

# CS69001 Computing Laboratory – I

## Assignment No: C4

Date: 05–November–2018

Make a parallel implementation of the standard linear-system solver algorithm (Gaussian elimination) using POSIX threads. Consider a square system of linear equations

$$A\mathbf{x} = \mathbf{b},$$

where  $A$  is an  $N \times N$  matrix, and  $\mathbf{x}$  and  $\mathbf{b}$  are  $N$ -dimensional (column) vectors, all with real-valued (floating-point) elements. Assume that the system is uniquely solvable (for  $\mathbf{x}$ ). Take  $N = 1000$  for this assignment.

### Gaussian elimination

Let  $a_{ij}$  denote the  $(i, j)$ -th entry of  $A$ , and  $b_i, x_i$  the  $i$ -th entries of  $\mathbf{b}$  and  $\mathbf{x}$ , respectively. Let us also use the symbol  $A_i$  to denote the  $i$ -th row of  $A$ . Array indexing is assumed to be zero-based.

#### A. Triangularize the matrix $A$ in place

For  $i = 0, 1, 2, \dots, N - 1$ , repeat Steps 1–4:

1. Try to locate a  $k \in \{i, i + 1, i + 2, \dots, N - 1\}$  such that  $a_{ki} \neq 0$ .  
If no such  $k$  is found, the system is underspecified, exit.
2. If  $k > i$ , swap  $A_i$  with  $A_k$ , and  $b_i$  with  $b_k$ .
3. Divide  $A_i$  and  $b_i$  by  $a_{ii}$  (so  $a_{ii}$  becomes 1 after this).
4. For  $k = i + 1, i + 2, \dots, N - 1$ , repeat:  
If  $a_{ki} \neq 0$ , subtract  $a_{ki}$  times  $A_i$  from  $A_k$ , and  $a_{ki}$  times  $b_i$  from  $b_k$ .

#### B. Backward substitution

5. For  $i = N - 1, N - 2, \dots, 2, 1, 0$ , compute the solution  $x_i = b_i - \sum_{j=i+1}^{N-1} a_{ij}x_j$ .

### The threaded implementation

The master thread  $M$  and  $p$  worker threads  $W_0, W_1, W_2, \dots, W_{p-1}$  run this algorithm as follows. The number  $p$  of worker threads is to be read from the user.

| The work of $M$  | The work of $W_t, t \in \{0, 1, 2, \dots, p - 1\}$   |
|--|--|
| Initialize the system of equations.<br>Create and initialize mutexes and condition variables.<br>Create the worker threads $W_0, W_1, W_2, \dots, W_{p-1}$ .<br>Wait for a while to allow the worker threads to start. |  |
| For $i = 0, 1, 2, \dots, N - 1$ , repeat:  | For $i = 0, 1, 2, \dots, N - 1$ , repeat:  |
| Carry out Steps 1, 2, 3.<br>Break the interval $[i + 1, N - 1]$ into (nearly) equal-sized sub-intervals $I_0, I_1, I_2, \dots, I_{p-1}$ .<br>Signal all the worker threads.<br>Wait until all worker threads are done. | Wait until signaled by $M$ .<br><br>Carry out Step 4 for all $k \in I_t$ .<br>If $W_t$ is the last thread to finish the current iteration, wake up the master thread $M$ . |
|  | Terminate.   |
| Wait until all $W_t, t \in \{0, 1, 2, \dots, p - 1\}$ , terminate.<br>Carry out Step 5.<br>Verify the correctness of the solution.   |  |

Notice that no iteration of the row-reduction loop may start before the previous iteration is over. Moreover, the main thread  $M$  must do some initial work before the worker threads can start the reduction process. Implement these two instances of synchronization using condition variables.

**Remark:** Arguably, a more natural way to implement the synchronization of the row-reduction loop is by using barriers. This technique is not covered in the class, so you use condition variables only.

### Checking for correctness

The linear system ( $A$  and  $\mathbf{b}$ ) can be randomly generated as follows. Choose each

$$a_{ij} \in_R \{-9, -8, \dots, -2, -1, 0, 1, 2, \dots, 8, 9\}.$$

Also, generate a solution  $\mathbf{y}$  with each entry chosen randomly in the same range. Compute  $\mathbf{b} = A\mathbf{y}$ . Forget  $\mathbf{y}$ . This ensures that the system is solvable. Its unique solvability (that is,  $\text{Rank}(A) = N$ ) cannot be guaranteed by this random generation process, but the situation  $\text{Rank}(A) < N$  occurs with very low probability. The master thread should keep a copy  $A'$  of  $A$ , and a copy  $\mathbf{b}'$  of  $\mathbf{b}$ .

Although the elements of  $A$ ,  $\mathbf{b}$ ,  $\mathbf{y}$  are chosen as integers, we need these elements to be floating-point variables (preferably `double`). Gaussian elimination cannot proceed with integer arithmetic.

After the master thread computes  $\mathbf{x}$ , it needs to check whether  $A'\mathbf{x} = \mathbf{b}'$  (initial system) and  $A\mathbf{x} = \mathbf{b}$  (reduced system). However, the use of floating-point arithmetic implies introduction of approximation errors. That is, the above equalities are only approximately satisfied. Compute and report the approximation errors as the largest entries of  $A'\mathbf{x} - \mathbf{b}'$  and  $A\mathbf{x} - \mathbf{b}$ . These errors should be rather small.

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### Sample output

```
+++ p = 8

+++ Worker thread 1 starting
+++ Worker thread 0 starting
+++ Worker thread 3 starting
+++ Worker thread 4 starting
+++ Worker thread 2 starting
+++ Worker thread 5 starting
+++ Worker thread 6 starting
+++ Worker thread 7 starting

+++ Worker thread 5 exiting
+++ Worker thread 1 exiting
+++ Worker thread 7 exiting
+++ Worker thread 4 exiting
+++ Worker thread 2 exiting
+++ Worker thread 6 exiting
+++ Worker thread 0 exiting
+++ Worker thread 3 exiting

+++ Master thread: Row reduction done

+++ Master thread: Solution computed
Maximum error (initial system) = 0.00000016573313
Maximum error (reduced system) = 0.0000000013097
```

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Submit a single C/C++ source file. Use no non-shared global variables.