

**Computer Science and Engineering Department
Indian Institute of Technology Kharagpur**

Compilers Laboratory: CS39003

3rd Year CSE: 5th Semester

TinyC, Part 3: Machine Independent Code Generator for tinyC

Marks: 100

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1 Preamble – tinyC

The Lexical Grammar (TinyC, Part 1) and the Phase Structure Grammar (TinyC, Part 2) for tinyC have already been defined as subsets of the C language specification from the International Standard **ISO/IEC 9899:1999 (E)**.

In this assignment you will write the semantic actions in Bison to translate a tinyC program into an array of 3-address quad's, a supporting symbol table, and other auxiliary data structures. The translation should be machine-independent, yet it has to carry enough information so that you can later target it to a specific architecture (x86 / IA-32 / x86-64).

2 Scope of Machine-Independent Translation

Focus on the following from the different phases to write actions for translation.

2.1 Expression Phase

Support all arithmetic, shift, relational, bit, logical (boolean), and assignment expressions excluding:

1. **sizeof** operator
2. Comma (,) operator
3. Compound assignment operators

* = / = % = + = - = << = >> = & = ^ = | =

Also support simple assignment operator (=)

4. Structure component expression

2.2 Declarations Phase

Support for declarations should be provided as follows:

1. Simple variable, pointer, array, and function declarations should be supported. For example, the following would be translated:

```
float d = 2.3;
int i, w[10];
int a = 4, *p, b;
void func(int i, float d);
char c;
```

2. Consider only **void**, **char**, **int**, and **float** *type-specifiers*. As specified in C, **char** and **int** are to be taken as **signed**.

For computation of offset and storage mapping of variables, assume the following sizes¹ (in bytes) of types:

¹Using hard-coded sizes for types does not keep the code machine-independent. Hence you may want to use constants like `sizeof.char`, `sizeof.int`, `sizeof.float`, and `sizeof.pointer` for sizes that can be defined at the time of machine-dependent targeting.

Type	Size	Remarks
void	<i>undefined</i>	
char	1	
int	4	
float	8	
void *	4	<i>All pointers have same size</i>

It may also help to support an implicit **bool** (boolean) type with constants **1** (TRUE) and **0** (FALSE). This type may be inferred for a logical expression or for an **int** expression in logical context. Note that the users cannot define, load, or store variables of **bool** type explicitly, hence it is not storable and does not have a size.

3. Initialization of arrays may be skipped.
4. *storage-class-specifier*, *enum-specifier*, *type-qualifier*, and *function-specifier* may be skipped.
5. Function declaration with only parameter type list may be skipped. Hence,

```
void func(int i, float d);
```

should be supported, whereas

```
void func(int, float);
```

may not be.

2.3 Statement Phase

Support all statements excluding:

1. Declaration within **for**.
2. All labelled statements (*labeled-statement*).
3. **switch** in *selection-statement*.
4. All Jump statements (*jump-statement*) except **return**.

2.4 External Definitions Phase

Support function definitions and skip external declarations.

3 The 3-Address Code

Use the 3-Address Code specification as discussed in the class. For easy reference the same is reproduced here. Every 3-Address Code:

- Uses only up to 3 addresses.
- Is represented by a quad comprising – opcode, argument 1, argument 2, and result; where argument 2 is optional.

3.1 Address Types

- *Name*: Source program names appear as addresses in 3-Address Codes.
- *Constant*: Many different types and their (implicit) conversions are allowed as deemed addresses.
- *Compiler-Generated Temporary*: Create a distinct name each time a temporary is needed – good for optimization.

3.2 Instruction Types

For Addresses x , y , z , and Label L

- *Binary Assignment Instruction*: For a binary op (including arithmetic, shift, relational, bit, or logical operators):

```
x = y op z
```

- *Unary Assignment Instruction*: For a unary operator op (including unary minus or plus, logical negation, bit, and conversion operators):

```
x = op y
```

- *Copy Assignment Instruction*:

```
x = y
```

- *Unconditional Jump*:

```
goto L
```

- *Conditional Jump*:

- *Value-based*:

```
if x goto L
ifFalse x goto L
```

- *Comparison-based*: For a relational operator op (including $<$, $>$, $==$, $!=$, \leq , \geq):

```
if x relop y goto L
```

- *Procedure Call*: A procedure call $p(x_1, x_2, \dots, x_N)$ having $N \geq 0$ parameters is coded as (for addresses p , x_1 , x_2 , and x_N):

```
param x1
param x2
...
param xN
y = call p, N
```

Note that N is not redundant as procedure calls can be nested.

