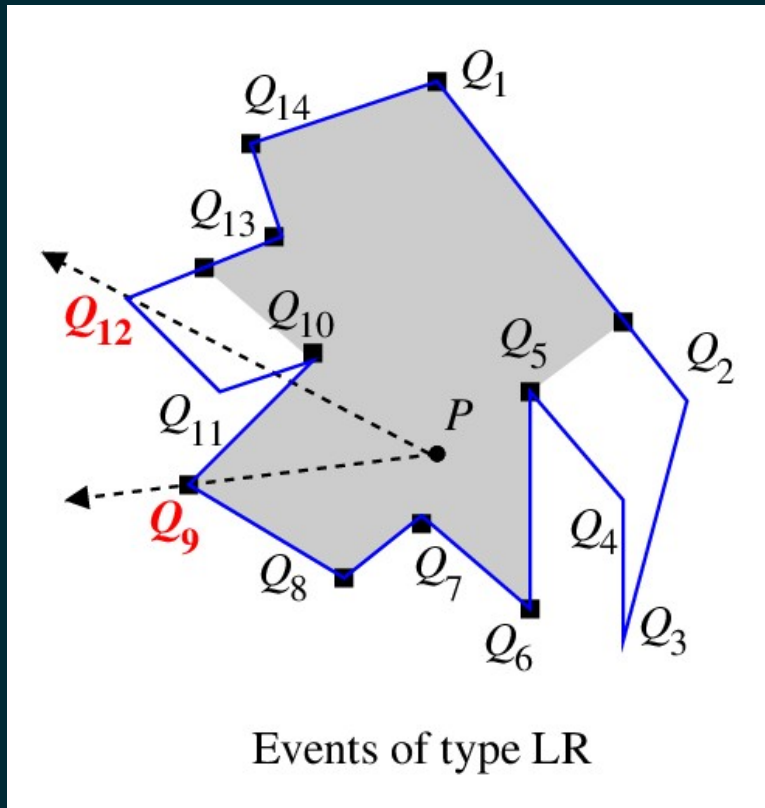
$$Q_+ = Q_{i+1}$$

$$Q_- Q \rightarrow e_-$$

$$Q Q_+ \rightarrow e_+$$

$$Q_1 - LR \quad Q_4 - RL$$

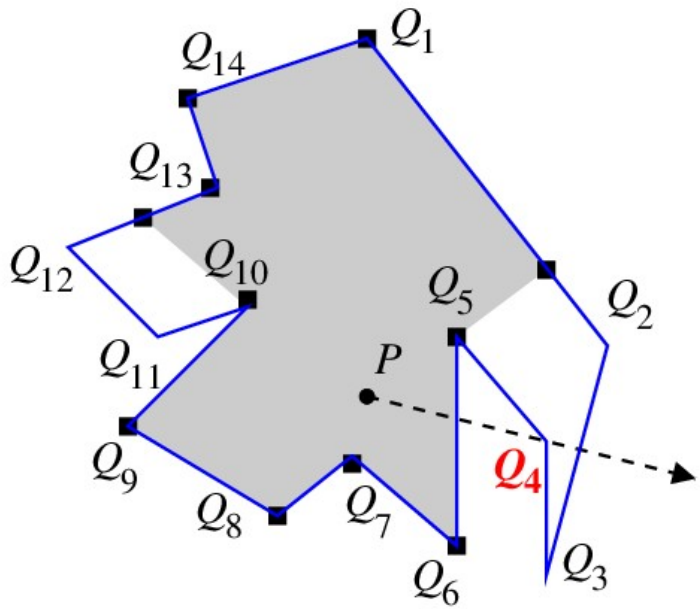
$$Q_3 - LL \quad Q_5 - RR$$



S : Remove e_-
 Insert e_+

Add Q to o/p if and only if
 e_+ is closest to P .

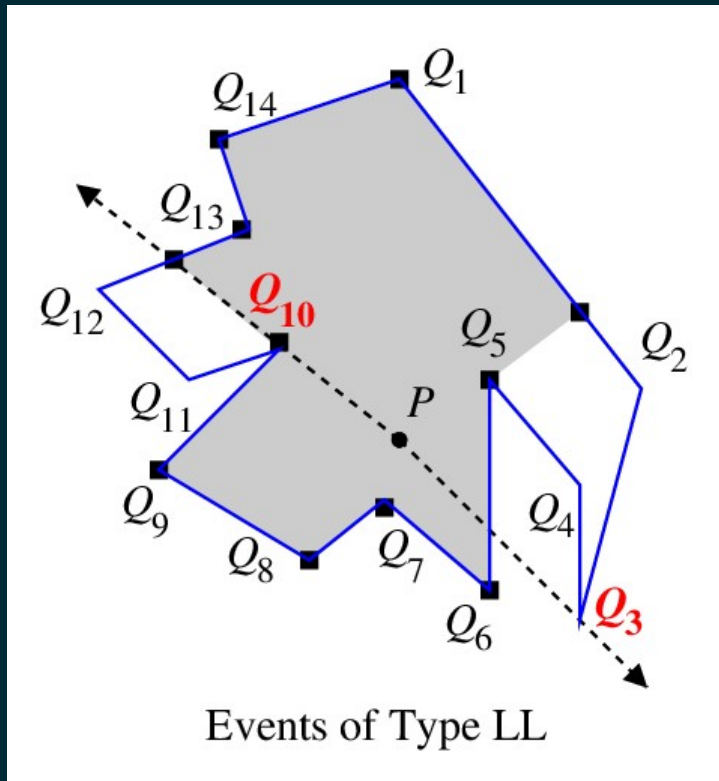
S is kept sorted
 with respect to their distances from P
 along the ray.