- *Return Value*: Returning a return value and / or assigning it is optional. If there is a return value v it is returned from the procedure p as:

```
return v
```

- *Indexed Copy Instructions*:

```
x = y[z]
x[z] = y
```

- *Address and Pointer Assignment Instructions*:

```
x = &y
x = *y
*x = y
```

4 Design of the Translator

Lexer and Parser Use the Flex and Bison specifications (if required you may correct your specifications) you had developed in Parts 1 and 2 respectively, and write semantic actions for translating the subset of tinyC as specified in Section 2. Note that many grammar rules of your tinyC parser may not have any action or may just have propagate-only actions. Also, some of the lexical tokens may not be used.

Augmentation Augment the grammar rules with markers and add new grammar rules as needed for the intended semantic actions. Justify your augmentation decisions within comments of the rules.

Attributes Design the attributes for every grammar symbol (both terminal and non-terminal). List the attributes against symbols (with brief justification) in comment on the top of your Bison specification file. Highlight the inherited attributes, if any.

Symbol Table Use symbol tables for user-defined (including arrays and pointers) variables, temporary variables and functions.

Name	Type	Initial Value	Size	Offset	Nested Table
...

For example, for

```
float d = 2.3;
int i, w[10];
int a = 4, *p, b;
void func(int i, float d);
char c;
```

the Symbol Tables will look like:

ST(global) *This is the Symbol Table for global symbols*

Name	Type	Initial Value	Size	Offset	Nested Table
d	float	2.3	8	0	null
i	int	null	4	8	null
w	array(10, int)	null	40	12	null
a	int	4	4	52	null
p	ptr(int)	null	4	56	null
b	int	null	4	60	null
func	function	null	0	64	ptr-to-ST(func)
c	char	null	1	64	null

ST(func) *This is the Symbol Table for function func*

Name	Type	Initial Value	Size	Offset	Nested Table
i	int	null	4	0	null
d	float	null	8	4	null
retVal	void	null	0	12	null

The Symbol Tables may support the following methods:

lookup(...)	A method to lookup an id (given its name or lexeme) in the Symbol Table. If the id exists, the entry is returned, otherwise a new entry is created.
gentemp(...)	A static method to generate a new temporary, insert it to the Symbol Table, and return a pointer to the entry.
update(...)	A method to update different fields of an existing entry.
print(...)	A method to print the Symbol Table in a suitable format.

Note:

- The fields and the methods are indicative. You may change their name, functionality and also add other fields and / or methods that you may need.
- It should be easy to extend the Symbol Table as further features are supported and more functionality is added.
- The global symbol table is unique.
- Every function will have a symbol table of its parameters and automatic variables. This symbol table will be nested in the global symbol table.
- Symbol definitions within blocks are naturally carried in separate symbol tables. Each such table will be nested in the symbol table of the enclosing scope. This will give rise to an implicit stack of symbol tables (global one being the bottom-most) the while symbols are processed during translation. The search for a symbol starts from the top-most (current) table and goes down the stack up to the global table.

Quad Array The array to store the 3-address quad's. Index of a quad in the array is the *address* of the 3-address code. The quad array will have the following fields (having usual meanings)

op	arg 1	arg 2	result
...

Note:

- **arg 1** and / or **arg 2** may be a variable (address) or a constant.
- **result** is variable (address) only.
- **arg 2** may be null.

For example, if

```
int i = 10, a[10], v = 5;
...
do i = i - 1; while (a[i] < v);
```

translates to

```
100: t1 = i - 1
101: i = t1
102: t2 = i * 4
103: t3 = a[t2]
104: if t3 < v goto 100
```

the quad's are represented as:

Index	op	arg 1	arg 2	result
...
100	-	i	1	t1
101	=	t1		i
102	*	i	4	t2
103	=[]	a	t2	t3
104	<	t3	v	100

The Quad Array may support the following methods:

<code>emit(...)</code>	An overloaded static method to add a (newly generated) quad of the form: <code>result = arg1 op arg2</code> where <code>op</code> usually is a binary operator. If <code>arg2</code> is missing, <code>op</code> is unary. If <code>op</code> also is missing, this is a copy instruction.
<code>print(...)</code>	A method to print the quad array in a suitable format.