Events of Type RL

S : Insert e_-
Delete e_+

e_- cannot be closest
to P .



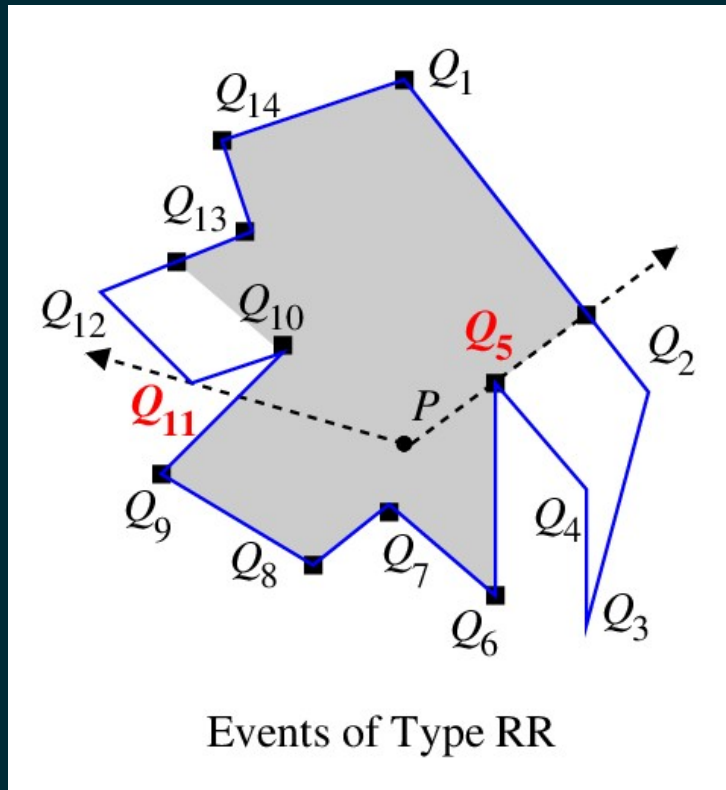
Remove e_- and e_+ from S .

Before removal:

Check whether e_-/e_+
was closest to P

If not, done.

After removal: Find the intersection R
of the ray with the closest
active edge
o/p Q, R in that order



Insert e_- and e_+ to S .

Q_5 : e_+ then e_-

Q_{12} : e_- then e_+

After insertion : check whether e_- / e_+ is closest to P .

If yes, find the intersection \bar{R} of the ray with the third nearest active line. O/p \bar{R} and then Q

E - the vertices of the i/p polygon

findmin, deletemin

(order: angle w.r to the horizontal
position)

priority queue (heap)

A sorted array is equally good.

S - insert, delete, findmin

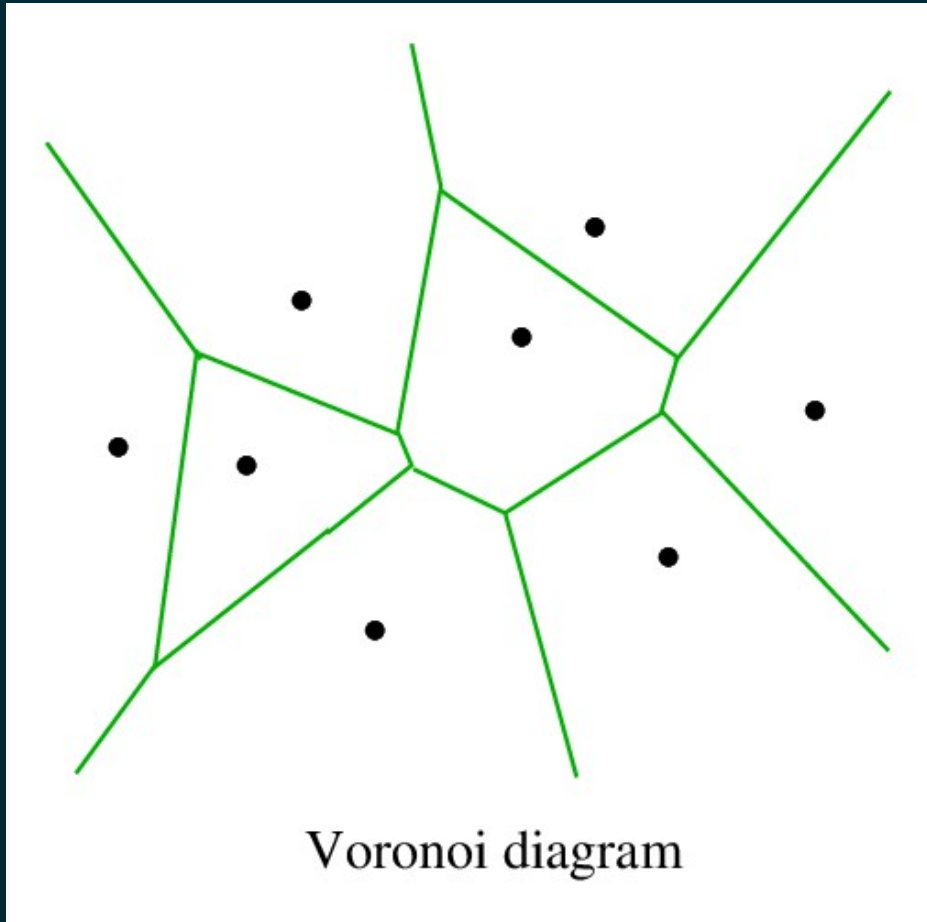
A height-balanced BST

Distances are not stored.

During ins/del, calculate
the distances along only
the ins/del path.

$O(n \log n)$

Voronoi Diagrams



$O(n \log n)$ algo

Input = A finite set of points in genl pos

- No three collinear
- No four on the same circle

$$H_{ij} = \{P \mid d(P, P_i) \leq d(P, P_j)\}$$

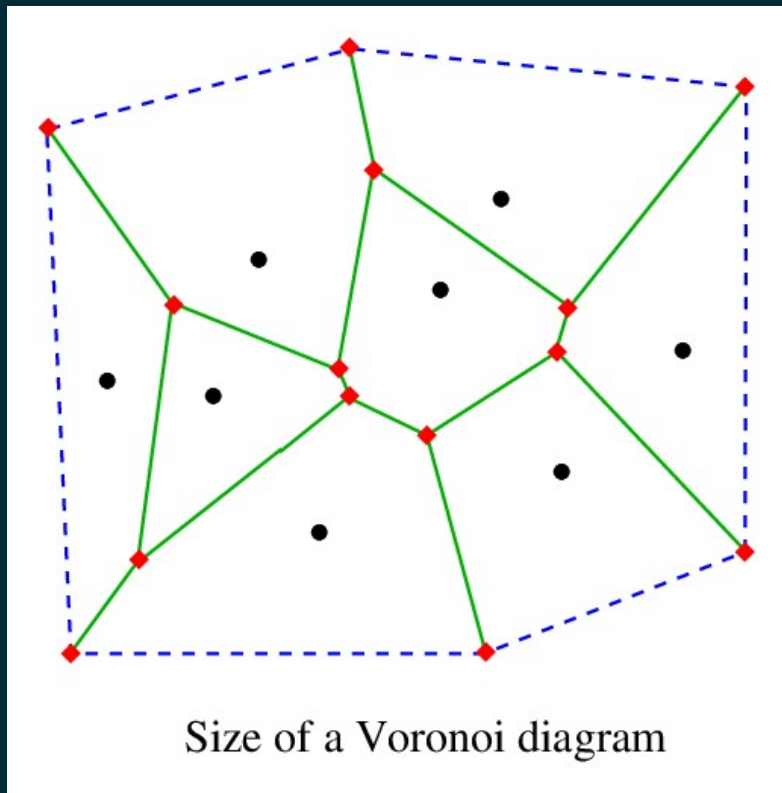
$$V_{\text{cell}}(P_i) = \bigcap_{j \neq i} H_{ij}$$

Vor(S)

There may be $\binom{n}{2}$ edges
in total

if every pair P_i, P_j
contributes a portion of
their perpendicular bisector

In reality, $\text{Vor}(S)$ consists only of
 $\Theta(n)$ edges.



$$G = (V, E)$$

a planar graph

$n+1$ faces

Each vertex has degree 3.

$$3V = 2E$$

$$V = \frac{2}{3}E$$

$$F = n+1$$

$$V - E + F = 2$$

$$\frac{2}{3}E - E + n+1 = 2$$

$$\frac{1}{3}E = n-1$$

$$E = 3n-3$$

$$V = 2n-2$$