For example the above state of the array may be printed (with the symbol information) as:

```

void main()
{
    int i = 10;
    int a[10];
    int v = 5;
    int t1;
    int t2;
    int t3;

    L100: t1 = i - 1;
    L101: i = t1;
    L102: t2 = i * 4;
    L103: t3 = a[t2];
    L104: if (t3 < v) goto L100;
}

```

Note:

- The fields and the methods are indicative. You may change their name, functionality and also add other fields and / or methods that you may need.

Global Functions Following (or similar) global functions and more may be needed to implement the semantic actions:

makelist(i)	A global function to create a new list containing only i, an index into the array of quad's, and to return a pointer to the newly created list.
merge(p1, p2)	A global function to concatenate two lists pointed to by p1 and p2 and to return a pointer to the concatenated list.
backpatch(p, i)	A global function to insert i as the target label for each of the quad's on the list pointed to by p.
typecheck(E1, E2)	A global function to check if E1 and E2 have same types (that is, if <type_of_E1> = <type_of_E2>). If not, then to check if they have compatible types (that is, one can be converted to the other), to use an appropriate conversion function conv<type_of_E1>2<type_of_E2>(E) or conv<type_of_E2>2<type_of_E1>(E) and to make the necessary changes in the Symbol Table entries. If not, that is, they are of incompatible types, to throw an exception during translation.
conv<type1>2<type2>(E)	A global function to convert ^a an expression E from its current type type1 to target type type2, to adjust the attributes of E accordingly, and finally to generate additional codes, if needed.

^aIt is assumed that this function is called from typecheck(E1, E2) and hence the conversion is possible.

Naturally, these are indicative and should be adopted as needed. For every function used clearly explain the input, the output, the algorithm, and the purpose with possible use at the top of the function.

5 The Assignment

1. Write a 3-Address Code translator based on the Flex and Bison specifications of tinyC. Assume that the input tinyC file is lexically, syntactically, and semantically correct. Hence no error handling and / or recovery is expected.
2. Prepare a Makefile to compile and test the project.
3. Prepare test input files `TinyC3_rolls_test<number>.c` to test the semantic actions and generate the translation output in `TinyC3_rolls_quads<number>.out`.
4. Name your files as follows:

File	Naming
Flex Specification	<code>TinyC3_rolls.l</code>
Bison Specification	<code>TinyC3_rolls.y</code>
Data Structures (Class Definitions) and Global Function Prototypes	<code>TinyC3_rolls_translator.h</code>
Data Structures, Function Implementations and Translator <code>main()</code>	<code>TinyC3_rolls_translator.cxx</code>
Test Inputs	<code>TinyC3_rolls_test<number>.c</code>
Test Outputs	<code>TinyC3_rolls_quads<number>.out</code>

5. Prepare a tar-archive with the name `TinyC3_rolls.tar` containing all the files and upload to Moodle.

6 Credits

Design of Grammar Augmentations: <i>Explain the augmentations in the production rules in Bison</i>	5
Design of Attributes: <i>Explain the attributes in the respective %token and %type in Bison</i>	5
Design and Implementation of Symbol Table and Supporting Data Structures: <i>Explain with class definition of ST and other Data Structures</i>	10
Design and Implementation of Quad Array: <i>Explain with class definition of QA</i>	5
Design and Implementation of Global Functions: <i>Explain i/p, o/p, algorithm and purpose for every function</i>	10
Design and Implementation of Semantic Actions: <i>Explain with every action in Bison</i>	
Expression Phase: <i>Correct handling of operators, type checking and conversions</i>	15
Declaration Phase: <i>Handling of variable declarations, function definitions in ST</i>	10
Statement Phase: <i>Correct handling of statements</i>	15
External Definition Phase: <i>Correct handling of function definitions</i>	5
Design of Test files and correctness of outputs: <i>Test at least 5 i/p files covering all rules</i> <i>Shortcoming and / or bugs, if any, should be highlighted</i>	20